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	Name	Date	Signature
Prepared by :	Land SAF Project Team		
Approved by :	Land SAF Project Manager (IM)		

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List of Acronimous

ASTER	Advanced Spaceborne Thermal Emission and Reflection Radiometer
ATBD	Algorithm Theoretical Basis Document
CASA	Carnegie-Ames-Stanford Approach
CPTEC	Centro de Previsão de Tempo e Estudos Climáticos
ECMWF	European Centre for Medium-range Weather Forecasts
EUMETSAT	European Organisation for the Exploitation of Meteorological Satellites
FAS	Fire Assimilation System (at FMI)
FIR	Finitive impulse response
FMI	Finnish Meteorological Institute
HRV	High Resolution Visible
FRE	Fire Radiative Energy
FREEVAL	Fire Radiative Energy Evaluation
FRP	Fire Radiative Power
FTA	Fire Thermal Anomaly
GAS	GMES Atmospheric Service
GCM	Global Circulation Model
GEMS	Global and regional Earth-system (Atmosphere) Monitoring using Satellite and in-situ data (EU 6 th framework Integrated Project)
GMES	Global Monitoring for Environmental Security, European initiative for the implementation of information services dealing with environment and security
GFED	Global Fire Emissions Database (GFED) (van der Werf et al. 2006)
IFS	Integrated Forecast System
INPE	Instituto Nacional de Pesquisas Espaciais
KCL	King's College London
NRT	Near Real Time
MACC	Monitoring of Atmospheric Composition and Climate
MIR	Middle InfraRed
MODIS	Moderate Resolution Imaging Spectroradiometer
MOPITT	Measurements of Pollution in the Troposphere
MPEF	Meteorological Product Extraction Facility at EUMETSAT
NOAA	National Oceanic and Atmospheric Administration
ORR	Operation Readiness Review
PM	Particulate Matter
RAO	Research Announcement of Opportunity
SAF	Satellite Applications Facility
SEVIRI	Spinning Enhanced Visible and InfraRed Imager
TA	Thermal Anomaly [K]
TIR	Thermal InfraRed

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Executive Summary

It has been demonstrated in small-scale experiments that the amount of radiant energy liberated per unit time during a vegetation fire (the so-called Fire Radiative Power) is related to the rate at which the fuel biomass is being consumed (e.g. Wooster et al., 2005). This is a direct result of the combustion process, whereby carbon-based fuel is oxidised (burnt) with the release of a certain ‘heat yield’. Measuring this FRP and integrating it over the lifetime of the fire therefore provides a measure of the total Fire Radiative Energy (FRE), which should be proportional to the total fuel mass combusted (M). The possibility to derive this FRP product from SEVIRI observations with an accuracy similar to that of MODIS for fires capable of being detected by SEVIRI has been demonstrated in the context of a MSG RAO project (Roberts et al., 2005).


The fire detection algorithm implemented for use with SEVIRI is thus an evolution of that first described in Roberts et al. (2005), and is based largely on the principles used to generate active fire detections within the MODIS fire products. The implemented algorithm described herein is very close to the enhanced geostationary fire detection algorithm fully detailed in Roberts and Wooster (2008), and works mainly on statistics derived from the 3.9 μm and 11.0 μm brightness temperatures, and their differences. Data from other channels are used primarily for false alarm identification. An operational version of this algorithm was prototyped at EUMETSAT in 2006 (Govaerts et al., 2007) and its accuracy verified against the original KCL version (Lattanzio 2006) using both Meteosat-8 and -9. This operational algorithm has subsequently been implemented in the Land SAF system in the framework of a direct technical collaboration between EUMETSAT and the Land SAF.

This validation report is based on the outcome of the FREEVAL study (EUM/CO/06/4600000277/YG) which concluded that two products are necessary to exploit the full potential of SEVIRI FRP data in (quasi) operational applications:

- (i) a pixel product containing observed FRP for each individual fire pixel together with ancillary data on the per-pixel FRP uncertainties at the full SEVIRI temporal and spatial resolution (referred to as FRP_PIXEL);
- (ii) a gridded product, ie, level 3, at a $1^\circ \times 1^\circ$ resolution containing area integrated FRP totals averaged over one hour time period and empirical corrections for undetected low FRP fires and partial cloudiness at the grid-cell scale (referred to as FRP_GRIDDED). This product is currently only in “development” status but the validation results are however already presented here as they provide relevant information on the product accuracy.

The derivation of these products is described in the Algorithm Theoretical Basis Document (Govaerts et al., 2007). The core work of this validation report evaluates the efficacy of a retrieval algorithm used to identify actively burning fires and estimate their fire radiative power from SEVIRI observations of fire-affected regions, and determines the effectiveness of the retrieved observations. The assessment of algorithm retrieval accuracy covered several aspects and was tailored to provide sufficient information so that an operational readiness review (ORR) can be issued and the data product can be generated with full specifications.

Validation of the SEVIRI fire radiative power (FRP) product considered four main aspects:


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- 1) An evaluation of the theoretical performance of the FRP algorithm;
- 2) An assessment of the accuracy and performance limitations due to the SEVIRI instrument and to the level 1.5 data characteristics from which all SEVIRI geophysical products are currently derived;
- 3) The verification of the performance of the specific FRP algorithm implementation at the Land Surface Analysis Satellite Applications Facility (Land-SAF);
- 4) The impact of the FRP product in operational applications such as aerosol and gas emission due to fires.

Validation was performed through radiative transfer modelling, through product analysis and cross-comparison at the pixel, fire, and grid-cell (*e.g.*, $1^\circ \times 1^\circ$) and regional basis, including comparisons with independent data products. In many cases, data from the EOS Terra and Aqua Moderate Resolution Imaging Spectroradiometer (MODIS) were used as the comparison dataset, since FRP can also be derived from the measurements of this sensor, but the analysis also included data from other sensors and platforms.

Due to the foreseen delay in substantial data products being available from the prototype operational processing chain implemented at EUMETSAT and the LandSAF, it was necessary to make use of different FRP dataset versions with largely similar but not identical characteristics during the FREEVAL study. Hence, much of the fundamental validation work was carried out with a full one year duration (Feb 2004 – Jan 2005) FRP dataset produced by running the first operational (non-commissioning phase) Meteosat-8 SEVIRI data through an enhanced version of the original fire detection and FRP algorithm developed at KCL in the Interactive Data Language environment (Wooster et al., 2003, 2005; Roberts et al., 2005, 2008). In parallel with this activity, a version of this enhanced algorithm was being implemented in C at EUMETSAT as the prototype processing chain, and was later ported to the Land SAF processing facility at the IM in Lisbon. Minor modifications were required to adjust the KCL code to the intricacies of the operational environment, and the details of this implementation are described in the algorithm theoretical basis document (Govaerts et al., 2007). Data from the Land SAF processing chain was made available later during the FREEVAL study, and the performance of this Land SAF product is here compared to that produced by the KCL processing chain. Some perturbations to performance are also expected due to unresolved differences between the calibration of the Meteosat-8 and Meteosat-9 imaging radiometers, particularly at higher signals such as are obtained over fires in the $3.9 \mu\text{m}$ spectral band.

A second important aspect of the FREEVAL project was the identification of potential users of the FRP product and the specification of user needs, which were then gauged against the product characteristics. The main users, who were identified prior to the project and were actively engaged in FREEVAL with discussions and sensitivity modelling studies, were national and European weather centres (UK Met Office and ECMWF). These centres are developing a range of applications requiring knowledge of atmospheric composition and emissions, including those from open vegetation burning. They expressed a strong need for an accurate and rapidly available data product helping them to quantify trace compound emissions from fires with good spatial and temporal resolution. The conclusions of this report reflect the consortium's view as to how well the SEVIRI FRP product can match user requirements. We also provide some recommendations how future developments could further enhance the existing capabilities for global and regional earth observation and monitoring of emissions from such fires.

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1 INTRODUCTION

1.1 FRP Product Background

“Forest fire” has been agreed as a MSG day-2/priority3 product during STG 37. Since “forest fire” encompasses many different types of products and associated applications, a better definition of a SEVIRI-based fire product was necessary. Several studies have been dedicated to that purposes (Pereira and Govaerts, 2001, Flasse 2004) which identified the Fire Radiative Power (FRP) as the most appropriate product that can be derived from SEVIRI observations, with relevant applications related to the science community interested in modelling of the carbon cycle. The development of such product has been endorsed in September 2005 by SWG-19 following a presentation given by Prof. M. Wooster who demonstrated, in the context of a MSG RAO project (Roberts *et al.*, 2005), the possibility to derive this product from SEVIRI observations with an accuracy similar to that of MODIS for fires capable of being detected by SEVIRI. This “proof-of-concept” work undertaken under the MSG RAO led by Prof. M. Wooster (hereafter referred to as the KCL algorithm) has been used as a starting point for the development of an operational version.


Such an operational version of this algorithm was prototyped at EUMETSAT in 2006 (Govaerts *et al.*, 2007) and its accuracy verified against the original KCL version using both Meteosat-8 and -9 (Lattanzio 2006). During this exercise, a discrepancy between SEVIRI band 3.9 onboard Meteosat-8 and -9 occurring at high temperature has been identified (Lattanzio and Govaerts, 2006). This operational algorithm has subsequently been implemented in the Land SAF system in the framework of a direct technical collaboration between EUMETSAT and the Land SAF. During its 5th meeting held in Brussels on 22 February 2007, the Land SAF IOP Steering Group welcomes this initiative and recommends the next SG (CDOP) to endorse this activity.

Late 2006, an external study (EUM/CO/06/4600000277/YG), referred to as the FREEVAL study (Schultz *et al.*, 2008), has been initiated at EUMETSAT aiming at (i) evaluate the FRP product currently prototyped at EUMETSAT and (ii) define user’s requirements for Fire Radiative Power derived from Meteosat-8/9 data at EUMETSAT that would support operational applications. This validation report is based on the outcome of the FREEVAL study.

This study concluded that two products are necessary to exploit the full potential of SEVIRI FRP data in (quasi) operational applications:

- (i) a pixel product containing observed FRP for each individual fire pixel together with ancillary data on the per-pixel FRP uncertainties at the full SEVIRI temporal and spatial resolution (referred to as FRP_PIXEL);
- (ii) a gridded product, ie, level 3, at a $1^\circ \times 1^\circ$ resolution containing area integrated FRP totals averaged over one hour time period and empirical corrections for undetected low FRP fires and partial cloudiness at the grid-cell scale (referred to as FRP_GRIDDED). This product is currently only in “development” status but the validation results are however already presented here as they provide relevant information on the product accuracy.

The derivation of these products is described in the Algorithm Theoretical Basis Document (Govaerts *et al.*, 2007). Except when specifically mentioned, this validation report essentially

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focuses on the validation of the FRP_PIXEL product generated with the FRP_PIXEL algorithm **version 0.8** in the Land SAF system.

1.2 Document structure

The use of the FRP product for the fire emission estimation is a rather new concept which is explained in Section (1.3). Its derivation from space observations is briefly described in Section (1.4). Section (1.5) lists the technical limitations associated with FRP extraction from SEVIRI observations. The overall strategy of the validation is explained in Section (1.6).

As the FRP product is based on novel concepts, no well-established user requirements can be found in the literature. Hence, Section (2) is entirely dedicated to the analysis of potential FRP applications and associated requirements.

Detailed descriptions of the reference datasets, the validation methodology and validation results are provided in Sections (3), (4) and (5), respectively. The validation efforts reported on here also include tests of the implementation of the SEVIRI FRP product for fire emissions and atmospheric transport modelling (case studies), also reported in Section (5). Major outcome of this first FRP validation effort are summarised in Section (6).

1.3 FRP Product Concept

Open vegetation fires are an important disturbance agent of the terrestrial biosphere, and represent a ubiquitous, highly variable emission source for many key greenhouse gases, air pollutants, and aerosols. Even though natural fires (ignited by lightning or volcanoes) have occurred throughout Earth's vegetated history, today the vast majority are initiated by humans. Fire is commonly used for land clearance and management, pest control and soil fertilization. Fires are most frequent in tropical and subtropical regions, with Africa usually regarded the continent with the most wide-spread fire occurrence. Emissions from vegetation fires are increasingly recognized as an important parameter in atmospheric modelling, and their accurate description is a fundamental pre-requisite for the installation of operational services to monitor and predict atmospheric composition and the long-range transport of air pollutants, and for the monitoring of compliance with international treaties on greenhouse gas and air pollutant emission ceilings.

The observation of open fires from space has greatly advanced our understanding of the global dimension of this phenomenon and of the spatial and temporal patterns of fire occurrence. Nevertheless, it has proven very difficult to use the remote sensing of active fires or the mapping of burned areas for accurate, temporally and spatially consistent estimates of emissions from these fires, and to provide these data in timeframes useful for atmospheric forecasting. This has to do on the one hand with great uncertainties in the estimates of fuel load and combustion behaviour (which have typically been required to convert observations of active fires or burned area into emission fluxes), and on the other hand with the non-ideal nature of the available EO systems for this application (*e.g.*, limited imaging frequency and inappropriate sensor characteristics). The lack of a near real-time data delivery of fire products from such systems has also hampered such efforts.

Fire observation has rarely been a primary mission objective for the design of satellite instruments. As a consequence, almost all sensors that can be used for fire detection and fire characterisation suffer from instrument saturation effects, relatively limited spatial and/or temporal resolution, and other limiting factors. Specifically, the temporal sampling from low



earth orbit instruments is often inadequate for capturing the high temporal variability of fire occurrence and fire strength, and for fully resolving the fire diurnal cycle (which is known to be extreme in some areas). The data delivery of 'fire products' from such systems has in the main not been viewed as an 'operational' near-real time service, but rather a service to the science community, but the former is required if the data are to support timely applications such as those involving forecasting of trace gas/aerosol concentrations, air quality and visibility.

Active fire data provided by the SEVIRI instrument on board Meteosat 8/9 promised significant advancements in the current state-of-the-art of fire monitoring and emission quantification systems in two ways.

Firstly, its main observable, the Fire Radiative Power (FRP) of each detected active fire pixel, is expected to be directly related to the rate of combustion of biomass and thus the release of smoke emissions from the identified fires (Wooster *et al.*, 2005). The FRP provides information on the measured radiant heat output of detected fires (in units of megawatts). Its integration over the lifetime of a fire, the fire radiative energy (FRE), should therefore be directly proportional to the accumulated emissions released by the fire. This has been verified in a number of small-scale field experiments, but needs further proof on regional to continental scales. Quantifying emissions based on FRE eliminates the need to separately assess burned area, fuel loads, and combustion rates as is done currently in most emissions assessment methods, and therefore removes a whole series of uncertainties due to our often rather limited knowledge of these variables.

Secondly, since SEVIRI is employed on a geostationary platform, it can sample a large footprint with high (15 min) frequency, and can therefore deliver important information on the temporal variability of fires. A limitation is that the relatively coarse spatial resolution of the measurements (3 km sampling distance at the sub-satellite point) lowers the detection probability of the smaller/less intense fires, and such fires therefore remain unaccounted for (*i.e.* undetected) in the raw output product. By definition each such fire may be releasing relatively small amounts of pollutants, but the total number of these smaller fires may make their cumulative emissions significant, and so statistical adjustment of the product to deal with this bias may be warranted.

1.4 Theory of the FRP Algorithm

The MIR radiance method of FRP estimation was first presented in Wooster *et al.* (2003) and is based on simple approximations to the physical laws governing the emission of thermal radiation from fires. The MIR radiance method exhibits two potential advantages over dual-wavelength methods such as those originally presented in Dozier (1981). Firstly it relies only on quantification of the fire pixel in a single spectral channel, removing problems related to interchannel spatial mis-registration that potentially impact such dual spectral band approaches (Shephard and Kennelly, 2003), and secondly it relies only on quantification of the fire signal in the MIR spectral band only, where spectral radiative emission from wildfires is maximised and thus where the signal increase of the fire pixel over the ambient background window signal is at its greatest (*i.e.*, the S/N is optimised). For these reasons, the method used to derive FRP in the official MODIS fire products also uses measurements in the MIR spectral band (Kaufman *et al.*, 1998a), though in that case expressed in terms of brightness temperatures rather than radiances. The MIR radiance method of FRP derivation is defined by:

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$$FRP_{MIR} = \left(\frac{\sigma \varepsilon_f}{a \varepsilon_{f,MIR}} \right) L_{f,MIR} \quad [Wm^{-2}]$$

Equation 1.1

where σ is the Stefan-Boltzmann constant ($5.67 \times 10^{-8} W m^{-2} K^{-4}$), ε_f is the emissivity of the fire over all wavelengths, and $\varepsilon_{f,MIR}$ is the emissivity over the MIR spectral band. In the absence of data to the contrary gray body behaviours is assumed ($\varepsilon_f = \varepsilon_{f,MIR}$), and this is understood to be a realistic approximation for vegetation fires (Langaas, 1995).

a ($W m^{-2} sr^{-1} \mu m^{-1} K^{-4}$) is a constant determined from the empirical best-fit relationship between the fourth power of the blackbody emitter temperature, T and the emitted spectral radiance, $B(\lambda_{MIR}, T)$, in the MIR spectral band [i.e. $B(\lambda_{MIR}, T) = aT^4$], made over the range of emitter temperatures appropriate to actively burning fires. Since the Stefan-Boltzman Law states that the true fire radiative power emitted over all wavelengths is also a function of the fourth power of the emitter temperature, then the FRP can be estimated as a linear function of the fires MIR emitted spectral radiance, as expressed in Equation 1.1.

In Equation 1.1, $L_{f,MIR}$ ($Wm^{-2} sr^{-1} \mu m^{-1}$) represents the MIR spectral radiance emittance of the fire. However, under the circumstances pertaining to the observation of sub-pixel sized fires by a system such as SEVIRI, the fire is not fully resolved by the imaging system and the at-sensor received signal L_{MIR} is in fact the summation the following terms; emitted fire thermal radiance, solar and atmospheric downwelling irradiance reflected from the fire, emitted thermal radiance from the non-fire background, solar and atmospheric downwelling irradiance reflected from the non-fire background, and upwelling atmospheric thermal radiation:

$$\begin{aligned} L_{MIR} = & \tau_{MIR} p_f \varepsilon_{f,MIR} B(\lambda_{MIR}, T_f) + \tau_{MIR} p_f (1 - \varepsilon_{f,MIR}) (\tau_{d,MIR} I_{sun,MIR} \cos \phi + I_{atm,MIR}) / \pi \\ & + \tau_{MIR} (1 - p_f) \varepsilon_{b,MIR} B(\lambda_{MIR}, T_b) + \tau_{MIR} (1 - p_f) (1 - \varepsilon_{b,MIR}) (\tau_{d,MIR} I_{sun,MIR} \cos \phi + I_{atm,MIR}) / \pi \\ & + L_{atm,MIR} \end{aligned}$$

Equation 1.2

where τ_{MIR} is the upward atmospheric transmission in the sensors MIR spectral band, ϕ is the solar zenith angle, $\tau_{d,MIR}$ is the downward atmospheric transmission in the sensors MIR spectral band at angle ϕ , $I_{sun,MIR}$ is the extraterrestrial solar irradiance in the sensors MIR spectral band, $I_{atm,MIR}$ is the diffuse downwelling atmospheric irradiance in the MIR spectral band, and $L_{atm,MIR}$ is the upwelling atmospheric spectral radiance in the MIR spectral band, the other symbols (T , ε , p) have their previously defined meanings, with subscript f corresponding to their value at the fire and b at the non-fire background.

Similarly for a neighbouring non-fire ‘background’ pixel:

$$L_{b,MIR} = \tau_{MIR} \varepsilon_{b,MIR} B(\lambda_{MIR}, T_b) + \tau_{MIR} (1 - \varepsilon_{b,MIR}) (\tau_{d,MIR} I_{sun,MIR} \cos \phi + I_{atm,MIR}) / \pi + L_{atm,MIR}$$

Equation 1.3

The fire emitted spectral radiance in the MIR spectral band, $L_{f,MIR}$, required for input into Equation 1.1 is in fact the $p_f \varepsilon_{f,MIR} B(\lambda_{MIR}, T_f)$ term on the right hand side of Equation 1.2, and its value can be obtained numerically by combining Equation 1.2 and Equation 1.3:

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$$L_{MIR} = \tau_{MIR} p_f \epsilon_f B(\lambda_{MIR}, T_f) + L_{atm,MIR} + (1 - p_f)(L_{b,MIR} - L_{atm,MIR}) + \tau_{MIR} p_f (1 - \epsilon_f)(\tau_{d,MIR} I_{sun,MIR} \cos \phi + I_{atm,MIR}) / \pi$$

Equation 1.4

and re-arranging:

$$p_f \epsilon_{MIR} B(\lambda_{MIR}, T_f) = \frac{1}{\tau_{MIR}} (L_{MIR} - (1 - p_f) L_{b,MIR} + p_f L_{atm,MIR}) - p_f (1 - \epsilon_f)(\tau_{d,MIR} I_{sun,MIR} \cos \phi + I_{atm,MIR}) / \pi$$

Equation 1.5

Equation 1.5 represents the true value of $p_f \epsilon_{MIR} B(\lambda_{MIR}, T_f)$ for use as $L_{f,MIR}$ in Equation 1.1. Multiplying the output of Equation 1.1 by the sensor pixel area then provides an estimate of the fire radiative power in Watts (generally expressed in MW due to the large fire radiative power values observed from open wildfires), based only on the MIR spectral signal.

However, certain of the parameters in Equation 1.5 cannot be determined, for example the fire fractional area, p_f , whilst others, for example the atmospheric parameters are likely to be imperfectly known. By neglecting the (relatively) unimportant terms, Equation 1.5 can be greatly simplified and then parameterised using even coarse resolution satellite data, in order to provide an estimate of $L_{f,MIR}$ for input into Equation 1.1.

The first assumption is that the atmospheric term $p_f L_{atm,MIR}$ on the right hand side of Equation 1.5 will always be small compared to at least one of the first two terms and is therefore negligible. Next, the requirement to know the fire fractional area is removed by assuming that $(1 - p_f) L_{b,MIR} \approx L_{b,MIR}$, which is considered workable when p_f is sufficiently small, and as p_f increases the error this assumption introduces is still negligible since in that case the spectral radiance of the fire pixel will be increasingly dominated by emittance from the (increasingly large) fire rather than from the much cooler ambient temperature background (since $B(\lambda_{MIR}, T_f)$ can be four orders of magnitude larger than $B(\lambda_{MIR}, T_b)$ at MIR wavelengths). The final term in Equation 1.5, corresponding to the solar and downwelling atmospheric radiation that are reflected from the fire, is assumed negligible for the same reason.

Via these simplifications the fire-emitted spectral radiance ($L_{f,MIR}$) for input into Equation 1.1 can be estimated from the difference between the MIR spectral radiance of the active fire pixel (L_{MIR}) and that of the surrounding non-fire ‘background’ ($L_{b,MIR}$) calculated as the mean signal of the ‘background window pixels, and adjusted for the MIR atmospheric transmission:

$$L_{f,MIR} = p_f \epsilon_{f,MIR} B(\lambda_{MIR}, T_f) = \frac{1}{\tau_{MIR}} (L_{MIR} - L_{b,MIR})$$

Equation 1.6

The impact of the assumptions made during the derivation and application of the above equation used to estimate $L_{f,MIR}$, the assumptions made during the derivation of Equation 1.1, will control the theoretical accuracy of the FRP algorithm.

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1.5 Factors Limiting FRP Product Accuracy

Although SEVIRI has been designed for operational weather forecasting and not specifically for fire detection, its MIR channel (thermal band centred at $3.9\text{ }\mu\text{m}$) shows great potential for fire detection and the measurement of fire radiative power (FRP) using Equation 1.1 and Equation 1.5, as demonstrated in Figure 1.1. However, the MIR channel of the SEVIRI sensor has a saturation level of $\sim 335\text{ K}$, and as a result a certain proportion of the particularly large and/or high intensity fires are expected to cause saturation of the measurements in this spectral band. Whilst this will not impact detection of such fire pixels (indeed their large signal will very likely make them amongst the most detectable such events), it will lead to an impact on the accuracy of the FRP measurements of such fires since their MIR spectral radiance will be underestimated.

A further factor influencing FRP product accuracy is the relatively coarse spatial resolution of the SEVIRI MIR channel, which also varies with viewing geometry. The sub-satellite pixel size is $4.8 \times 4.8\text{ km}$ (FWHM), and these 23 km^2 pixels are oversampled by a factor 1.6 in the EW and SN directions leading to a sub-satellite pixel sampling distance of $3 \times 3\text{ km}$. Pixels close to the disk edge (for example those over Madagascar and South America) reach areas of $\sim 90\text{ km}^2$. The relatively large pixel size limits the detectability of small/low intensity fires having a low FRP, and may lead to a misinterpretation of fire clusters as individual large fire events. The increasing pixel size away from the sub-satellite point is expected to increase the significance of these events relative to smaller fires.

Finally, the on-board processing of SEVIRI data and its conversion to the level 1.5 radiance product from which all geophysical datasets including the FRP product are derived (termed here the level 1 to level 1.5 processing) introduces perturbations to the measurements made in each spectral band. This will include the introduction of interpolation errors due to the geolocation and projection onto the nominal geostationary projection centered at $(0^\circ; 0^\circ)$ (see EUMETSAT Technical Document EUM/MSG/ICD/105, 2007).

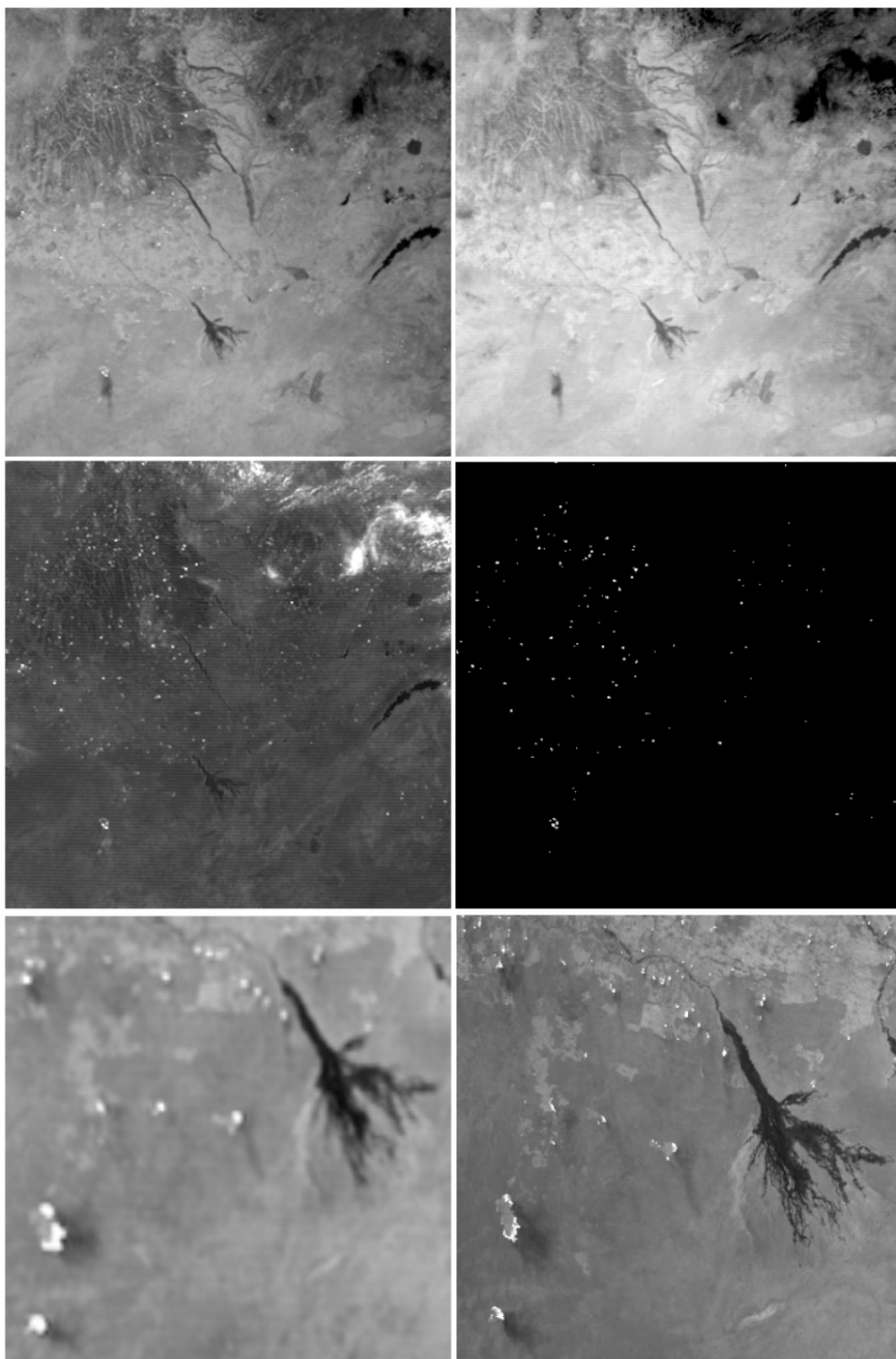


Figure 1.1: Imagery of southern Africa on 4 September 2003, in which numerous active fires are burning. (a)-(d) are derived from SEVIRI data covering a 1200 km wide region, collected at 12:12 UTC. (a) 3.9 μ m, (b) 10.8 μ m, (c) 3.9 μ m - 10.8 μ m brightness temperature difference, and (d) mask of confirmed active fire pixels. (e) and (f) show, respectively, a SEVIRI and MODIS MIR image subset centred on the Okavango delta region of Botswana, captured at 11:57 UTC and 12:05 UTC respectively.



1.6 Validation Strategy


The initial implementation of the geostationary fire detection algorithm was made at King's College London using commissioning phase SEVIRI data, and was coded in the Interactive Data Language (IDL) environment (Roberts et al., 2005). At the start of the validation activity this algorithm was in the process of being significantly improved, and it is this improved implementation that forms the basis of the approach to be used in the proposed operational production of FRP data from SEVIRI, as outlined in the FRP Product Algorithm Theoretical Basis Document (Govaerts et al., 2007). Details of this fire detection algorithm are provided there in full, and are also included in a forthcoming paper (Roberts and Wooster, 2008) and so will not be repeated here.

After the fire detection process, each pixel has its FRP estimated, as a function of the pixels MIR spectral radiance increase above the background non-fire signal. The theory behind this approach to FRP estimation can be found in Wooster et al. (2003; 2005), and Section (1.4) of this document. Hence, much of the fundamental validation work described herein was carried out with dataset covering a full one-year duration (Feb 2004 – Jan 2005) that was produced at KCL by running the first year of operational (non-commissioning phase) Meteosat-8 SEVIRI data through the available IDL-coded processing chain. This product is here referred to as the *KCL FRP dataset*, and is supplemented by Meteosat-9 derived FRP data from July and August 2007 produced by the same system. It is assumed that the validation of the algorithm mathematical concept is independent from the environment where the algorithm is used.

At the start of the validation, a prototype FRP algorithm was developed at EUMETSAT in C language, using the KCL IDL code as the basis but with minor modifications to deal with the operational environment (Lattanzio 2006). The details of this implementation are fully described in Govaerts et al. (2007), and this is the code that runs at the LandSAF processing facility at the IM in Lisbon and which generates the operational FRP product. Data from the LandSAF processing chain was made available later during the FREEVAL study, produced solely from Meteosat-9 SEVIRI data of 2007, and the performance of this *LandSAF FRP* product is here compared to that produced by the KCL processing chain to ensure that it has similar product accuracy characteristics. Some perturbations to performance are expected due to the aforementioned (small) differences in the KCL and EUMETSAT/LandSAF processing chains, and due to unresolved differences between the calibration of the Meteosat-8 and Meteosat-9 imaging radiometers, particularly at higher signals such as are obtained over fires in the MIR channel (Lattanzio and Govaerts, 2006).

Considering the potential aspects theoretically limiting the accuracy and performance of the SEVIRI FRP algorithm and outlined in Sections (1.4) and (1.5), and the availability of FRP products produced via the KCL and EUMETSAT/LandSAF data processing chains, the strategy adopted to validate the SEVIRI FRP product was to individually assess the following aspects:

- (1) **The theoretical and actual performance of the SEVIRI fire detection and FRP algorithm:** This is assessed using model simulations and analysis of the *KCL FRP* product and matching MODIS-derived FRP data.
- (2) **The accuracy and performance limitations introduced due to the SEVIRI instrument characteristics and level 1.0 to 1.5 data pre processing procedures:** This is assessed using model simulations and analysis of

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matching SEVIRI level 1.0 and 1.5 data and data from SEVIRI ‘special’ mode operations

- (3) **The actual performance of the operational algorithm implementation at the Land Surface Analysis Satellite Applications Facility [Land-SAF];** assessed using the *LandSAF FRP* product and comparisons to the *KCL FRP* product and to matching MODIS-derived FRP data.
- (4) **The impact of using it in potential operational applications:** Both the *KCL FRP* and *LandSAF FRP* products have been used in these exercises.

The validation strategy approach comprises both theoretical modelling, including simulations of the spectral energy emissions of fires of different sizes/temperatures and calculations of the atmospheric effects on such signals with the MODTRAN radiative transfer code (Berk et al., 1999), and comparisons to independent observations of the same parameter (*i.e.*, per-fire FRP and per-area FRP) made with the MODIS sensor onboard the polar-orbiting EOS Terra and Aqua satellites. The data sets used in these comparisons are described in Section (3).

Under (1) the underlying assumptions of the FRP algorithm are considered via an analysis of the numerical approximations made during its derivation, and the main error sources impacting the product are considered. In addition, a sensitivity analysis was performed including the effect of SEVIRI MIR channel saturation and background thermal ‘clutter’ (referring to the fact that the background temperature signal upon which the fire signal is superimposed is unlikely to be uniform).

Findings from the simulation are compared to the actual retrieved range of fire characteristics present in the FRP data to determine the consistency of the product in relation to the theoretical performance and determine whether the current error estimations are appropriate. The impact of the SEVIRI 3.9 μm channel saturation was considered in terms of the percentage of observations where saturation has an impact, and its temporal distribution.

The products’ error of fire detection omission, commission and FRP accuracy is assessed via comparison of the *KCL FRP* product to near simultaneous MODIS observations (both at a per-fire level, as well as over fixed grid-cells and regions of the MODIS swath for regional-scale comparisons). This analysis includes an assessment of the fire detection capabilities of SEVIRI in various vegetation cover classes. MODIS was selected as the reference data set because of its relatively finer spatial resolution (1 km at the sub satellite point) and its sufficient data coverage (up to 4-times daily observations over Africa). Daytime and nighttime MODIS to SEVIRI FRP comparisons have been conducted, across the fire-affected regions of the SEVIRI disk. Furthermore, derivative secondary datasets, which are themselves derived from observations made by MODIS are also used. One of these is the Global Fire Emissions Database (GFED) (van der Werf et al. 2006), whose fire emissions calculations are based upon the previously mentioned burned area \times fuel load \times combustion completeness relationship. In version 2 of the GFED database, burned area is actually calibrated from cumulative counts of MODIS hotspots (*i.e.* active fire detections) and a previously derived relationship between this variable and actual area burned in the causal fire (van der Werf et al. 2006).

Under (2) the impact of the observational and data pre-processing procedures used to generate the SEVIRI level 1.5 data product, which is the input to all versions of the FRP processing chain, was assessed via simulation modelling of the SEVIRI observations process when

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viewing active fires, by comparisons of level 1.0 and 1.5 data recorded under standard conditions, and via analysis of co-incident Meteosat 8 and 9 SEVIRI data when the Meteosat 8 instrument was operated in a number of non-standard modes (including a low gain mode to reduce or negate the influence of sensor saturation).

Under (3), the fire detection and FRP products output from the recently implemented LandSAF data processing chain were validated. This chain will ultimately be used to produce the operational SEVIRI FRP product foreseen to be produced from mid-2008 onwards (see <http://landsaf.meteo.pt/algorithms.jsp?seltab=8>). The aim of the LandSAF product validation is to demonstrate that the LandSAF operational products have the same or similar accuracy to those produced by the original IDL code used at KCL. Since the EUMETSAT-derived C code operating at the LandSAF is essentially an implementation of the original KCL algorithm written in IDL, with some small modifications necessary for its implementation in an operational environment, it should be expected that the performance of the two products is similar (Lattanzio 2006).

Finally, under (4), the content, efficacy and value of the spatio-temporal patterns and magnitude of burning provided by the information contained within the SEVIRI FRP product have been assessed via an ‘impact analysis’ study. This was undertaken via inclusion of the data product as an emissions source term in a series of specific impact studies, with comparison of the results to those found when using alternative fuel consumption databases (e.g., GFED version 2, van der Werf et al., 2006) as the source term. In these impact studies, the results of atmospheric modelling applications using SEVIRI FRP information to estimate fire emission fluxes were evaluated with independent data sources measuring the atmospheric composition and its changes due to vegetation fires. The strategic approach comprises the following steps: The FRP product from the KCL chain was formatted and distributed to the users ECMWF and Met Office. Emission factors were used to convert the FRP data to emissions estimates. Due to the need for global emission data sets, SEVIRI FRP derived emissions were superimposed on an existing global data set based on MODIS fire counts (GFEDv2). Model runs with and without blending of the FRP-derived emissions, were conducted in order to assess the adjustments to the model outputs provided by the FRP products inclusion. Comparisons to *in situ* and/or remotely sensed observations of atmospheric constituents (mainly aerosols) perturbed by major biomass burning events allowed for an assessment of the impact of the FRP data product on the model results. Consideration was given to whether adjustments to the FRP product spatio-temporal characteristics or error specifications are required to provide an optimum emissions data source for ingestion into these currently operating simulation models.



2 FRP REQUIREMENT DEFINITION

2.1 *Identification of Potential Operational Users*

In the context of this project we define operational use predominantly as short-term “chemical weather” and “air quality” forecasts and reanalysis simulations of greenhouse gases, aerosols, and reactive gas-phase compounds, all of which are significantly affected by emissions to the atmosphere from open vegetation fires. In light of the ongoing urgent and high-profile development of such services, and given the relatively coarse spatial resolution of the SEVIRI FRP product, these seem certainly the most promising applications in the near future. Other potential applications could include early detection of new fires (for fire fighting and management purposes), the monitoring of land-use change by fire, and assessment of climate impacts on fire activity. FREEVAL established a list of potential applications and contacted a number of key potential users to inform them about the availability of an FRP product from SEVIRI and sample their specific requirements. An evaluation of the product with respect to these ‘secondary’ applications will require another dedicated study.

2.1.1 Chemical Weather Forecasting/Monitoring

Besides the large European efforts in the GEMS project, which includes global trace compound forecasts and analyses at ECMWF as well as a suite of regional-scale European air quality models, there are other similar activities in the United States (Navy Research Laboratories, Monterey, CA; NOAA), Canada (Environment Canada) and in Brazil (INPE-CPTEC). Principal investigators from these initiatives were contacted and expressed their interest in the SEVIRI FRP methodology and in the data product so produced. Due to the similar nature of these systems we expect that they will have very similar requirements as the GEMS system.

GEMS is expected to develop into the core service component of the GMES Atmospheric Service, and several project members already made a commitment to make use of the SEVIRI FRP product in their respective modelling efforts on greenhouse gases, reactive gases, aerosols and regional air quality, respectively. Some further development of the GEMS models is needed before the product can be used as a regular and primary input data set for fire emissions. These developments have been written into the work plan of the GEMS successor project Monitoring of Atmospheric Composition and Climate (MACC). Initial use of the near-real-time SEVIRI FRP product is envisioned for the summer of 2008.

2.1.2 Validation of Prognostic Fire Models and Visibility Forecasts

There are two potential applications of SEVIRI FRP data that were further explored during FREEVAL at the Met Office in Exeter, UK. Firstly, the FRP product can be extended to estimate CO₂ emission released by fires. This, in turn, can be compared to the output of on-line and off-line interactive fire models. Such a procedure allows a useful verification of current fire models. An example of such a comparison is shown in Figure 2.1.

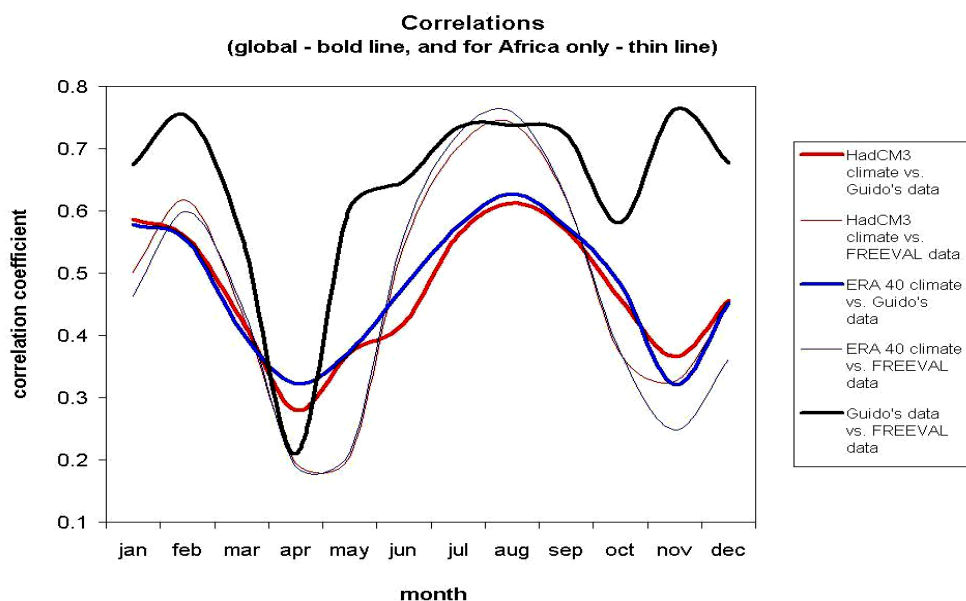


Figure 2.1: Example of a comparison of the correlation of monthly burned area derived from the fire model Had FIRE (using HadCM3 or ERA 40 climate data) with burned area derived from the GFED (Guido van der Werf et al. 2006) and from SEVIRI (FREEVAL).

A temporal resolution of 3 hours is sufficient for this purpose and would allow evaluation of the diurnal cycle of fire emissions, which is known to exhibit large variations in such areas as the African savannah. A spatial resolution of $1^\circ \times 1^\circ$ would match current GCM grid-size. In the case of such model modification/validation applications, there is no need to obtain FRP data in real or near-real time.

A further application of the FRP product lies with visibility forecasts. There is a small but increasing interest from various stakeholders in NRT forecast of atmospheric visibility in different regions of the world. The decrease in visibility associated with open fires requires an accurate source term for the emission of particulate matter from fires. The FRP product can be extended to provide estimates of particulate matter (PM) emissions, with emission factors depending on the type of ecosystem, and possibly the size of the fire. Temporal resolution of 1 to 3 hours and spatial resolution of about 10 km would be sufficient given the current resolution of models used for visibility forecasting at the regional scale.

In conclusion the FRP product will prove very useful at the Met Office as the importance of visibility forecasts and fire modelling grows. The operational provision of the FRP product is therefore strongly encouraged.

2.1.3 Public Information and Safety Aspects

South Africa operates a public fire information system reporting on the nightly weather forecast and on the web (<http://safnet.co.za/>). This is presently based mainly on MODIS active fire observations, though locally generated active fire detections from SEVIRI are available in addition, and the system could well benefit from the inclusion of operationally produced SEVIRI FRP data. Another application is the internal fire early warning system used by ESCOM (South African Power Company), which uses the locally-produced SEVIRI active fire information to determine when and where fires are burning close to electrical power lines. If they are deemed to pose a threat to power safety the line can be shut down

before a ‘flashover’ (essentially a spark induced by the heated air and flames above a fire) can occur. At the present time locally derived MODIS and SEVIRI active fire location data are used for this application, and discussions with ESCOM resulted in the quote that the SEVIRI data were actually the most useful for the purpose due to its capability to detect rapidly changing fires, and the possibility for near realtime data transmission. Whilst MODIS can detect smaller fires, its usefulness is limited by the far less frequent nature of the observations. The potential value of additional FRP information to this application was determined using SEVIRI-derived FRP data for 2004 for fires that were identified as being close (within 10 km on the SEVIRI observational grid) to a power line.

Figure 2.2 confirms that fires that resulted in flashovers have, on average, an FRP that is higher than those that do not, and that the difference is statistically significant. This implies that the operational provision of SEVIRI FRP data might lead to an improved warning system at ESCOM and potentially other electric power companies in Africa.

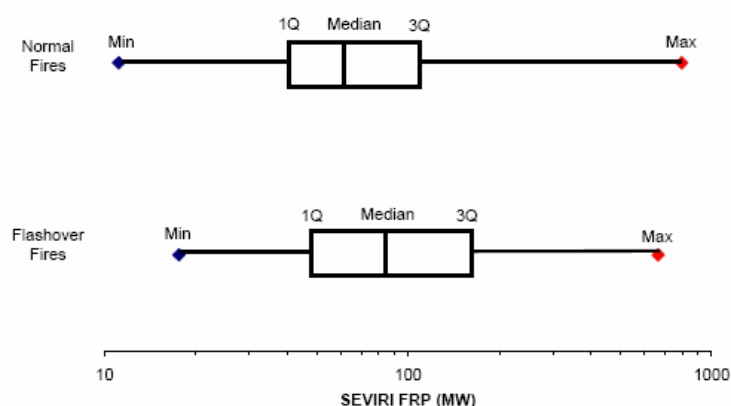


Figure 2.2: Differences in FRP for fires related to flashover events and those that pass within 10 km of the transmission line but which do not result in a flashover.

2.1.4 Scientific Studies

Several members of the atmospheric science community have expressed great interest in SEVIRI FRP data, because of its potential to improve accurate quantification of trace compound emissions from fires and to study fire behaviour and climatology in Africa and southern Europe. Through the combined use of multiple remote sensing products, a more accurate and reliable quantification of fire emissions should become possible. As stated previously, the presently employed method for estimating fire emissions as input to atmospheric modelling studies relies on knowledge of the pre-burn fuel load and the combustion completeness. The SEVIRI FRP product can provide an independent validation for this approach. Figure 2.3 shows an example of such a comparison, where the SEVIRI time-integrated FRP data of a series of fires located in southern African grasslands and woodlands has been converted to a measure of fuel consumption via the method of Wooster et al. (2005). This is then compared to the pre-burn available fuel estimates, which have been derived from the burn scar area (as measured by manual mapping from MODIS level 1b 250 m spatial resolution NIR spectral reflectance imagery) and time integrated estimates of net primary production (NPP) made over the area of each burn scar during the prior growing season. The NPP data were obtained from the “geoscience” portal, and are derived from use



of SPOT-VGT spectral reflectance measures and a light use efficiency plant growth model (www.geosuccess.net/geosuccess/relay.do?dispatch=NPP_info). The ratio of the actual estimated fuel consumption to the available fuel consumption provides an estimate of the proportion of fuel combusted (*i.e.*, the “combustion completeness”) for this particular land cover type and time of year. As can be seen from Figure 2.3, the estimate of combusted biomass derived from SEVIRI is correctly below the estimate of available biomass for all fires examined.

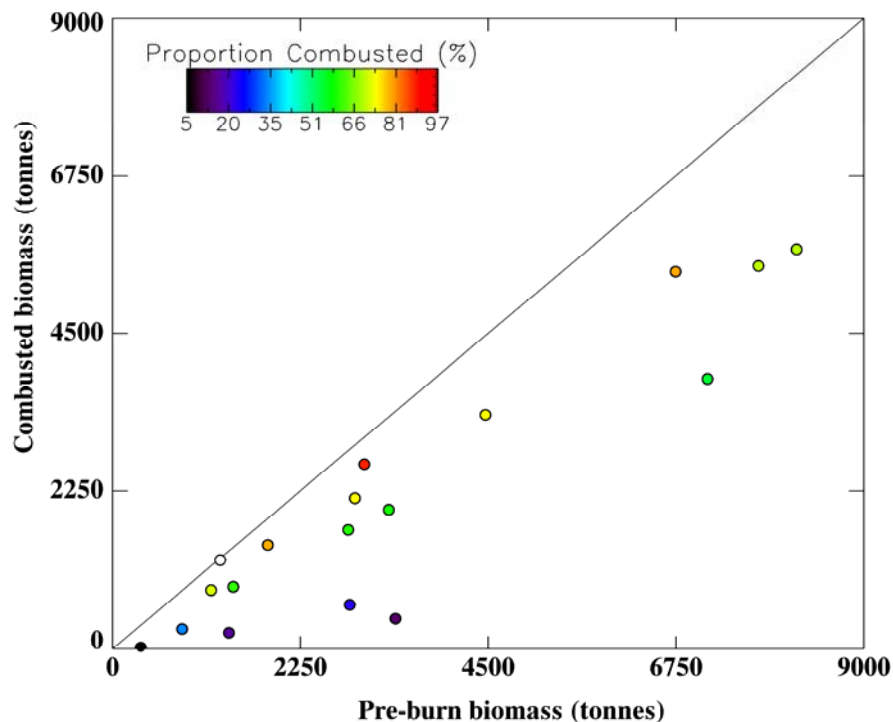


Figure 2.3: Estimates of SEVIRI FRP-derived biomass combustion as compared to the pre-burn fuel load for eighteen fires in southern African grasslands and woodlands. The latter was calculated from SPOT-VGT derived NPP data and burned area measures taken from MODIS. The ratio of the two provides an estimate of the proportion of available fuel combusted.

2.2 Requirements Analysis

The requirements of operational and scientific users of the FRP product can be categorized as follows:

- accuracy: what are the acceptable errors of omission and commission and what is the required accuracy of the derived FRP?
- resolution: is the relatively coarse spatial resolution of the SEVIRI MIR channel adequate for fire detection?
- measurement frequency: is the time interval of 15 minutes between SEVIRI scenes adequate to capture fire variability?
- data delivery and formats: how fast (timeliness) do users need the data and in which format should the data be provided?

Active fire products are by necessity subject to errors of omission and commission since at their heart is an anomaly detection procedure working on thresholding of image radiance and brightness temperature signals (Figure 1.1). This anomaly detection procedure will not



successfully capture all pixels containing active fires, and will indeed very likely report some pixels where the supposed ‘anomaly’ is not caused by fire. Generally speaking, if an active fire product is made less sensitive in order to reduce false alarms (*i.e.*, errors of commission) then its errors of omission will very likely increase, so there is a balance to be struck. Giglio *et al.* (2003b) report the errors of commission of the widely used TRMM VIRS active fire product as, on average, $\sim 10\%$ for a spatial resolution that provides 4 km^2 pixels at nadir. The fire detection false alarm rate present in the SEVIRI FRP product should ideally be no higher than this, but the errors of omission are expected to be larger than for TRMM VIRS due to SEVIRI’s lower spatial resolution. It is difficult to formulate precise requirements for omission and commission errors, because the impact of such errors will depend on the application and its degree of aggregation and processing of the individual SEVIRI slot-level data products, and because the product errors are not independent of each other and one needs to find a balance between these errors so as to maximize the product usefulness. As a general rule, the level of fire detection omission for SEVIRI should be such that the fire pixels that it does successfully detect are responsible for the majority (*i.e.* $> 50\%$) of the FRP actually being emitted at the time of observation (this can be verified via simultaneous use of a higher spatial resolution sensor, such as MODIS). Furthermore, the size spectrum of detected fires should ideally be unbiased (beyond a set lower FRP threshold) such that extrapolation of frequency – magnitude relations (Roberts *et al.*, 2003) can in theory be applied to estimate the frequency of ‘missing’ (undetected) low FRP fire pixels that are below the detection threshold.

In terms of the accuracy of the FRP observations made for the detected fire pixels, it is worth considering the theoretical optimum performance that can be achieved. The relatively high spatial resolution (370 m) BIRD sensor, that was designed specifically for active fire observations, and which was used by Wooster *et al.* (2003) in the derivation of the MIR FRP algorithm, is reportedly able to measure the FRP of around 75% of detected active fire pixels to within $\pm 30\%$, assuming perfect knowledge of the atmospheric transmissivity (Zhuckov *et al.*, 2005). It can be expected that SEVIRI with its coarser resolution and lower saturation temperature will yield somewhat larger errors than this. Since the accuracy is largely limited by the measurement of the background radiance that has to be determined from neighbouring pixels, it contains a random error term, which will decrease in relative magnitude when several fires are aggregated as in a gridded FRP product. Furthermore, as noted above, there are ways to improve estimates of total FRP within a grid cell if a correction for small fires escaping detection is applied (*e.g.* based on extrapolation of frequency magnitude statistics).

Finally, for the purpose of estimating combustion totals from SEVIRI data, one needs to consider that these are to be estimated as the time-integrated values of FRP, which will tend to reduce the impact of random error on each individual FRP observation. Specifically, it should be recognised that many applications are focused not on the use of per-slot FRP measures of individual fires or fire pixels, but on spatial and temporal aggregations of such measures so as to derive estimates of the overall amount of a chemical species emitted over a particular area and time (*e.g.* a 1 degree resolution spatial grid, over a 1 hr period) and as such the influence of random errors in FRP characterisation will be reduced in these applications via this spatial and temporal aggregation.

The spatial resolution requirements of the FRP product can be summarized as follows: for early detection and fire warning systems, it must be as high as possible – ideally, the fire position should be discernible within a few hundred metres. Nevertheless, even a coarser resolution product can be of use for these applications, in particular when it is delivered

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rapidly and with temporal sampling frequencies of less than 1 hour. Inclusion of fire data for emission estimates in global and regional modelling applications generally poses less stringent resolution requirements, although some regional models are run on grid scales of 5 km × 5 km or less.

Since fire characteristics are extremely variable, a high temporal sampling frequency is desirable, and it is clear that a geostationary platform offers great advantage in this respect. Due to the fact that in the past data with less than daily coverage has hardly been available, and even these data proved highly useful in the various applications of fire satellite observations, it may be premature to define strict thresholds for the temporal sampling frequency requirements. From the feedback we gathered from various users it certainly seems as if the 15-minute sampling frequency provided by SEVIRI is adequate, though for “emergency response” type applications the delay between the collection of the level 1.5 source data and receipt of the locational information on new actively burning fires should be kept to an absolute minimum.

Atmospheric composition forecasts and event warning applications require a timely delivery of fire data products, ideally within less than 15 minutes after sampling. Other applications, notably for model validation and carbon budget studies, have much less stringent or no specific timeliness requirements. It should be noted that there is presently hardly any fire data set covering Africa and Europe that is delivered operationally and in near realtime. Therefore, even if the 15-minute requirement cannot be strictly met, a regular near-realtime data product from SEVIRI would improve the status quo and would be welcomed by all users. Data formats don’t seem to be a major issue, but some users expressed wishes concerning the use of specific dissemination channels so that their access is guaranteed.

2.3 Requirement summary

The following Table summarizes the temporal, spatial and accuracy requirements that were expressed by various user communities. Note that in particular the spatial resolution requirements refer to the resolution used in the various applications. Fire detection and derivation of FRP generally require data with finer resolution than what the applications will use.



User community	<i>User requirement</i>				
	<i>temporal resolution</i>	<i>spatial resolution</i>	<i>timeliness</i>	<i>accuracy</i>	<i>Notes</i>
GEMS ¹	15-60 min (3 hours)	25-50 km for global system, 5-50 km for regional air quality models	15-30 min after image acquisition (less than 6 hours)	25-50% error, aggregated within model grid box after correction for missing small fires	Access at ECMWF; includes reprocessing of past periods
CPTEC-INPE	1-2 hours (3 hours)	pixel - 50 km	30 min	as above	Access from Brazil; ftp access requested
Visibility forecast	1-3 hours	10 km	3-6h	<100% error	
Carbon budget study	daily integrals	1 deg	1 month	25-50% error, aggregated within model grid box after correction for missing small fires	Reprocessing of past SEVIRI observations
fire climate model development	3 hours	1degree	1 month	25-50% error, aggregated within model grid box after correction for missing small fires	Reprocessing of past SEVIRI observations
SA FIS	15 min	Pixel	asap (e.g. 15 min of end of slot)	Errors of omission and commission as low as possible, FRP uncritical	
Emergency response	15 min	Pixel	asap (e.g. 15 min of end of slot)	Errors of omission and commission as low as possible, FRP uncritical	

asap= as soon as possible

¹ this includes the GEMS follow-up project MACC and ultimately the GMES Atmospheric Service

Table 2.1: User requirements for operational use of the SEVIRI FRP product. Unless otherwise stated, the requirements should be seen as target requirements. Where a range is given, the lower value represents the optimal value and the upper value the target requirement. In cases where a clear threshold requirement can be identified, this is listed in paranthesis.



3 VALIDATION DATASET DESCRIPTION

The independent validation data came mainly from the MODIS active fire products, and specifically the fire detections recorded in the MOD14/MYD14 product (Justice *et al.*, 2002; Giglio *et al.*, 2003) collected by the MODIS sensors onboard the EOS Terra and Aqua satellites. Various study periods have been selected as described below. SEVIRI data was acquired from MSG-8 and MSG-9 and processed either at KCL, EUMETSAT or the Land SAF data processing centre. Radiative transfer modelling at KCL was performed using MODTRAN v4 (Berk *et al.*, 1999). Other datasets used in the validation were the Global Land Cover Map 2000 (GLC2000; Mayaux *et al.*, 2004) to prescribe landcover type. Validation of emission estimates and performance analysis in impact studies was done using the the Global Fire Emission Database (GFED) version 2 and the prototype version 3 (van der Werf *et al.*, 2006), and using the modelling systems at ECMWF (GEMS), the UK Met Office, and the Finnish Meteorological Institute (SILAM). The following sub sections describe these data sets in more detail and discuss some dataset features that are relevant for the SEVIRI FRP validation procedure.

3.1 The MODIS MOD14 Data Set

The MOD14 product is a level 2 data product for thermal anomalies/fire derived from the Moderate Resolution Imaging Spectroradiometer (MODIS) instruments on EOS-Terra and EOS-Aqua (Justice *et al.*, 2002; Giglio *et al.*, 2003). A dataset description can be found on <http://edcdaac.usgs.gov/modis/mod14.asp>. For our analysis we used ver4 of the MOD14 product, and the fire detection abilities of these data in southern Africa have been independently assessed by Morissette *et al.* (2005) against high spatial resolution data from the 15 m – 90 m spatial resolution ASTER imaging radiometer which also flies on EOS Terra. Results from that study demonstrate the strong performance of the MODIS MOD14 fire detection algorithm, since when even when only relatively few 30 m spatial resolution ASTER-derived active fire pixels are present within the MODIS 1 km pixel recorded at the same moment, the MODIS active fire detection algorithm provides a high probability of detection [provided the ASTER fire pixels are distributed in a relatively spatially contiguous manner within the MODIS pixel, as measured here by Moran's I (Moran, 1950)]. When larger numbers of ASTER fire pixels are present within a MODIS pixel (e.g. > 100) the MOD14 product shows strong performance whatever the actual fire pixel spatial distribution at the scale of the ASTER observations.

The MOD14 product contains both a fire pixel mask, but also a near-complete record of the spectral characteristics of both the fire pixel and its neighbouring background pixels. It also contains an FRP record, though this is produced using a different algorithm to that implemented with SEVIRI and which takes no account of the spatially varying pixel size across the MODIS swath (in fact the MODIS algorithm reports FRP in units of W/m^2). **For this reason, during the comparisons made herein, the FRP for each MODIS fire pixel detected by the MOD14 product, i.e., using all confidence levels, was recomputed based on the same equation as for SEVIRI (Equation 1.1), as described in Wooster *et al.* (2005).** Prior to comparisons to SEVIRI, the MODIS-derived FRP data were post-processed to remove the influence of duplicate fire detections in the original MOD14 mask due to the so-called MODIS 'bow-tie' effect that significantly affects far off-nadir views (see below



explanation). The ability of MODIS to measure FRP to a set accuracy and precision has not yet been fully verified due to the difficulties of finding an independent data source covering different land cover and fire regimes. However, testing against BIRD high spatial resolution FRP data derived on a per-fire basis for forest fires in Australia indicated, on average, that the MODIS FRP measure was within 25% of the near-contemporaneously recorded BIRD FRP measure (Wooster *et al.*, 2003). The main reason for the differences were identified as (i) the fact that the MODIS fire detection algorithm failed to identify some parts of the individual fronts of each fire that BIRD successfully managed to detect by virtue of its higher spatial resolution, and (ii) the small time delay, of the order to minutes, between the MODIS and BIRD observations of each fire.

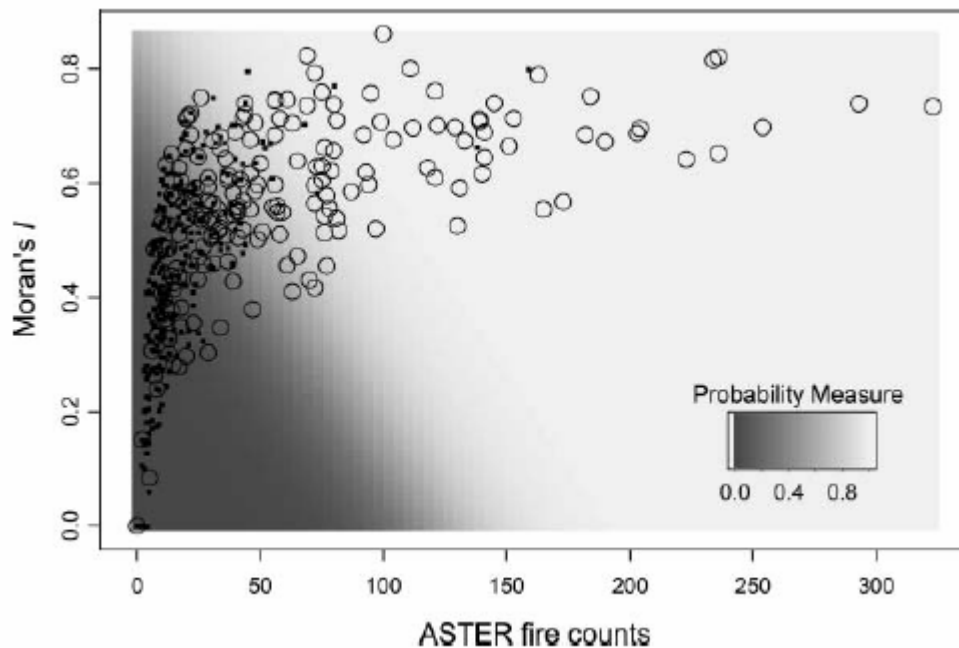



Figure 3.1: Estimated detection probabilities of a 1 km MODIS active fire pixel, calculated as a function of the number of 30 m ASTER active fire pixels it contains, and the spatial distribution of those ASTER active fire pixels (as expressed by Moran's I). Taken from Morisette *et al.* (2005).

3.2 Dataset Used to Investigate Algorithm Assumptions

Numerical simulations using calculations of the spectral radiant energy emissions resulting from bodies of different temperatures, and with atmospheric components of the signal calculated using MODTRAN v4, were used as the primary data to investigate the algorithm assumptions, following in part the methodology adopted previously by Wooster *et al.* (2005) but expanding this to provide an uncertainty estimate for each per-pixel FRP record. Additional data used to parameterise these numerical simulations consisted of radiances recorded in the SEVIRI level 1.5 data product, atmospheric transmissivity values calculated via radiative transfer modelling made at EUMETSAT, and example per-pixel FRP products processed with the KCL and Land SAF data processing chains.

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3.3 Dataset Used to Investigate Per-Fire Comparisons


For the purpose of the per-fire intercomparisons, all the MODIS active fire pixel detections from over 800 individual MODIS active fire products were used. The data were MOD14 (EOS Terra) and MYD14 (EOS Aqua) Level 2 Active Fire Products (Giglio *et al.*, 2003) covering Africa for the matching period of 2004-05 and were obtained through the EOS Data Gateway at the Land Processes Distributed Active Archive Center (LP DAAC). This represents all the active fire pixel detections made by MODIS over Africa in February, May and August 2004, during which time continental-scale fire activity shifted southwards from Senegal and Ethiopia (February) to southern Africa (August). Matching SEVIRI data processed through the KCL data processing chain were selected as those taken within ± 6 minutes of the MODIS overpass, and all such matchups were used in the comparison process.

As mentioned above, prior to the inter-comparison, MOD14 fire detections were post-processed to remove the influence of the ‘bow-tie’ effect, an artifact of the MODIS design that results in off-nadir areas being imaged more than once in successive scans (Wolfe *et al.*, 2002). Double-counted, off-nadir fire pixels were identified using their recorded latitudes and longitudes, and the duplicates removed. The FRP for each remaining fire pixel was then calculated using the MIR radiance method of Wooster *et al.* (2003), applying the MIR radiance method algorithm coefficients presented in Wooster *et al.* (2005) for use with MODIS data and taking account of the changing MODIS pixel area across the swath.

3.4 Dataset Used to Investigate Effects of Spatial Resolution

SEVIRI data obtained from EUMETSAT between February 1st, 2004 and January 31st, 2005 from MSG-8 were used to investigate this issue. With the exception of a few, spurious failures in data acquisition, all images of the full Earth disk at 15-minute temporal resolution were processed over this one-year period. As stated previously, the algorithm used was the KCL geostationary fire detection and characterisation algorithm defined in Robert and Wooster (2008). This algorithm forms the bases (with only minimal changes) of the operational FRP algorithm defined in the ATBD (Govaerts *et al.*, 2007). Only the continent of Africa, including Madagascar, was processed since the algorithm has been optimised for this area, and the vast majority (> 95%) of the biomass burning covered by the imagery was located on the African continent. The active fire detection algorithm uses i.) a novel high spatial resolution cloud mask derived from thresholding of the HRV channel data to supplement the cloud processing scheme of the Meteorological Product Extraction Facility (MPEF) at EUMETSAT (Lutz *et al.* 2003), ii.) a preliminary detection stage with liberal thresholds to identify the maximum number of potential fire pixels, iii.) multiple subsequent stages to minimize false detections due to large uniform areas of warm ground, and sun glint from water bodies or undetected clouds, iv.) a stage to reject potential fire pixels based upon their proximity to a cloud or water body, and v.) a stage to statistically compare the elevated thermal signal of a potential fire pixel relative to the surrounding background.

On average four MODIS swaths per day subtended some portion of the African continent, depending on the exact ground tracks of the polar orbiting, sun-synchronous AQUA and TERRA satellites that carry the MODIS instrument. The fire detections made by MODIS and contained within the aforementioned MOD14/MYD14 active fire products obtained for the same one year time period (February 1st, 2004 and January 31st, 2005) from the LP DAAC were used to identify fire pixels, and for each active fire pixel FRP was calculated via the

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MIR radiance method, taking account of the MODIS pixel area variation across the swath as described above and in Wooster *et al.* (2005).

3.5 Dataset Used to Investigate Effect of SEVIRI Sensor Characteristics and Level 1 to 1.5 Pre-Processing Operations

A key dataset used here was that from a dedicated SEVIRI Fire Radiative Power (FRP) test (so-called SEVIRI ‘special operations mode’) conducted to collect data for an evaluation of the errors inherent in the FRP product due to the SEVIRI standard configuration. In order to do this the following configuration changes were made to Meteosat-8, and co-incident Meteosat-8 and 9 data collected over the duration of the test period (3- 7 September 2007):

- a. Change to SEVIRI Rapid Scan (5 minute temporal resolution) for a latitude range covering 0° to 30° S
- b. Change the digital filter coefficients to a top hat function instead of the standard finite impulse response filter
- c. Reduce the gain for for the 3.9 μm channel to allow measurement up to pixel brightness temperatures of ~ 375 K without sensor saturation.

In addition to exploitation of the data from the above SEVIRI ‘special operations mode’ experiment, the dataset used for this study consisted of a small set of co-incident level 1.0 and 1.5 SEVIRI data obtained over Africa for large fires recorded by Meteosat-9, together with a BIRD Hotspot Recognition Sensor image of southern Africa recorded in 2003 and which contained a series of active fire observations that provided data from which model simulations were derived. Characteristics of the BIRD HSRS imager can be found in Wooster *et al.* (2003) and Zhuckov *et al.* (2005), with the most relevant aspects to this study being the provision of non-saturated MIR channel data at fairly high spatial resolution (370 m pixel size) over even the most intensely burning fires.

3.6 Datasets Used in Impact Studies

3.6.1 Global Fire Emissions Database (GFED)

The SEVIRI-FRP derived fire emission estimates for Africa are compared to the published inventory of the Global Fire Emissions Database (GFED) version 2 (van der Werf *et al.*, 2006). The GFED dataset was compiled using fire satellite data from different sources and the Carnegie-Ames-Stanford Approach (CASA) biogeochemical model. Burned area measures for 2001-2004 were derived from the aforementioned MOD14/MYD14 MODIS active fire (‘hot spot’) data which were calibrated using MODIS 500m burned area estimates for selected regions (Giglio *et al.*, 2006). ATSR (Along Track Scanning Radiometer) and VIRS (Visible and Infrared Scanner) satellite data were used to extend the burned area time series back to 1997 based on simple linear regression between the time periods when both products overlapped (Arino *et al.*, 1999; Giglio *et al.*, 2003; Van der Werf *et al.*, 2006). Fuel loads and net flux from terrestrial ecosystems were estimated as the balance between net primary production, heterotrophic respiration, and biomass burning, using time varying inputs of precipitation, temperature, solar radiation, and satellite-derived fractional absorbed photosynthetically active radiation.



The current version, GFED version 2, is freely available for download from <http://www.geo.vu.nl/users/gwerf/GFED/index.html>. The dataset consists of $1^\circ \times 1^\circ$ gridded monthly burned area, fuel loads, combustion completeness, and fire emissions (Carbon, carbon dioxide (CO₂), carbon monoxide (CO), methane (CH₄), non-methane hydrocarbons (NMHC), hydrogen (H₂), oxides of nitrogen (NO_x), nitrous oxide (N₂O), particulate matter smaller than 2.5 μm diameter (PM_{2.5}), total particulate matter (TPM), total carbon (TC), organic carbon (OC), black carbon (BC)). Emission estimates for the 2001 – 2006 period are also available with an 8-day time step.


For the comparison with SEVIRI-based biomass burning estimates, data from the preliminary ver3 GFED database are also included, because processing newly available burned area data has revealed relatively large changes in Africa [with less burned area (compared to version 2) for northern Africa and more in southern Africa]. For the comparisons presented in section 5.4.2, the GFED version 2 emission estimates were therefore scaled with the ratio between burned area from version 2 and 3 in order to produce a prototype GFED ver3 emissions estimate. The final version 3 will include other important changes, so that the GFED ver3 emissions presented here should be considered a preliminary data set only.

3.6.2 Global GEMS Model

The Global and regional Earth-system Monitoring using Satellite and in-situ data (GEMS) project is combining the manifold expertise in atmospheric composition research and numerical weather prediction of thirty-two European institutes to build a comprehensive monitoring and forecasting system for greenhouse gases, reactive gases, aerosol, and regional air quality (Hollingsworth *et al.*, 2008). The project is funded by the European Commission as part of the Global Monitoring of Environment and Security (GMES) framework.

As part of the GEMS project, prognostic representations of aerosols and greenhouse gases are being developed in the ECMWF Integrated Forecast System (IFS), in both its analysis and forecast modules. An experimental version of the global forecast model now accounts for five tropospheric aerosol types (i.e. sea-salt, desert dust, organic matter, black carbon and a sulphate related variable), carbon dioxide and methane. The sources for all species are located at the surface. The species are advected and included explicitly in the vertical diffusion and mass-flux convection schemes. The greenhouse gases have sinks at the surface only, while the aerosols undergo sedimentation and dry and wet deposition by large-scale and convective precipitation (Morcrette *et al.*, 2008). Feedbacks of the aerosol and greenhouse gas fields on other atmospheric variables are not included in the current model version.

Biomass burning emits carbon dioxide, methane, organic matter, black carbon, and sulphate and some of its precursors. The global GEMS system currently accounts for these emissions using the aforementioned retrospective inventory GFED version 2, that has a temporal resolution of 8 days (van der Werf *et al.*, 2006). However, this approach is only a temporary solution. In the operational phase, more and better fire observations need to be acquired in near realtime and assimilated to obtain accurate atmospheric composition estimates (Kaiser *et al.*, 2006). For the impact studies described in this report (section 5.4.3) the SEVIRI FRP product was used to provide a greatly improved temporal resolution over the observed areas, and GFED ver2 provided the source terms outside of the SEVIRI-observed regions of Africa and Southern Europe. The latest information on the GEMS system can be found on the project home pages at http://www.ecmwf.int/research/EU_projects/GEMS/index.jsp.

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3.6.3 SILAM Dispersion Model and Fire Assimilation System at FMI

The Finnish Meteorological Institute (FMI) is producing regional PM_{2.5} aerosol concentration forecasts with the SILAM dispersion model driven by emissions calculated with the FMI Fire Assimilation System (FAS). The FMI FAS is based on fire observation products over Northern Europe from the MODIS instrument. It uses the products of either temperature anomaly (TA) [K] or fire radiative power (FRP) [W], both with a temporal resolution of one day. Calibration of both FAS versions was started from literature data, *e.g.*, Ichoku and Kaufman (2005). Then the emission factors were fine-tuned using a model-based approach. Namely, FMI took a few fire cases, primarily in 2006, estimated their emissions of PM_{2.5}, ran the SILAM dispersion model and compared total column loads and near-surface concentrations with available observations. The systematic deviation was eliminated via adjustment of the emission factor. More information on SILAM can be found at <http://silam.fmi.fi>.

3.6.4 MOPITT Atmospheric Carbon Monoxide Concentration Data

Carbon Monoxide column concentrations, and vertical profiles, are provided by the Measurements of Pollution in the Troposphere (MOPITT) instrument on EOS Terra (http://terra.nasa.gov/About/MOPITT/about_mopitt.html). MOPITT is an 8-channel nadir infrared instrument with a 22 km pixel spatial resolution designed to detect trace gas signals of carbon monoxide (CO) and methane (CH₄) in the troposphere. Via the application of different weighting functions, CO vertical profiles can be retrieved for independent levels within the atmosphere.

For the impact study presented in section 5.4.2, MOPITT level 3 (ver 3) data derived via averaging the daily level 2 product into a global 1°×1° dataset and obtained from the NASA Langley DAAC (http://eosweb.larc.nasa.gov/PRODOCS/mopitt/table_mopitt.html) were used. The MOPITT level 3 data contain retrieved CO profiles for seven pressure levels, day / night total column CO concentration and various quality indicators. Following the filtering approach implemented by Hyer *et al.* (2007), the ‘percent *a priori*’ quality indicator is used to filter out retrievals which were composed of greater than 40% of *a priori* profile. In addition to this, only daytime cloud free (as determined from the MOPITT cloud mask) land pixels are used in the analysis.

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4 Specific Validation Methodology

4.1 Algorithm Performance Analysis

As explained in Section 1.4, the following assumptions are made in the FRP algorithm derivation and application of the approach in the SEVIRI FRP product:

- i. Over the temperature range relevant to active fires, Planck's radiation law is well approximated by a fourth order power law in the 3.4–4.2 μ m interval (as implied in the derivation of the scaling factor a of Equation 1.1, shown in Section 1.4.).
- ii. The approximations made during the derivation of the equation to estimate the fires contribution to the fire pixels MIR spectral radiant emission (Equation 1.6) are valid.
- iii. The background MIR radiance signal of the fire pixel can be appropriately estimated from analysis of the neighbouring non-fire, non-cloudy pixel group. At present the mean spectra radiance of this pixel group is used.
- iv. The effects of aerosols and trace gases (beyond those in the ambient atmosphere) are not taken into account, and the atmospheric transmissivity assumed in the application of the algorithm is a reasonable estimate of the true atmospheric transmission in the 3.4 – 4.2 μ m interval.

In addition, it is assumed that the fire (and background) thermal emission is isotropic and that the fire behaves as a grey body. These assumptions (or indeed, quite commonly the even more stringent assumption that the fire is a blackbody) are made in all existing applications deriving fire radiative power, and cannot be easily checked without detailed field experiments that have not been carried out. They will therefore not be addressed here.

The investigation of the theoretical FRP algorithm performance analysis was based around an analysis of these assumptions and a sensitivity study of the FRP algorithm. The effect of assumption (i) above (the fourth order power law approximation) was analysed by first comparing FRP derived using Equation 1.1 to that derived from the true Stefan Boltzmann Law. The effect assumption (ii) was investigated using a radiative transfer modelling study simulating the radiances measured over sub-pixel sized fires observed from space, and then using these within Equation 1.1 to estimate the fires FRP using the equations applied during the SEVIRI FRP processing chain. These estimates were then compared to the true fire FRP calculated using the Stefan Boltzmann Law. Finally, the impact of uncertainty in the background radiance field, and in the atmospheric parameters (assumptions iii and iv), was considered using a sensitivity study that perturbed these values prior to incorporation into within FRP algorithm. The appropriate range of atmospheric transmissivity in the 3.4 – 4.2 μ m interval (that covered by the SEVIRI MIR spectral band) was taken from the ATBD (Govaerts *et al.*, 2007), and was assumed to vary over the range 0.61 – 0.7 [mid-range value of 0.66]. Expected uncertainties in the MIR background window pixel signal, and the difference between this and fire pixel background, were taken from SEVIRI level 1.5 data and LandSAF FRP products covering the southern African region.



4.2 SEVIRI Product Performance Analysis

4.2.1 Per-Fire Comparisons

Assessment at the scale of individual fires was performed via a comparison to the aforementioned MODIS active fire observations identified by the MOD14 and MYD14 MODIS level 2 fire products. MODIS is the sensor for which the measurement of fire radiative power was first proposed as a mean of classifying a fire emission source strength (Kaufman *et al.*, 1998).

The analysis was conducted at the scale of individual fires (*i.e.*, clusters of separately identified fire pixels) using data from eight MODIS MOD14/MYD14 products (6 days and 2 nights) from February and August 2004, together with fire detections extracted from the SEVIRI-derived KCL FRP dataset within 6 minutes of the MODIS acquisition time¹. The MIR radiance method algorithm (Equation 1.1) was used to derive the FRP measure of each fire pixel detected by the sensors. The approach followed that first used by Wooster *et al.* (2003) and Roberts *et al.* (2005), clustering groups of spatially contiguous fire pixels in the primary dataset into single ‘fires’ whose total FRP for that imaging slot was then derived, and using the latitude and longitude range of that fire pixel cluster (expanded by the equivalent of two SEVIRI pixels to account for any geo-locational offsets) to check for the presence of the same fire pixel cluster in the reference dataset.

In most cases a fire would be expected to be represented by more fire pixels in the MODIS dataset than in the SEVIRI dataset, due to the higher spatial resolution of the MODIS observations. Comparison of fire detections made by MODIS and SEVIRI allowed for an assessment of the errors of commission (false alarms) and omission (missed fires). When both datasets successfully recorded the presence of the same fire, the total FRP of the fire as recorded by both sensors was compared to assess the ability of SEVIRI to characterise the full FRP of each fire detected.

4.2.2 Effect of Spatial Resolution - Area Based Comparisons

SEVIRI has a nominal sampling distance at the sub-satellite point of 3 km, and a spatial resolution of 4.8 km, the values increasing with distance away from the sub-satellite point. This spatial resolution is relatively coarse compared to most other imaging radiometers currently used for active fire detection and characterisation, most notably the polar-orbiting MODIS sensor which as mentioned previously has a nominal 1 km × 1 km spatial resolution at the sub-satellite point (increasing to ~ 2 × 10 km at the swath edge). Detectability of a fire within a cloud-free pixel depends primarily on the MIR spectral radiance signal increase of the ‘fire pixel’ above that of the surrounding (background) non-fire pixels and/or above the signal of the same pixel in another spectral channel less affected by the presence of sub-pixel fires (e.g. a longer wavelength TIR channel). These signal increases ultimately depend on (i) the fires effective emitter temperature, and (ii) the effective proportion of the pixel covered

¹ The SEVIRI acquisition time is 12 minutes and so every MODIS fire pixel will be observed by SEVIRI a maximum of 6 minutes before or after. Since some fires will get more intense and others less intense between the two sensors “simultaneous” observations, the FRP difference induced by the maximum 6 min time difference should be random rather than in any one direction, and thus the time difference is not expected to introduce bias in the comparison (but it maybe responsible for a large part of the scatter between the data from the two sensors).



by this elevated emitter temperature. These two properties also determine the fires FRP through the Stefan-Boltzmann Law, and so for any particular fire detection algorithm criteria (e.g. a required MIR brightness temperature increase of the fire pixel above that of the ambient background) the corresponding minimum-detectable fire can be calculated in terms of its FRP.

Figure 4.1 shows this calculation for the SEVIRI sub-satellite point over a temperature range wider than that which is assumed valid for open vegetation fires ($\sim 650 - 1300$ K). It indicates that SEVIRI should be able to confidently detect actively burning fires whose FRP reaches a minimum of around 100 MW, and in certain cases maybe able to detect fires whose FRP is even lower than this, down to around 50 MW. Conversely, the calculation also suggests that SEVIRI will saturate over fire pixels whose FRP is greater than around 900-1000 MW.

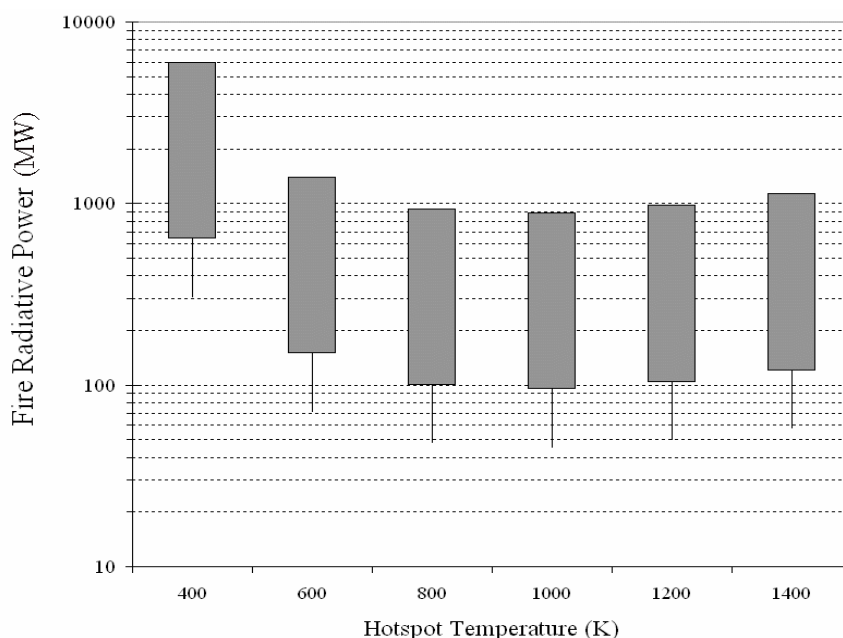


Figure 4.1: Estimated FRP range detectable for various fire temperatures using SEVIRI at the sub-satellite point. Minimum detectable FRP is shown by the vertical line extending below the bar (fire pixel MIR brightness temperature raised 3 K above the background temperature). The lower limit of the black bar indicates the minimum detectable FRP when this threshold is raised to 6 K. The per-pixel FRP that saturates the sensor is shown by the upper limit of the black bar. FRP is calculated in each case by parameterising the Stefan-Boltzmann Law with the relevant fire temperature and area, and is relatively consistent across the assumed fire temperature range since these parameters are inversely related for a particular fire pixel brightness temperature. Calculations were performed using the MODTRAN radiative transfer code (Berk et al., 1999) and assume a mid-latitude summer atmosphere (rural aerosol, 23 km visibility), with a fixed surface reflectance (0.15) and emissivity (0.85) and a daytime solar zenith angle of 20° . Results differ between day and night due to differing assumed ambient background temperatures (day: 300 K, night: 285 K) and the lack of a solar reflected radiation contribution in the latter case.

The calculations presented in Figure 4.1 do not take into account any impact of the finite impulse response (FIR) filter applied in the production of the Level 1.5 SEVIRI data, nor the true SEVIRI pixel oversampling (by a factor 1.6) which is taken into account of during the FRP algorithm application via a reduction in assumed SEVIRI pixel area by the appropriate



oversampling factor in the x and y directions (Govaerts *et al.*, 2007). Taking these factors into account would lead to minimum FRPs returned by the fire detection algorithm when applied to real SEVIRI Level 1.5 data of the order of ~ 40 MW (and at the extreme ~ 20 MW) at the sub-satellite point, whilst maximum retrieved FRP would be expected to be of the order of 400 MW. These values will increase linearly with pixel area away from the sub-satellite point, and Figure 4.1 indicates that FRP retrievals from real SEVIRI data shows a statistical distribution consistent with this modelling. In Figure 4.2, the small number of fires pixels having FRP > 400 MW are the result of fire detections at pixels well away from the sub-satellite point, and thus which are able to record FRP values higher than is possible at that location.

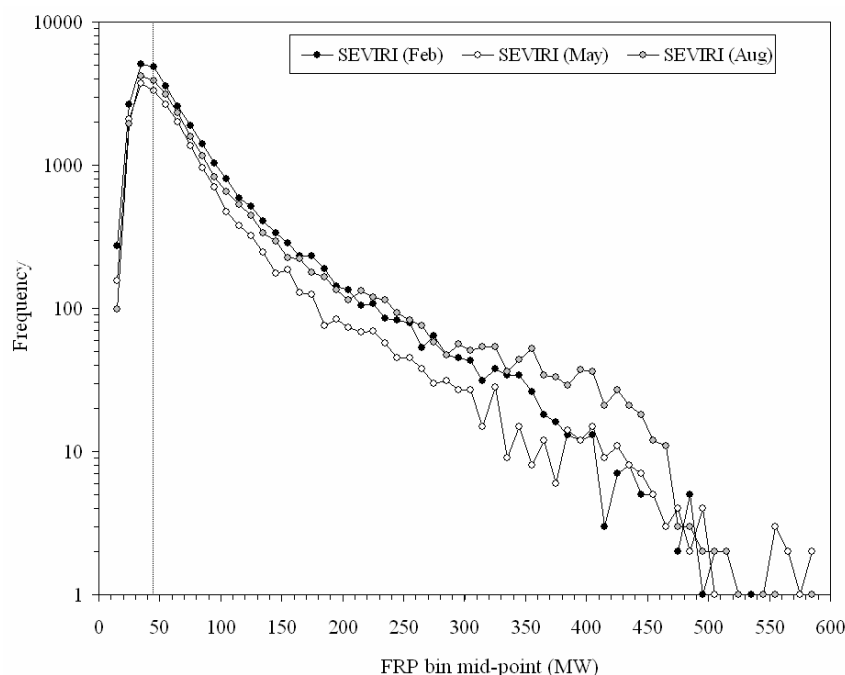



Figure 4.2: Frequency-magnitude of per-pixel FRP derived from SEVIRI active fire detections, binned into 10 MW intervals. Data are all SEVIRI fire pixel detections made across Africa using the KCL algorithm over the periods February, May, and August 2004. Only SEVIRI images matching the MODIS overpass time and swath were used to produce this plot, since the same data are used later to compare to MODIS. The vertical dotted line indicates the 40-50 MW threshold, indicated by modelling as the approximate minimum fire FRP that can be confidently detected by SEVIRI. Here the frequency of fire pixels with an FRP lower than this is significantly reduced, and thus these data are in accordance with that prediction.

In contrast to SEVIRI, the much higher spatial resolution MODIS sensor can detect fire pixels whose FRP values are as low as 7 - 10 MW. From this analysis, it is very clear that SEVIRI will fail to detect some fire pixels that MODIS can detect.

Whilst such low FRP fire pixels are each themselves responsible for only a small amount of the total emitted FRP of an area, Figure 4.2 confirms that the statistical distribution of per-pixel FRP is skewed towards low FRP fire pixels. For this reason, the overall FRP underestimation resulting from SEVIRI's inability to detect the lowest FRP fire pixels can be substantial.

The degree of regional-scale underestimation inherent in the SEVIRI data products is, however, slightly more complex than can be gauged by simply applying a minimum FRP

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detection threshold to a set of MODIS-derived FRP data in order to determine which fires SEVIRI would detect and which it would not. This is because individual MODIS-detected fire pixels, that each may have a lower FRP than the SEVIRI FRP detection threshold, may still in fact have their FRP characterised by SEVIRI if they are arranged spatially such that a sufficient number of them contribute to the signal of one SEVIRI pixel (and thus result in a per-pixel FRP measure higher than the SEVIRI minimum FRP detection threshold). For this reason, the best way of gauging the impact of the effect of SEVIRI's lower spatial resolution on regionally aggregated FRP measures is to directly compare simultaneously-derived MODIS and SEVIRI active fire detections and FRP retrievals, with the assumption that the MODIS-derived record represents the true representation of the regionally-aggregated FRP from all fires burning in the area.

It was expected that the degree of underestimation inherent in the SEVIRI-derived FRP measures might vary in space and time, due for example to changes in the FRP frequency-magnitude relationship over burning season (e.g. from early to late dry season). For this reason, the magnitude of the FRP underestimation inherent in the regional-scale SEVIRI-derived FRP measures was investigated spatially over the entire continent of Africa for the period Feb 2004 - Jan 2005, using the KCL derived FRP dataset and a matching MODIS-derived dataset extracted from the year-long MOD14/MYD14 archive of the same area. This investigation has particular relevance to the proposed production of a SEVIRI-derived FRP gridded product at 0.5 or 1.0 degree grid resolution and which is proposed to best represent the mean FRP emitted by all fires in each cell averaged over one hour intervals (Govaerts *et al.*, 2007). In this dataset, the SEVIRI-derived FRP signals within each grid cell would ideally be adjusted to the value that MODIS would have seen had it been the observing instrument (remembering that the advantage of actually using SEVIRI rather than MODIS is that it provides data at a very much higher temporal resolution than MODIS, and which is in theory available in near-real time for use in the derivation of short- to medium-term atmospheric forecasts). For this reason, potential methods to adjust the proposed SEVIRI-derived FRP gridded product for the expected effects of FRP underestimation were also implemented, and their efficacy assessed via testing with an independent MODIS- and SEVIRI-derived FRP match up dataset collected in August 2007.

4.2.2.1 Basic Approach

Regional scale FRP comparisons were first conducted by comparing the cumulative (aggregated) within-scene FRP observed near simultaneously by SEVIRI and by MODIS over the area equivalent to the full MODIS swath and latitudinal image extent, together with visual examinations of the active fire pixel detections made across key-fire affected regions of Africa. This analysis used data from three separate months of 2004 where fires were predominately located in North Africa (February), Central Africa (May) and Southern Africa (August). As will be shown in section 5.2.2, this analysis established a substantial difference between the MODIS and SEVIRI area based FRP measures in all regions, and one that varied in time/space, and so confirmed the need for a more complete investigation covering the full year of continent-wide data.

This longer-term investigation again used a 'validation dataset' consisting of active fire detections made only with near-simultaneous SEVIRI and MODIS fire pixel and FRP observations collected over the same geographic extent. Fire pixels reported by the MOD14 and MYD13 MODIS products were temporally subset to within ± 6 minutes of a SEVIRI



scan, and this time were also spatially subset to include only those detected within the center two-thirds of the MODIS swath, specifically between columns 225 and 1129, in order to reduce any effect introduced by the very large MODIS pixel areas that are found towards the edges of the MODIS swath. As previously mentioned, at these locations the MODIS “bowtie effect” (Wolfe, 2002) is known to (i) induce multiple, overlapping detections for a single fire occurrence, (ii) reduce the absolute number of detections at extreme view angles since an elevated thermal signal is required to overcome the increased ground sampling area, and (iii) as a consequence of (ii), produce fire pixels with mean FRP values significantly greater than those interior to the swath. Conversely, fire pixels detected by SEVIRI were temporally subset to only those within ± 6 minutes of a MODIS overpass, and also spatially subset to a convex hull encompassing the MODIS-detected fire pixels within the centre $2/3^{\text{rds}}$ of the MODIS swath. Given that SEVIRI is less responsive than MODIS to the lower FRP fire pixels that sometimes exist along a fires’ perimeter, the potential number and intensity of SEVIRI fire pixels lying outside a convex hull of MODIS fire pixels was considered negligible.

If there were insufficient MODIS fire pixels to perform a convex hull operation (e.g., if there only existed one or two MODIS fire pixels in a scene) then a 2 km square buffer around the identified MODIS fire pixels was used instead of the convex hull. The procedure for subsetting all SEVIRI and MODIS data to concurrent and collocated fire pixels essentially imposed the temporal resolution and spatial coverage of MODIS onto the SEVIRI temporal cycle and spatial extent -- as is demonstrated in Figure 4.3. For brevity, this temporal and spatial subset of the combined SEVIRI and MODIS fire products across Africa in 2004/05 is hereafter referred to as the “training dataset.”

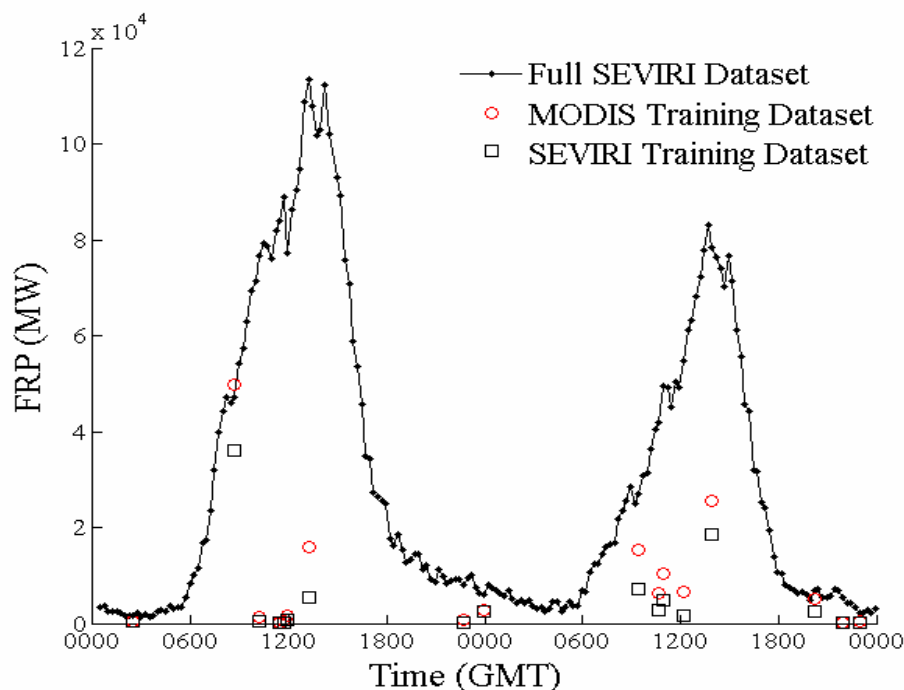


Figure 4.3: Temporal profile of FRP measured by SEVIRI and MODIS over two consecutive days. The full SEVIRI dataset (—●—) contains fire pixels at continental coverage and 15-minute temporal resolution. Observations in the training dataset for SEVIRI (□) and MODIS (○) are composed of concurrent and collocated fire pixels within the center $2/3^{\text{rds}}$ of a MODIS swath.

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4.2.2.2 Detailed Sensor-to-Sensor Comparisons of Fire Activity Over the Annual Cycle

Sensor-to-sensor comparisons were performed by calculating the SEVIRI to MODIS ratios of both total fire pixel counts, ϕ_{count} , and total FRP, ϕ_{FRP} . Within the training dataset, the yearly ratios of total fire count and total FRP were calculated simply by summing the number of individual fire pixels and their respective FRP, then dividing the SEVIRI totals by the MODIS totals. This provided the base information of the extent to which SEVIRI underestimates fire pixel count and FRP with respect to MODIS, and how this varies seasonally.

To assess the effects of temporally aggregating the fire pixels, ϕ_{count} and ϕ_{FRP} were calculated in discrete, non-overlapping intervals of one-day, one-week, and four-weeks beginning from the time of the first observation. Widening the temporal window essentially expanded the number of samples available to calculate ϕ_{count} and ϕ_{FRP} . Ratios of fire pixel counts and FRP were assigned timestamps corresponding to the centre of each temporal window such that:

$$\phi_{FRP}\left(t + \frac{\Delta t}{2}\right) = \frac{\sum_{i_{SEVIRI}=1}^{n_{\Delta t}} FRP_{i_{SEVIRI}}}{\sum_{i_{MODIS}=1}^{n_{\Delta t}} FRP_{i_{MODIS}}}$$

Equation 7

where t is the serial time at the beginning of the day, week or four-week interval, Δt is the duration of the interval, i_{SEVIRI} and i_{MODIS} are indices of the fire pixels detected by each sensor, $n_{\Delta t}$ is the total number of fire pixels detected by each sensor within the respective interval, and FRP is the fire radiative power associated with each fire pixel. The ratio of fire pixel counts, ϕ_{count} , is simply the values of $n_{\Delta t}$ for SEVIRI divided by that for MODIS.

Since fire activity varies with the season, as well as with ecoregion and land use, the patterns of ϕ_{count} and ϕ_{FRP} were also mapped spatially. For comparison, the full continent of Africa was gridded at 5.0°, 1.0° and 0.25° grid cell resolutions. Spatially explicit yearly ratios of count and FRP were calculated by summing all concurrent and collocated fire pixels detected in a single grid cell throughout the year, and again then dividing the SEVIRI totals by the MODIS totals within each grid cell.

4.2.2.3 Potential Adjustment of SEVIRI Gridded FRP Data for the Effect of Undetected Fires

Statistical distributions of FRP measured by SEVIRI suffer from left-hand truncation due to the inability of the sensor and active fire detection algorithms to reliably distinguish low FRP fires, an effect illustrated in Figure 4.3 above. Figure 4.4 shows the effect of this truncation on the FRP frequency-magnitude distributions obtained from the matched SEVIRI and MODIS training dataset, and it can be seen that the distribution here is in agreement with that of full SEVIRI data set displayed in Figure 4.2. It also confirms that for MODIS, the minimum FRP detection threshold for reliably detected fire pixels is ~ 7 – 10 MW. Right hand truncation of the distributions is also seen, and this is due to the effects of sensor saturation occurring at a lower FRP for SEVIRI than for MODIS due to the low gain, high saturation temperature of the MODIS MIR channel (Kaufman *et al.*, 1998).

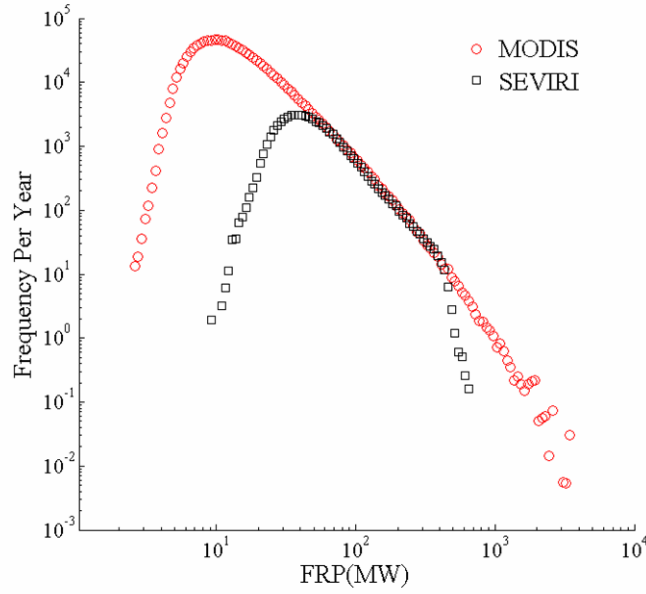


Figure 4.4: Frequency-magnitude distributions for all contemporaneous SEVIRI and MODIS fire pixels detected across Africa in Feb 2004-Jan 2005 (i.e. the training dataset discussed herein).

To account for the artefacts illustrated in the above frequency magnitude plot, two simple methodologies were tested for adjusting the full SEVIRI dataset at 15-minute temporal resolution and continental coverage. Both methods relied on the relationships developed within the one-year training dataset. The first approach simply interpolated the temporal profile of ratios calculated within the training dataset described previously, initially on a non-spatial basis by combining data from the whole continent together for each temporal window considered. As will be justified in the results, instead of incrementing the temporal window by a discrete week, however, a rolling weekly window was incremented by a single day over the year to provide 365 weekly ratios at daily temporal resolution:


$$\phi_{FRP}\left(t + \frac{\Delta t}{2}\right) = \frac{\sum_{i_{SEVIRI}=1}^{n_{\Delta t}} FRP_{i_{SEVIRI}}}{\sum_{i_{MODIS}=1}^{n_{\Delta t}} FRP_{i_{MODIS}}}$$

Equation 8

where t is the serial time at the beginning of each day, Δt is a constant interval of one week, and $n_{\Delta t}$ is the total number of fire pixels detected by each sensor within the week.

The rolling weekly ratios calculated for each day had the following characteristics: i) ratios were assigned timestamps at the middle of the rolling weekly window, i.e., at 12:00 on the 4th day of the week, ii) ratios on sequential days shared fire pixels that were detected over six of the previous seven days used to construct the ratios, and iii) only the ratios between days 4 and 362 were considered valid since the weekly window was moving into and out of the training dataset at these times respectively. Ultimately the values for ϕ_{count} and ϕ_{FRP} at each of the 96 daily SEVIRI timeslots were derived by linearly interpolating between the ratios obtained from Equation 4.2.

Adjusting SEVIRI's response to fire activity in the manner described above assumes that the sensor-to-sensor ratios in the training dataset are valid outside the MODIS ground coverage over which they were originally developed, and that the temporal trend of the ratios in the

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training dataset was valid for SEVIRI observations occurring between the MODIS overpass times. Furthermore this technique is not spatially explicit, since adjustments are performed at the continental scale using all fire pixels detected by SEVIRI at each timeslot.

The second method to adjust SEVIRI measurements was designed to incorporate both the temporal and spatial variability of ϕ_{count} and ϕ_{FRP} . To do so, the continent of Africa was gridded into 5° resolution cells for each calendar month, with a total of 16×16 grids covering the continent (a domain of $80^\circ \times 80^\circ$, with identical boundaries as the grids defined in the previous section). All fire pixels detected by SEVIRI and MODIS within the training dataset were summed in each grid cell for each calendar month, and spatially explicit monthly ratios calculated by dividing the SEVIRI totals by the MODIS totals. Where and when in the 2004/05 training dataset that SEVIRI detected fire pixels but MODIS did not, or MODIS detected fire pixels but SEVIRI did not, the yearly ratios of ϕ_{count} and ϕ_{FRP} were stored in the monthly grid product by default. Justifications for the use of a 5° grid cell resolution and a monthly temporal window are presented in the results section.

For validation of the approach, the set of 12 monthly spatially explicit ratios were first applied to the full 2004/05 SEVIRI active fire dataset at 15-minute temporal resolution and continental coverage. For each of the 96 SEVIRI timeslots per day, the number of fire pixels and FRP detected by SEVIRI in each 5° grid cell were summed and divided by ϕ_{count} and ϕ_{FRP} that were stored in the respective monthly grid product. As a pseudo-validation exercise, the adjusted FRP_{SEVIRI} at each timeslot was then spatially integrated (i.e., summed over the continent) and compared to the adjusted SEVIRI measure obtained through the linear interpolation of the rolling weekly ratios. A comparison of the two techniques can at best be considered as semi-independent validation of the monthly grid product via comparison to the continent-wide adjustment procedure.

A full independent validation was conducted by using concurrent and collocated fire pixels detected by both sensors across Africa in a period completely outside of that used to determine the gridded ratio product – in this case August 2007. The subsetting procedure for the MODIS and SEVIRI fire detections in August 2007 was identical to that used to create the training dataset in 2004/05. Hereafter the concurrent and collocated fire pixels detected by SEVIRI and MODIS in August 2007 is referred to as the “validation dataset.” For each MODIS overpass concurrent with a SEVIRI scan, the number of fire pixels and FRP detected by SEVIRI in each 5° grid cell were summed and divided by the spatially explicit monthly ratios of ϕ_{count} and ϕ_{FRP} stored in the August 2004 grid product. Subsequent comparisons between the adjusted SEVIRI and the measured MODIS values in August 2007 were performed on a per overpass basis (i.e., spatially integrated basis) and on a per grid cell basis.

As a last step, an evaluation was conducted to assess the utility of the 5° grid-cell ratios when applied at 1° and 0.25° grid cell resolution. As described above, for each MODIS overpass concurrent with a SEVIRI scan, the number of fire pixels and FRP measured by SEVIRI in each 1° , or 0.25° , grid cell were summed, however in this case the spatially explicit monthly ratios ϕ_{count} and ϕ_{FRP} were applied depending upon which 5° grid cell the 1° or 0.25° grid cell resided. The adjusted SEVIRI data are, in theory, representative of what MODIS would have recorded had it viewed the full grid cell at the time of the SEVIRI observation, and these ‘simulated MODIS’ results were compared to the actual MODIS observations in both a spatially integrated and a spatially explicit basis.



4.2.3 Analysis of Ecosystem-Specific Biases

In this study component, the ratio of fire detections between SEVIRI and MODIS was studied with a view to an analysis of any bias that resulted from fires burning in different landcover types. As an example, it might be possible that SEVIRI detects a greater proportion of the MODIS-detected fires in grasslands than in forests due to the fires in forests being dominated by lower FRP events. For this study, fire detections from the KCL SEVIRI FRP product for the time period February 2004 to January 2005 were grouped according to the land cover type classification of the Global Land Cover (GLC) 2000 product (Mayaux *et al.*, 2004). MODIS fire detections from the corresponding MOD14 and MYD14 datasets were used for the comparison datasets. The relative frequency of fire occurrence in the various land cover classes was analyzed in order to find out if the detection algorithm or the pixel resolution of the SEVIRI data was leading to ecosystem specific biases.

4.2.4 Effects of Viewing Geometry

As noted above, the SEVIRI pixel size increases with distance from the sub-satellite point. This will lead to larger FRP values required to detect a fire (and also the ability to record larger FRP values before the pixel reaches saturation). The impact will be masked to some degree by the fact that different landcover classes will likely be characterised by different FRP characteristics (see above), and that landcover is not uniform as you move away from the sub-satellite point. The most extreme effects of viewing geometry related issues will be seen towards the edge of the scan, and this issue was therefore investigated via an analysis to determine whether the SEVIRI FRP/MODIS FRP ratio is lower over such areas (e.g. Madagascar and South America) than at regions closer to the sub-satellite point.

4.2.5 Effects of Saturation

Saturation of the SEVIRI pixels (nominally for brightness temperatures above 335 K) will not impact on the ability of the FRP algorithm to detect fires, but it will lead to an underestimation of the true fire radiative power. The impact of this was gauged by firstly determining the typical degree of saturation seen in standard SEVIRI level 1.5 data, and secondly by exploiting data from the SEVIRI 'special operations' mode experiment whereby the Meteosat-8 SEVIRI was operated in the low-gain setting. In this mode the sensor was able to record without the effects of sensor saturation, and the resulting 'true' FRP record was compared to that in which the FRP of pixels whose MIR brightness temperature was above the normal 335 K maximum was set to what it would have been had saturation in fact occurred at that temperature.

4.2.6 Effects of SEVIRI sensor characteristics and Level 1.0 to 1.5 pre-processing operations

The methodology adopted was two fold, firstly a direct comparison of SEVIRI level 1.0 and level 1.5 data of large fires, in order to assess the impact of the level 1.0 to 1.5 pre-processing procedures. Secondly, simulation of the SEVIRI observation process, using modelled fires and background conditions taken from the aforementioned BIRD HSRS imagery (in order to obtain realistic measures of ambient background brightness temperature variability around fires). The modelling including simulation of the SEVIRI point spread function (PSF) and the impact of the Finite Impulse Response (FIR) filter, which is applied to the recorded signals onboard the MSG satellite. The impact of the PSF and FIR filter are present even within Level 1.0 data, but the level 1.5 data have additional features induced via the spatial regridding and interpolation algorithms used in the EUMETSAT data processing chain

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(algorithms are fully detailed in the Image Processing Facility Algorithm Documentation; EUMETSAT, 2003).

4.3 LandSAF Product Validations

The key purpose here was to determine whether the Land SAF FRP product had similar accuracy characteristics to the KCL FRP product, which had formed the dataset used for the majority of the other accuracy evaluation tests.

4.3.1 Comparison to KCL product

This work examined the errors of omission and commission of the LandSAF FRP product with respect to the KCL FRP product, only over Africa since the KCL FRP product is only available for this continent. Data from 1 – 5 August 2007 (415 separate SEVIRI imaging slots) from both processing chains were compared over the Land SAF southern Africa region, with errors of omission, commission and per-fire FRP levels of agreement quantified. This allowed determination of whether the Land SAF products have the same or similar accuracies as the original KCL FRP product. The August 2007 Land SAF FRP product dataset showed insufficient fire detections in the north Africa region to warrant a detailed comparison, and data from a different period (e.g. February) should be obtained for this purpose during any future work.

4.3.2 Comparison to MODIS

Here the errors of omission, commission and per-fire FRP levels of agreement were quantified for the Land SAF FRP product, using as the comparison dataset the MOD14/MYD14 MODIS data. The methodology used was that previously adopted for the same analysis undertaken for the KCL FRP product, outlined in Section 4.2.1. The areas covered by this analysis were the southern African and South American Land SAF regions.

4.4 Validation Based on Impact Studies

4.4.1 Impacts of Temporal Resolution

In order to assess the impact of representing or neglecting the temporal variability of fire emission on time scales of hours and days, model simulations of atmospheric carbon dioxide concentrations (CO₂) using a preliminary version of the GEMS CO₂ model were carried out. Atmospheric CO₂ has been selected for the study because it has a long atmospheric lifetime and does not possess atmospheric sources and sinks. Therefore, it can be regarded as a passive tracer with a long lifetime, and its fields display the interactions of the different emission data with the atmospheric transport most clearly. Even though the variations of the CO₂ field induced by fire emissions appear relatively small, they are significant for the source/sink inversions, which are the ultimate goal of atmospheric CO₂ monitoring.

The GEMS CO₂ model is a global atmospheric transport model which predicts 3D global distributions of CO₂. In the current setup of the model, CO₂ is treated as passive tracer and transport by advection, turbulence and convection are resolved (see also section 3.6.2). The current GEMS system (Hollingsworth *et al.* 2008) uses fire emissions from the GFEDv2 inventory (van der Werf *et al.* 2006) with 8 day time resolution (see Section 3.6.1).



Atmospheric CO₂ fields modelled with these emissions are compared to fields modelled with emissions with 1 hour and 1 day time resolution.

The CO₂ emission data with different time resolutions were created by modulating the GFEDv2 8 daily emissions with the higher frequency temporal patterns observed by SEVIRI. Thus the impact of the temporal resolutions is separated from the one due to different total emission amounts. The following steps are performed to make consistent emissions with 8d, 1d, and 1h resolution:

1. convert GFEDv2_8days dimensions to [kg/m²/s]
2. obtain gridded (1°×1°) SEVIRI FRP data set corrected for partial cloud cover, atmospheric transmission, and missed small fires. This product has been generated by KCL.
3. fill FRP data gaps
 - a. missing 1 hour frames replaced with previous frames
 - b. missing grid cell values (-1) replaced with zero
4. average FRP over 8 day periods of GFEDv2_8days
5. add 1 W to eliminate division by zero errors
6. compute conversion factor = GFEDv2 emission / SEVIRI FRP, for each 8 day period and 1°×1° pixel over Africa
7. compute SEVIRI emission = SEVIRI FRP times conversion factor, for each 1 hour and 1°×1° pixel over Africa
8. pad with GFEDv2_8days for global coverage
9. average over 1 day and 8 days
10. convert 8. and 9. to GRIB with 1°×1° grid
11. convert 10. to GRIB with reduced Gaussian resolution T159


Four model runs have been performed, based on the different fire emission input data sets. The simulations are not constraint by any CO₂ observations. Key properties of the model setup are listed in Table 4.1.

Table 4.1: CO₂ model run setup

modelled period	2 February – 24 December 2004			
horizontal resolution	T159 (~ 125 km)			
number of vertical levels	60			
meteorology	nudged to operational analysis at 00 and 12 UTC			
Fire emission level	Lowest model level			
fire emission time resolution	no fires	8 days (8d)	1 day (1d)	1 hour (1h)

4.4.2 Impact of FRP versus Hot Spot Detection

Mikhail Sofiev at FMI has kindly given FREEVAL access to his analyses of the PM_{2.5} fire emission fields generated with the FMI Fire Assimilation System (FAS) from MODIS TA

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and FRP observations and of the SILAM dispersion model forecasts of PM_{2.5} based on the FAS emissions, see section 3.6.3.

One line of analysis compares the emission fields obtained from the two MODIS products and averaged over several months. Since both are obtained with empirical emission factors, the comparison is mostly sensitive to the different geographical distributions of fire emissions obtained by using either a qualitative hot spot product, i.e. TA, or the quantitative FRP information.


The second line of analysis compares modelled atmospheric PM_{2.5} fields, based on the two different fire observation products, with satellite-based and in-situ observations of the actual atmospheric aerosol fields. Thus an end-to-end assessment of the two approaches can be made.

4.4.3 Impact on Estimating Fire Emissions

The quality of SEVIRI FRP-derived fire emissions was assessed by comparison to the published estimates contained in the Global Fire Emissions Database (GFED) version 2 (van der Werf *et al.* 2006). Because of the spatially limited coverage of the SEVIRI retrievals, the comparison is restricted to the African continent. For the analysis, the continent is subdivided into two study regions, namely Africa north of the equator and Africa south of the equator. The analysis covers the period February 2004 to January 2005 and uses monthly estimates of carbon emissions. The focus of the comparison is on how well SEVIRI FRP derived carbon emissions for the two sub-regions agree with the GFED estimates in terms of seasonal pattern and total amounts.

The GFED inventory for years after 2001 is based on MODIS active fire detections which were scaled to a limited number of MODIS burned area observations and then multiplied by available fuel loads and combustion efficiencies derived from the CASA vegetation model. While MODIS has a higher likelihood of fire detection in an individual scene compared to SEVIRI, there are far less scenes available per day and these do not capture the time window of maximum daily fire activity (the two daytime overpasses of MODIS Aqua and MODIS Terra occur at 10:30 and 14:30 local time, respectively). As a consequence SEVIRI actually detects a larger absolute number of fires per day than MODIS and one has to rely on the scaling procedure for MODIS to provide a complete estimate of fire affected area and burned material. Therefore, the comparison of SEVIRI FRP to GFED emissions should be regarded as a comparison between two independent data sets rather than a validation using a reference data set. Nevertheless, this comparison is important, because GFED has become a de-facto standard in atmospheric composition modelling.

Another, more qualitative validation of the seasonality of emissions derived from SEVIRI FRP uses MOPITT CO profiles for comparison. The analysis covers the same period as the analysis mentioned above (February 2004 to January 2005). For the analysis, monthly variations in SEVIRI FRP in southern hemispheric Africa are directly compared to mean monthly MOPITT CO profiles for the same region. CO is a tracer for biomass burning and the satellite-derived CO profiles provide an estimate of the seasonality and the amount of burning. Because of being different quantities, the direct comparison of FRP with measured CO profiles provides no quantitative comparison. However, because estimated CO emissions are considered to be largely proportional to the FRP (assuming that at least on a regional scale fires always represent a mix between flaming and smouldering conditions with roughly constant proportion), the comparison provides qualitative information on whether the seasonal pattern of FRP-derived CO emissions will match with observations.

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4.4.4 End-to-end Use (Greek Fires Case Study)

In late August 2007, huge fires burnt in Greece. The FRP derived emissions and the simulated and observed plumes of these fires were used to test and demonstrate the feasibility and potential of fire plume modelling and, ultimately, forecasting by combining SEVIRI FRP with the GEMS system for aerosol monitoring.

The current version of the global aerosol model developed in GEMS (Morcrette *et al.*, 2008) is driven with the GFEDv2 inventory. For this study, aerosol emissions derived from the SEVIRI FRP product by KCL have been superimposed on this data set and the modelled smoke plumes are compared to MODIS observations. In contrast to the tests on the impact of temporal resolution (see section 4.4.1) where only the time information of SEVIRI was used, here the FRP product was used quantitatively with its correction to account for small fires. The simulation also covers a smoke plume that is transported from Algeria to Italy and is compared to ground-based AERONET observations at Lecce University. The individual data processing steps were:

1. convert SEVIRI 3.9 μm channel to FRP [MW]
2. grid FRP to 0.1x0.1 deg grid
3. average over 1 hour
4. correct for fires below detection limit (no correction for partial cloud cover was needed, since Greece was cloud-free at the time of the fires)
5. convert
 - to Dry Matter combustion rate [kg/s] (factor 0.368 kg/s/MW)
 - to BC, OM, and SO₄ emission rate [kg/s] with emission factors based on a combination of Andreae and Merlet (2001) and Ichoku and Kaufman (2005)
6. interpolate to the grid cells corresponding to model resolution T799 (triangular truncation at wave number 799), which is the resolution of the operational deterministic ECMWF weather forecast and also representative for current regional air quality monitoring systems. (~25km)
7. run the GEMS aerosol model with fire emissions in lowest layer for 1 August – 6 September 2004. Compared to the standard GEMS model the resolution has been increased.



5 Validation Results

5.1 Results of the Algorithm Performance Analysis

Figure 5.1 shows the impact of assumption (i), the fourth order power law approximation to Planck's Radiation Law, by comparing the FRP derived via the MIR radiance method (FRP_{MIR}) to that derived via the Stefan-Boltzmann Law (FRP_{TRUE}), in the case that the fire is fully resolved by the sensor (i.e. there is no 'background' non-fire component to the signal). The difference between these two measures, denoted by their ratio (R), is due only to the uncertainty introduced by the Planck Function approximation, and is shown here to be relatively constant (i.e. R constrained between 0.88 and 1.12) over a significant part of the emitter temperature range considered (i.e. $> \sim 665$ K and < 1365 K).

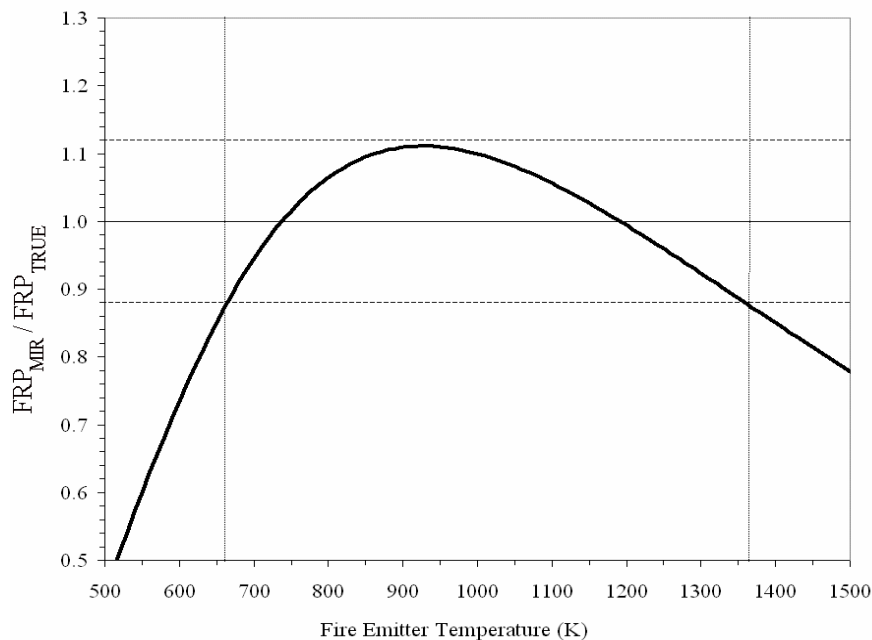


Figure 5.1: Ratio (R) between the Fire Radiative Power estimate derived from MIR radiance method (FRP_{MIR}), and the true FRP derived from the Stefan-Boltzmann Law (FRP_{TRUE}). Calculations here assume pixels fully filled by fire. Horizontal dashed lines denote the limits where FRP_{MIR} values are within a factor of 0.88 and 1.12 of FRP_{TRUE} , whilst vertical lines denote the corresponding temperature range (665 - 1365 K).

An example of the emitter temperature distribution retrieved over a real wildfire is shown in Figure 5.2, indicating that in excess of 95% of the fire pixels have emitter temperatures in the 665 – 1365 K range, where R is constrained between 0.88 to 1.12. Thus the underlying FRP uncertainty induced by use of the MIR radiance method is governed by this uncertainty, but the advantage is that by using this method we do not have to resolve the fire temperature distribution and can thus use the method on highly sub-pixel sized events, providing of course that we can assume that their temperatures lie within the above range. This range is expected to cover the vast majority of fire events, and is broadly consistent with that specified in, for example, Ohlemiller (1995) and Riggan *et al.*, (2004) for actively burning fires and in the assumptions made during derivation of the MODIS fire detection and fire characterisation approach (Kaufman *et al.*, 1998).

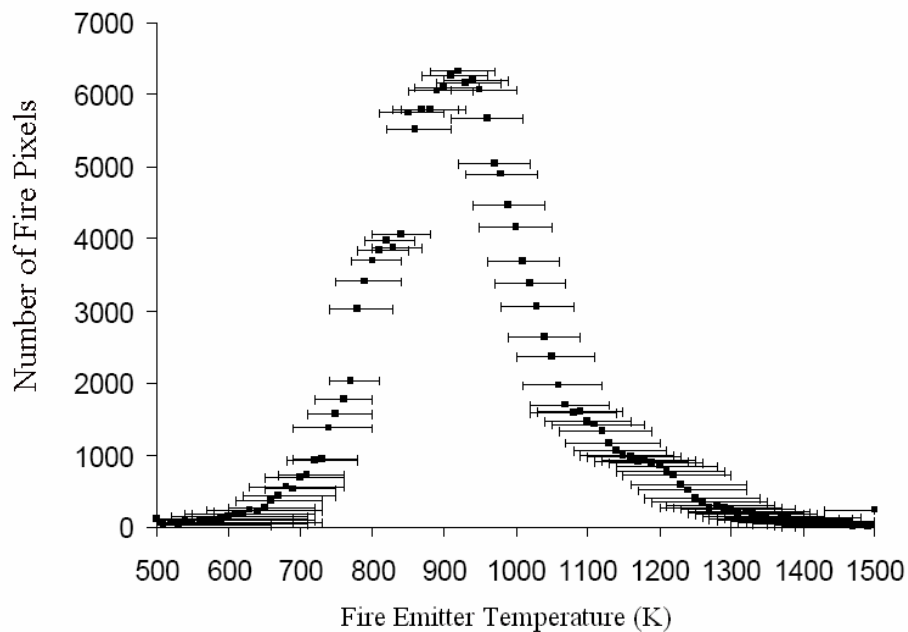


Figure 5.2: Fire emitter temperatures retrieved from analysis of Airborne Visible Infrared Imaging Spectrometer (AVIRIS) hyperspectral data of the 2003 Simi Fire in Southern California, USA by Dennison et al. (2006). The method used a spectral library of emitted hyperspectral radiance endmembers corresponding to a fire temperature range of 500-1500 K, along with reflected solar radiance endmembers, both based on simulations using the MODTRAN radiative transfer model. These endmembers were used to determine the true subpixel fire emitter temperature within each active fire pixel identified with AVIRIS. Error bars indicate the median range of emitter temperatures modelled within 5% of the RMSE for the indicated emitter temperature.

At the scale of satellite observations, e.g. the nominal 4.8 x 4.8 km pixel sizes supplied by SEVIRI, real fires consist of a wide mixture of temperature components within each ‘fire pixel’ rather than single temperature emitters – as can be seen from the temperature distributions seen in the 50 m spatial resolution AVIRIS data shown above. As a result, the ratio (R) of FRP_{MIR}/FRP_{TRUE} for the mixed temperature fires contained in such large pixels may likely move away from the extremes shown in

Figure 5.1 due to FRP underestimation inherent towards the lower (< 750 K) and upper (> 1200 K) fire temperature limits being counteracted by FRP overestimation from the mid-range (750 – 1200 K) emitters. However, since the actual fire temperature distribution within a SEVIRI pixel is by definition unknown, the theoretical accuracy limits of 0.88 to 1.12 are maintained. Note that in the case of Figure 5.2, most fire pixels have temperatures between 800 and 1050 K, and in this range FRP estimated by the MIR radiance method positively biased ($R > 1.0$), but when the full fire temperature distribution is considered the overestimation will be by a factor less than the maximum of 1.12.

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The assumptions (ii) used to derive Equation 1.6 from Equation 1.5 were assessed for their impact on FRP retrieval accuracy via the aforementioned radiative transfer modelling of sub-pixel sized active fire observations. They were found to introduce no error significantly above the $\pm 12\%$ introduced by the fourth order approximation to Planck's Radiation Law (whose magnitude was already demonstrated in

Figure 5.1.

Assumptions (iii) and (iv) regard uncertainties in the atmospheric parameter of the FRP equation (τ_{MIR} , the MIR atmospheric transmission) and in $L_{b,MIR}$ (the background radiance of the fire pixel, estimated from the background window pixels). Combining Equation 1.1 and an error of $\pm L_{berror,MIR}$ in the assumed background radiance we state:

$$FRP_{MIR} = \frac{1}{\tau_{MIR}} \left(\frac{\sigma}{a} \right) (L_{MIR} - L_{b,MIR}) \pm \frac{1}{\tau_{MIR}} \left(\frac{\sigma}{a} \right) L_{berror,MIR} \quad [Wm^{-2}]$$

Equation 9

The first term on the rhs of Equation 9 represents the fire FRP, which has the potential *multiplicative* error sources due to the uncertainties related to the power law approximation (a factor of 0.88 to 1.12 as shown in Figure 5.1 and the assumed atmospheric transmission, which can act either in the same direction as the error introduced by the power law approximation (and thus magnify it) or can act in the opposite direction (and thus counteract it). The second term on the rhs represents the error in FRP introduced by the inability to estimate $L_{b,MIR}$ perfectly from the background window pixels, and this is an *additive* error source. As can be seen from Equation 9, this value is multiplied by the inverse of the assumed atmospheric transmission. Only in cases where the fires actual FRP (term 1 of Equation 9) is relatively small but the uncertainty in the background (term 2 of Equation 9) is relatively large will the error in background characterisation have a major impact. Conversely however, the magnitude of the multiplicative error on term 1 of Equation 9 will grow with the fires FRP, and so it can remain significant for all classes of fire FRP.

The magnitude of these error sources is illustrated using a modelling exercise based on sets of true fire parameters (effective fire temperature and sub-pixel proportion; which together determine the fires FRP), the radiative transfer modelling to simulate SEVIRI spectral radiance observations of the 'fire' and 'background window' pixels, and the equations used to derive an estimate of the fire FRP from these observations. This system was perturbed by parameter alterations, notably to the assumed values of MIR atmospheric transmission and differences between the background pixel radiance and the true background radiance of the fire pixel itself (i.e. $L_{berror,MIR}$ is non-zero in Equation 9).

Results for three different effective fire emitter temperatures (650, 850 and 1000 K) and considering only a range of errors in the background characterisation, and not in assumed τ_{MIR} , are shown in Figure 5.3. For each fire temperature, the results converge at the $L_{berror,MIR} = 0$ point, with the magnitude of the error simply being that induced by the fourth order power law approximation to the Planck's Radiation Law at that temperature (assumption (i)). As $L_{berror,MIR}$ increases away from zero, the additive error component shown in Equation 9 becomes non-zero and the same $L_{berror,MIR}$ perturbation induces a larger percentage error in FRP for low FRP (i.e. lower temperature and/or lower sub-pixel fractional area) fires than for large FRP fires. Giglio and Kendall (2001) in a somewhat similar exercise considered



perturbations in the background radiance of $\pm 0.02 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$, but here we consider perturbations up to of $\pm 0.1 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ since this level of background window radiance variability is seen in the SEVIRI FRP data, though values around $\pm 0.03 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ are more common. Only in situations where the fires are, in any case, very unlikely to be detectable do $L_{\text{error},\text{MIR}}$, perturbations of $\pm 0.03 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ have a strong influence on FRP_{MIR} . For fires having FRPs greater than the minimum values confidently detectable by SEVIRI, perturbations of this sort add significantly less than 10% error to that already existing from the Planck function approximation, irrespective of the actual fire temperature or sub-pixel size.

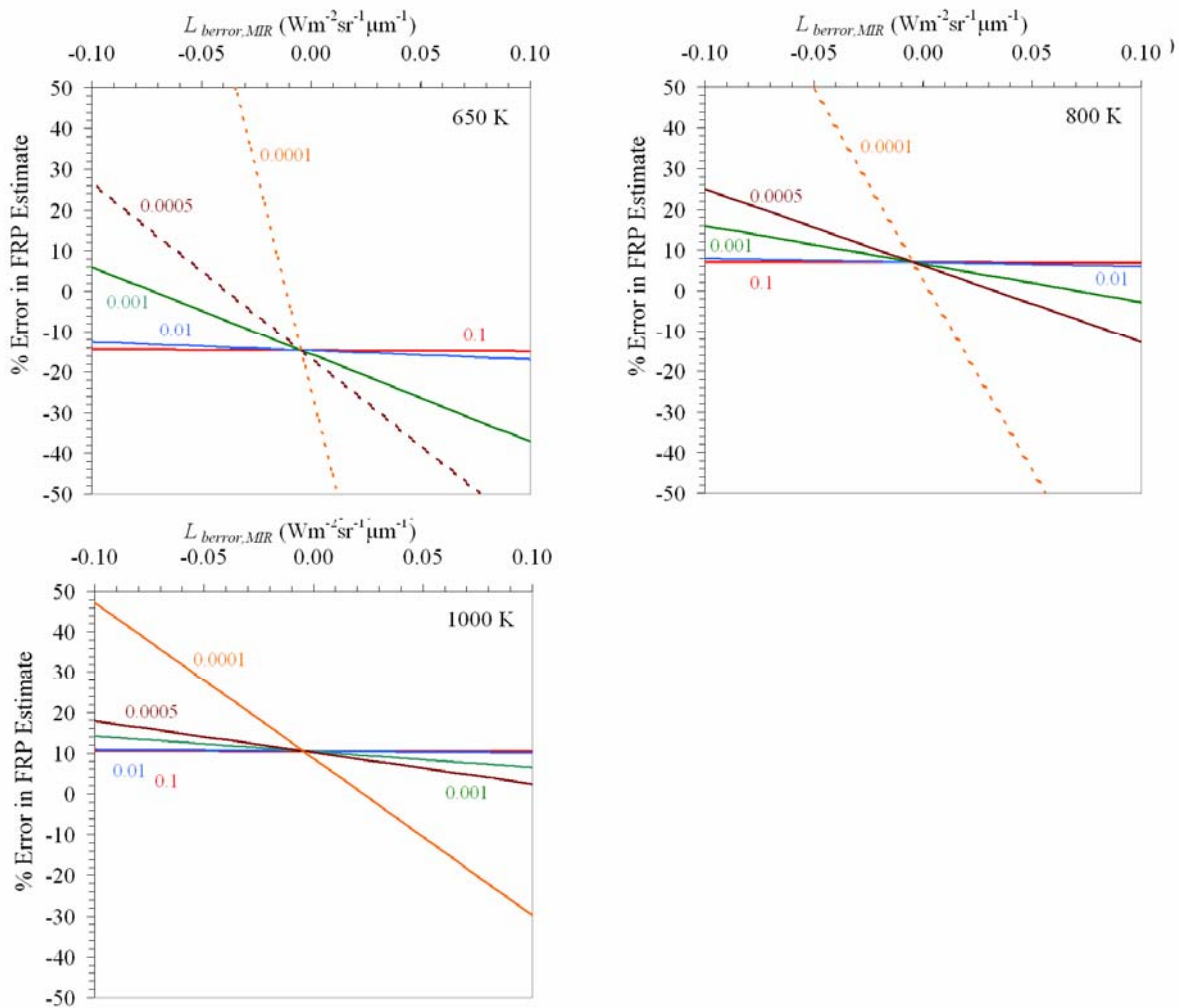


Figure 5.3: Departure of estimated FRP from true FRP for blackbody fires of temperature 650, 800 and 1000 K and fractional areas 0.1 to 0.0001 (denoted by the labels) as a function of the level of disagreement between the assumed background radiance signal and its true value (i.e. the value expressed by $L_{\text{error},\text{MIR}}$ in Equation 9). Values of other fixed parameters such as downwelling and upwelling atmospheric radiances and the atmospheric transmissivity have the values taken previously in the similar modelling study conducted by Wooster et al. (2005). Results are calculated here using the full parameterisation of Equation 1.5 and Equation 1.1 to take into account all error sources. Dotted lines indicate situations where the fire is too cool and/or small to be robustly detectable (i.e. MIR brightness temperature is raised by less than 6 K over that of surrounding non-fire pixels). At $L_{\text{error},\text{MIR}} = 0$ results for each fire temperature converge, confirming the



insensitivity of the error to fire fractional area under this condition and thus the appropriateness of the assumptions made in deriving Equation 1.6 from Equation 1.5.

Figure 5.4 indicates the additional sensitivity of the FRP retrievals to the estimate of MIR atmospheric transmission, and how this interacts with $L_{\text{berror},\text{MIR}}$ assessed in the previous Figure. Using an 800 K fire as an example, the effect of an error of $\pm 15\%$ in the assumed value of τ_{MIR} is assessed. Assuming observations at the sub-satellite point, this equates approximately to an assumed minimum atmospheric transmission in the MIR spectral band ($\tau_{\text{MIR}} = 0.61$) when the transmission is actually at a maximum ($\tau_{\text{MIR}} = 0.7$), and *vice versa*. For such a fire, Figure 5.4b confirms that perfect knowledge of both τ_{MIR} and $L_{\text{b},\text{MIR}}$ allows the maximum error in FRP to remain lower than $+10\%$ for all fire fractional areas and thus all FRP values. A 15% overestimate in τ_{MIR} results in an FRP underestimate of $\sim 10\%$ (Figure 5.4a), whilst a 15% underestimate in τ_{MIR} increases the magnitude of the FRP overestimate derived via the MIR radiance method, to $\sim 25\%$ for all detectable fires Figure 5.4c).

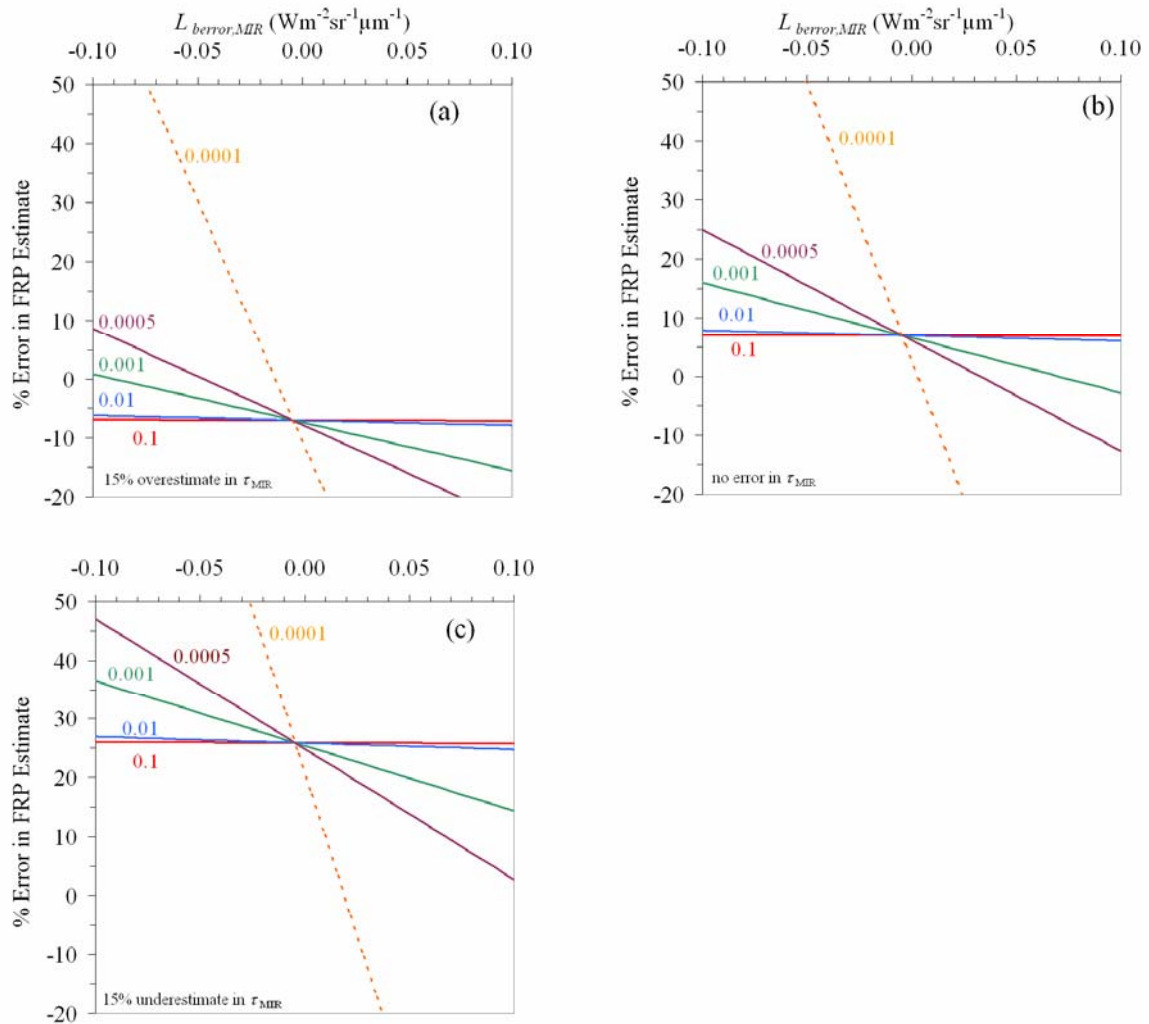


Figure 5.4: As Figure 5.3. but now expressing the departure of the estimated FRP from the true FRP for blackbody fires of temperature 800 K and fractional areas 0.1 to 0.0001 (denoted by the labels) as a function of the level of disagreement between the assumed background radiance signal and its true value (i.e. the value expressed by $L_{\text{berror},\text{MIR}}$ in Equation 9) and for different errors in the assumed MIR atmospheric transmission. Values of other fixed parameters such as downwelling and upwelling atmospheric radiances and the

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atmospheric transmissivity have the values taken previously in the similar modelling study conducted by Wooster *et al.* (2005). A 15% overestimate in assumed MIR atmospheric transmission is assumed in (a), perfect knowledge in (b), and a 15% underestimate in (c). Dotted lines indicate situations where the fire has too low and FRP to be robustly detectable (i.e. the MIR brightness temperature is raised by less than 6 K over that of surrounding non-fire pixels). At $L_{\text{error}, \text{MIR}} = 0$ results for each fire temperature converge, indicating the insensitivity of the error to fire fractional area under this condition.

In terms of reported error for each FRP estimate, currently what is provided in the Land SAF FRP product is a measure of the additive error component (term 2 of Equation 9), calculated as the following [though from the ATBD it may not, apparently, currently be adjusted for the atmospheric transmission]:

$$FRP_{\text{error_additive}} = \pm \frac{A_s}{\tau_{\text{assumed}, \text{MIR}}} \left(\frac{\sigma}{a} \right) \sigma_{\tilde{I}_b} \quad [W]$$

Equation 10

where $\tau_{\text{assumed}, \text{MIR}}$ is the assumed MIR atmospheric transmission, A_s is the pixel sample area, and $\sigma_{\tilde{I}_b}$ is the estimate of uncertainty in the background radiance of the fire pixel, estimated from the background window standard deviation.

Additional uncertainty comes from the multiplicative error term, which can be calculated from:

$$FRP_{\text{error_multiplicative}} = \left(FRP_{\text{measured}} \pm FRP_{\text{error_additive}} \right) \left(\frac{1}{R} \frac{\tau_{\text{assumed}, \text{MIR}}}{\tau_{\text{actual}, \text{MIR}}} - 1 \right) \quad [W]$$

Equation 11

Where FRP_{measured} is the reported FRP in the product, $FRP_{\text{error_additive}}$ is the additive error calculated from Equation 10, R is the ratio uncertainty resulting from the fourth order approximation to the Planck function shown in Figure 5.1 and $\tau_{\text{assumed}, \text{MIR}}$ and $\tau_{\text{actual}, \text{MIR}}$ are the assumed and actual MIR atmospheric transmission respectively. In most cases the actual values of R and $\tau_{\text{actual}, \text{MIR}}$ will be unknown, though their potential range is known and reported in the ATBD (Govaerts *et al.*, 2007). Hence, using these values the appropriate range of potential multiplicative error can also be calculated for any FRP estimate reported in the product. The extreme values of the sum of the additive and multiplicative error components can then be taken as the estimate of overall uncertainty on FRP, which can be used to place uncertainty bounds on FRP_{measured} .

A mean background window radiance standard deviation of $\sim 0.03 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ was determined from the Land SAF FRP products of southern Africa, with maximum values three times this. Independent testing of the levels of background window variability found at non-fire pixels (where the true ‘background’ temperature of the central pixel in the background window pixel grid is known) indicated that the standard deviation of background window radiances was mostly larger than the actual radiance difference between the central pixel of the background window and the mean radiance of the surrounding pixels, with Figure 5.5 showing an example of this at two different landcover classes (grassland and forest). This was found true for background windows of 5×5 , 7×7 or 10×10 pixels in size. Therefore, the background window radiance standard deviation measure currently used to estimate the additive error component of the FRP uncertainty budget is an appropriate, if perhaps somewhat conservative, measure.

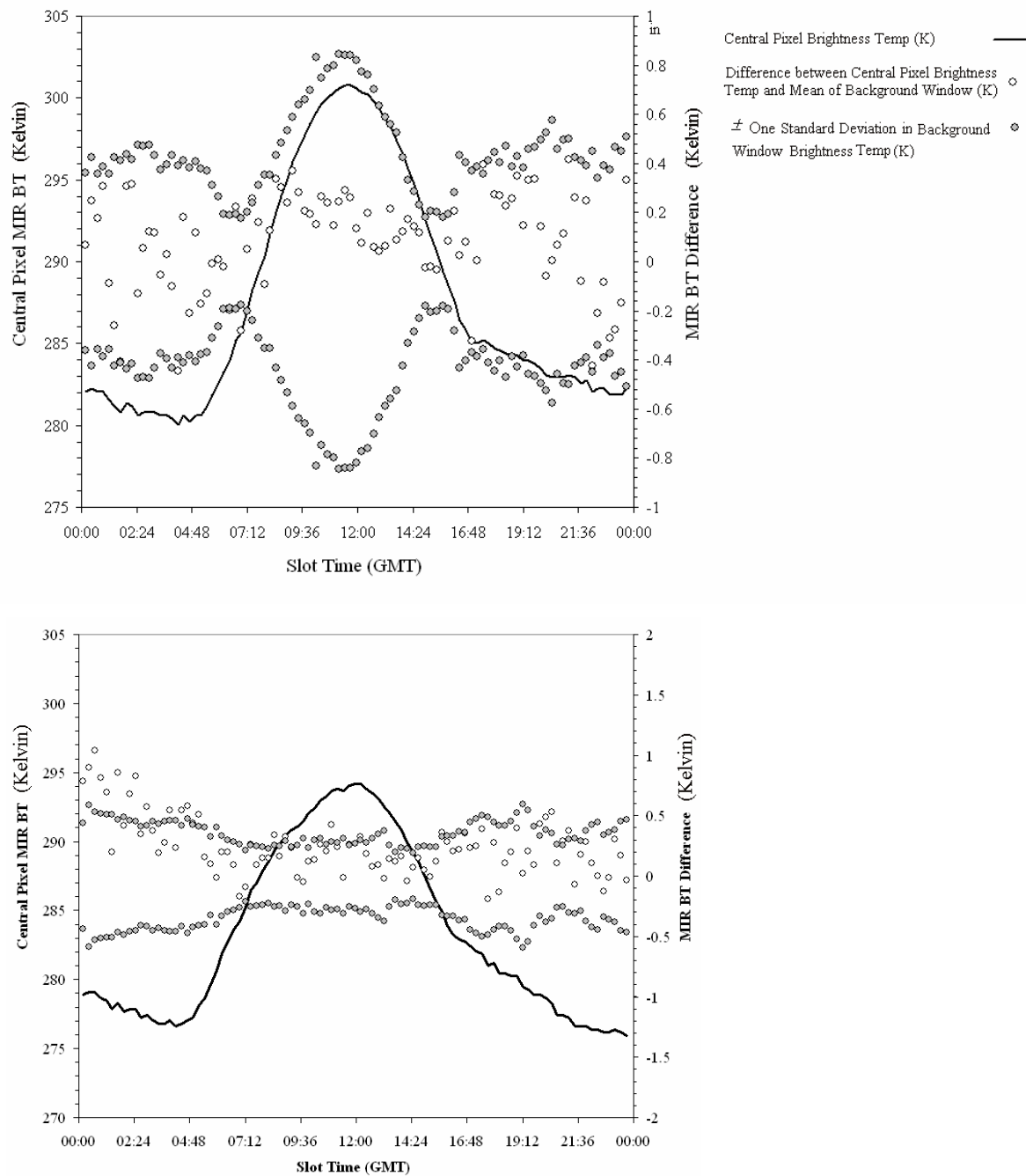


Figure 5.5: The central pixel brightness temperature of a 5×5 pixel window plotted over the full 24 hr cycle for a southern Africa closed grassland site (top) and a deciduous forest site (bottom), as identified by the GLC2000 landcover database. Also shown are the difference between this pixels brightness temperature and the mean of the remaining background window pixels, and \pm one standard deviation of the background window pixels. This latter figure is seen to mostly be larger than the actual difference between the central pixel and the mean of the background window pixels.

The total FRP uncertainty, estimated as the maximum range of the sum of the additive and multiplicative error components discussed above and presented in Equation 10 and Equation 11, was estimated for the full range of per-pixel FRP potentially measurable from SEVIRI. The calculations assumed both a ‘worst case’ (Case 1) additive error budget scenario where σ_{I_b} is equivalent to the aforementioned maximum background variation, and the ‘mean’ case

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(Case 2) where $\sigma_{\tilde{I}_b}$ is equivalent to the aforementioned mean variation. In both cases it was assumed that little information was available to estimate the true atmospheric transmission in the MIR spectral band, so $\tau_{assumed, MIR}$ was taken as the mid-range value of 0.66 calculated for a SEVIRI view zenith angle of 30 degrees and a water vapour content of 30 kg/m² [and thus is essentially a ‘default’ value in the middle of the actual potential range] and values of $\tau_{actual, MIR}$ were taken up to the possible extremes of 0.61 to 0.7 for that view zenith angle. In this way the multiplicative error budget represented here is the maximum uncertainty likely to be present, and could be reduced should it be possible to provide values of $\tau_{assumed, MIR}$ that are known to be closer to $\tau_{actual, MIR}$ than this (e.g. from modelled atmospheric water vapour distributions across the SEVIRI field of view obtained with a meteorological forecast model).

Figure 5.6 shows the results from the uncertainty model produced with such assumptions. In Case 1 the additive error resulting from the large background radiance uncertainty equates to an FRP uncertainty of 34 MW at the 30 degree VZA (where pixels are 15% larger than at the sub-satellite point), which represents a substantial fraction of the measured FRP for fire pixels not too far above the minimum that are detectable with SEVIRI. (e.g. $FRP_{measured}$ in the 50 – 100 MW range). In Case 2 the additive error resulting from the lower background radiance variability equates to a more manageable FRP uncertainty of 10 MW. In both Cases, it is apparent that the multiplicative error dominates the total uncertainty budget for most of the potential range of measured FRP, and only at the lower end of the potentially measurable FRP scale does the additive error make a major contribution. It should be noted, however, that this is particularly relevant as the majority of detected fires in Africa are characterised by low FRP values.

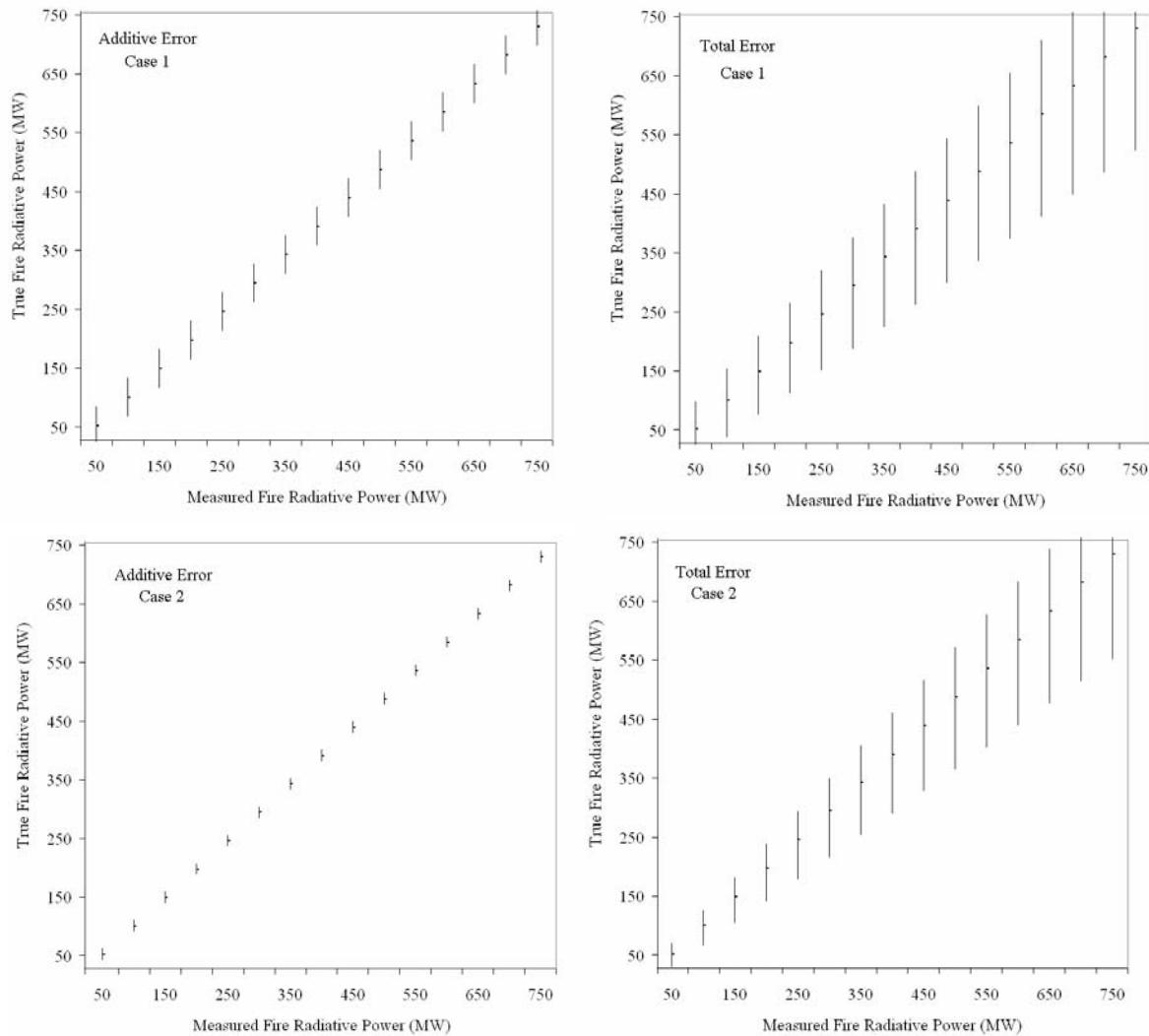


Figure 5.6: The x-axis reports the recorded FRP estimated by SEVIRI, whilst the y-axis reports the potential range of true FRP that could have given rise to that SEVIRI-derived FRP estimate. Results are shown over the 50 – 750 MW range, taking account of the additive error only (at left), and then both the total (additive plus multiplicative) error (at right). Case 1 assumes ‘maximum uncertainty’ errors in the radiance estimate of the fire pixel background (as deduced from the standard deviation of the background window radiances), whereas Case 2 assumes the mean uncertainty in this parameter. The maximum uncertainty in MIR atmospheric transmissivity is assumed in both cases, and both also take into account the full range of uncertainties in the fourth order approximation to the Planck Function (see text for details). In this way the multiplicative error component expressed here is the maximum expected for SEVIRI.

The calculations above assume the maximum uncertainty in atmospheric transmissivity. In all likelihood this will be reduced during the product development, for example by making use of model output for parameterise the atmospheric water vapour content and thus provide an estimate of $\tau_{assumed, MIR}$ that better approximates $\tau_{actual, MIR}$. Where atmospheric transmissivity is known with negligible uncertainty, the error budget reduces to the additive error component from the background window radiance variability, and the uncertainty due to the fourth order power law approximation to the Planck function. Assuming this, and using the relation presented in Equation 11 together with the observed FRP measures and additive error components deduced from 2000 fire pixel observations made across the southern African region on 2 June 2004 at the peak fire time slot (13:12 GMT). Figure 5.7 shows the



distribution of FRP uncertainty. Half of the observations have a total FRP uncertainty less than $\pm 40\%$, and the mean uncertainty is also very close to this (i.e. uncertainties are normally distributed). On average the per-pixel FRP uncertainty due to the additive error component is 30%, and the remaining uncertainty comes from the Planck function approximation. If SEVIRI were to have a higher spatial resolution, the magnitude of the uncertainty for a particular FRP fire would reduce, since the spectral radiance contribution of that fire to the overall pixel radiance would be increased, though a higher spatial resolution system would also be able to detect fires having low FRP so the overall uncertainty distribution may not be significantly affected.

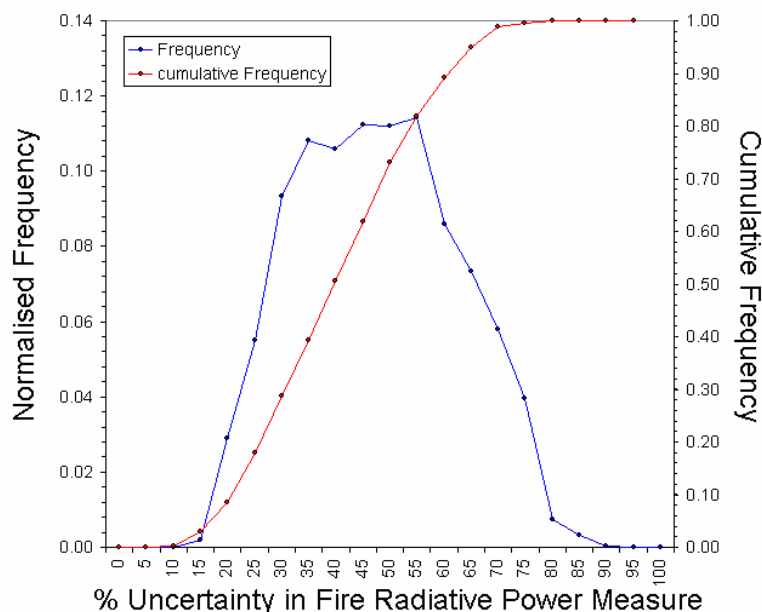


Figure 5.7: % uncertainty in FRP for 2000 observed fire pixels across southern Africa. The MIR atmospheric transmissivity of 0.66 was assumed to be known perfectly, and the additive error component was calculated from the background pixel window standard deviation. The multiplicative error component came from the fourth order power law approximation only.

5.2 Results of the SEVIRI Product Performance Analysis

5.2.1 Per-Fire Comparisons

5.2.1.1 Errors of Omission and Commission

The analysis of errors of omission confirms that, though SEVIRI successfully detects very many fires each month, when MODIS and SEVIRI image the same area at the same time SEVIRI fails to detect many fires that MODIS does detect. Figure 5.8(a and b) demonstrate the effect over Central African Republic, where when using the SEVIRI observations that match to MODIS overpasses, SEVIRI detects only the larger of the MODIS detected fires. However, comparison of Figure 5.8a and 5.6c indicates that when all SEVIRI observations over the course of the 15-day study period are used, the spatio-temporal pattern of the SEVIRI-detected fires is very similar to those detected by MODIS – so most fires detected by MODIS are in fact detected by SEVIRI at some point in their lifetime. Thus by using all SEVIRI observations the spatial pattern and total number of individual fire events observed

over any particular period is reproduced rather well. However, the fact that the signal of many of these fires goes undetected by SEVIRI at the time of the MODIS overpass [Figure 5.8a and b] indicates the likelihood that, at any particular individual SEVIRI time slot, the instrument will only be detecting a fraction of the FRP that MODIS would have detected had it observed the area at the same moment. Thus, the total FRP derived from SEVIRI for a region at any given time will also be low biased when compared to MODIS.

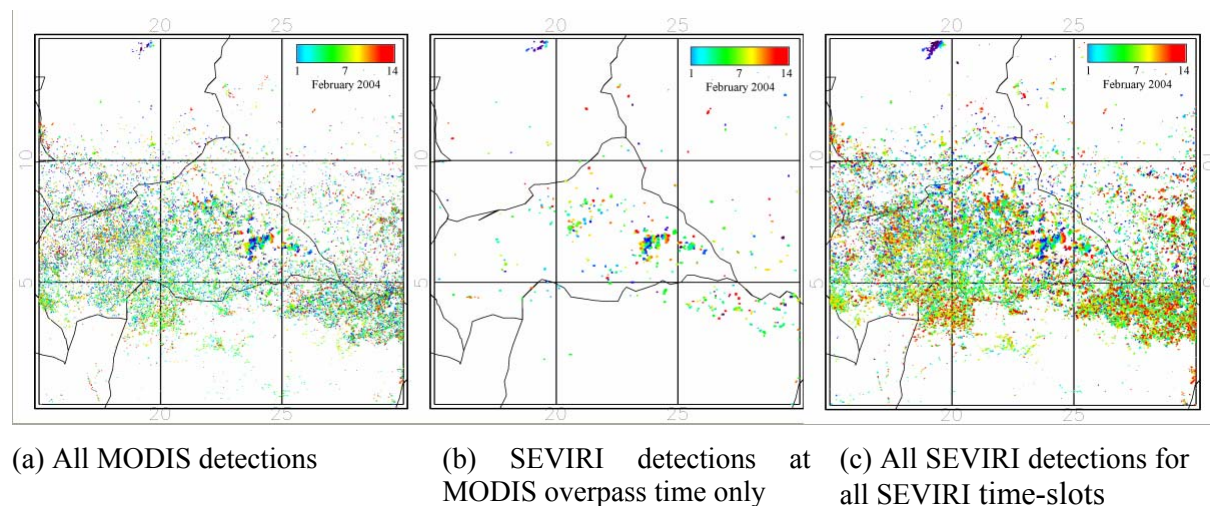


Figure 5.8: Effect of the inability of SEVIRI to detect low FRP fire pixels that MODIS can detect, illustrated by SEVIRI and MODIS fire detections collected over Central African Republic and surroundings in February 1-14 2004. Fire pixel detections are coloured by day of detection. When only using data from the SEVIRI imaging slots that were co-incident with a MODIS overpass, comparison of (b) with (a) confirms that SEVIRI misses a large number of (low FRP) fire pixels. However, it should also be noted that when using all SEVIRI imaging slots, SEVIRI appears to agree well in comparison to MODIS in terms of identifying the spatial distribution fire-affected areas, and in fact can detect a larger number of fires overall. The conclusion is that whilst many fires have an insufficiently high FRP to be detected by SEVIRI if we limit the SEVIRI observations to just those at the MODIS overpass time, most fires appear to become sufficiently large and intense at some point in their lifecycle that they will be successfully detected by SEVIRI.

Full results from the analysis of omission and commission, indicate that in February 2004, 54% of all MODIS-detected fire pixels over Africa (a total of 140,000 pixels) had no corresponding SEVIRI fire pixel. However, it should be remembered when interpreting these results that a large number of these MODIS pixels likely formed clusters such that several MODIS fire pixels correspond to only one ‘missing’ SEVIRI pixel. For May 2004 the equivalent results were 101,000 missed MODIS fire pixels (57%), and for August 198,000 fire pixels (57%). Corresponding errors of commission (false detections) by SEVIRI were rather small, at 6% (February), 8% (May) and 6% (August), a level comparable to the ~ 10% rate quoted for the TRMM active fire product (Giglio *et al.*, 2003a). The FRP of these false detections accounts for 3% (February), 6% (May) and 3% (August) of that months cumulative FRP total for the continent, indicating that the falsely detected fires have typically low FRP values.

In addition to its FRP, each detected fire pixel in the Land SAF and KCL FRP products has a confidence parameter attached, calculated as a function of the fires spectral signal above the background, its spatial location relative to clouds and water bodies, and series of other parameters detailed in Govaerts *et al.*, 2007. The statistical distribution of this fire pixel confidence parameter for the erroneously detected fire pixels identified in the February, May



and August 2004 datasets discussed above is plotted in Figure 5.9 and compared to the confidence parameter of the set of correctly identified fire pixels. The similar degrees of commission error seen in each of the three months is reflected in the similar frequency distribution of the confidence parameter, though May has a distribution peaking towards a slightly lower confidence value, which reflects its slightly higher error of commission. The confidence values of the correct fire detections have a peak correctly shifted towards higher confidence values when compared to that of the false detections. However, it is not the case therefore that all fire pixels below a certain confidence limit can be automatically assumed to be false detections, since Figure 5.9 indicates that even some of the correctly identified fire pixels have confidence values lower than 0.5 for example. Such fire pixels are those most likely to be at the limit of detectability in terms of their spectral radiance signal above the background, and which may be close to regions where false alarms are likely to be increased.

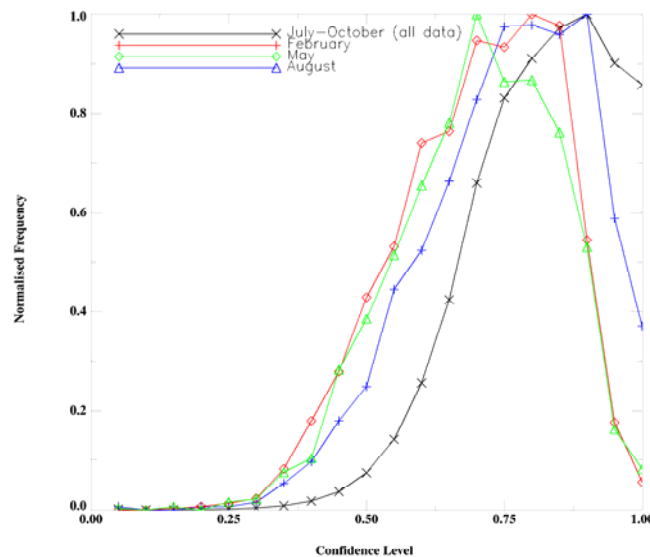


Figure 5.9: Frequency distribution of SEVIRI fire pixel detection confidence for all falsely detected fire pixels in February, May and August 2004, as compared to that of all fire pixels.

In fact, the majority of the false alarm fire pixels still have a confidence value exceeding 0.5, and this is mostly a result of the MIR brightness temperature limits used to define strong confidence and weak confidence fire pixels (Govaerts *et al.*, 2007), and the fact that the detection algorithm is designed only to confirm potential fire pixels as true fire pixels when there is a reasonable level of certainty that this is correct (i.e. to minimize errors of commission as far as possible; which has shown to be the case since levels of commission are < 10% even though low FRP fires at the very limit of detectability are in fact regularly distinguished by the algorithm). A similar effect relating to relatively high confidence values for false alarm fire pixels has been noted in the MODIS fire products (Giglio *et al.*, 2005). Of course, a small fraction of the identified false alarm detections by SEVIRI maybe due to MODIS incorrectly missing a fire. Morisette *et al.* (2005) indicate the strong performance of the MODIS fire detection product (using the version 4 algorithm), but Figure 5.10 illustrates two examples where we have found MODIS fire detection errors occur in comparison with a successful SEVIRI detection. Figure 5.10 (a-b) illustrates a case where SEVIRI detects three fires, whilst for some reason the MODIS MOD14 product only detects one fire. Figure 5.10 (c-d) highlights a further example where a MODIS pixel that clearly does contain an active

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fire is classified as a water pixel by the landcover map used in the MODIS fire detection procedure, and is therefore not passed through to the fire detection algorithm. This may possibly be a seasonal water body that in the dry season is the site of many fires.

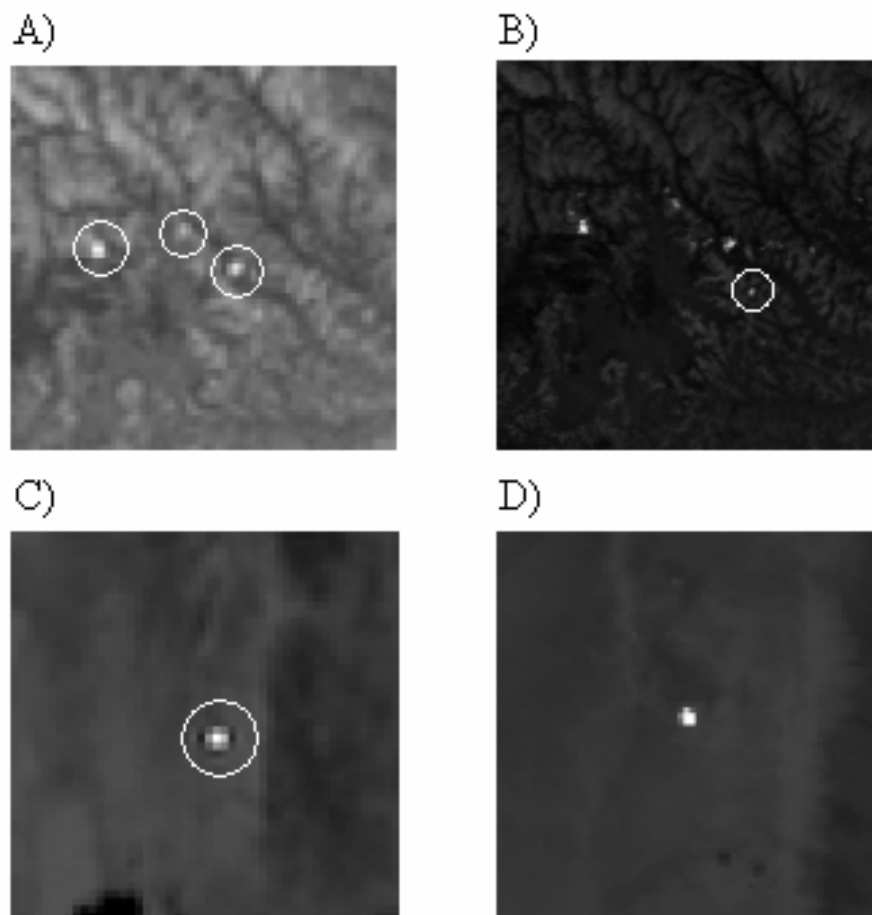


Figure 5.10: Two examples where MODIS fire detection appears less sensitive than that of SEVIRI. (A) and (B) show, respectively, matching SEVIRI and MODIS night-time MIR channel images where fires are visible. White circles indicate the detected fires for each dataset. Of these, MODIS detects only one but SEVIRI all three. (C) and (D) again show, respectively, SEVIRI and MODIS MIR channel imagery which indicate the presence of a fire, which SEVIRI successfully detects. MODIS, however, fails to detect this fire, which appears to be due to the landcover of these pixels being (incorrectly) classed as water in the landcover map used by the MODIS fire detection algorithm. Although these results indicate that some errors of omission do exist in the MOD14 fire detections with respect to SEVIRI, these are likely to be the exception rather than the norm since validation of the MOD 14 product using matching ASTER data indicates strong overall performance in this environment (Morissette et al., 2005).

5.2.1.2 Sensor-to Sensor Per-Fire FRP Comparison

Figure 5.11 presents the results of the per-fire FRP comparison between fires that were successfully detected by SEVIRI and by MODIS, remembering that a fire maybe represented by different numbers of spatially contiguous fire pixels in the data of each sensor (an indeed is very likely to be, due to the sensors differing spatial resolutions). The per-fire FRP data generally show a strong level of agreement, with low bias but significant scatter. The observed scatter can result from a number causes, including:



- i) uncertainty in the ambient background characterization results of each sensor (Wooster *et al.*, 2005);
- ii) the small but potentially significant (≤ 6 minutes) time difference between corresponding MODIS and SEVIRI observations of the same fire, during which time fire characteristics may have changed significantly;
- iii) variation in retrieved FRP related to the sub-pixel location of the fire with respect to the sensor IFOV and point spread function, and the impact of the filtering operations conducted during the production of SEVIRI level 1.5 data;
- iv) the fact that ‘fire pixels’ have to have a significantly higher minimum FRP to be detected by SEVIRI than by MODIS, but more of the overall radiance contribution from a fire maybe contained within a SEVIRI pixel than a MODIS pixel, and so on a case-by-case basis, certain of the individual pixels making up a fire may remain undetected by SEVIRI but detected by MODIS, or visa versa.
- v) the assumption of greybody emission from fires being significantly in error, and the spectrally varying emissivity interacting in such as way with the MIR channel sensor spectral response funcning that differences in retrieved FRP resulted.
- vi) the effects of sensor saturation in some of the detected fire pixels

Figure 5.11 indicates that the level of per-fire FRP agreement is lower for fires with a MODIS-derived FRP exceeding 3000 MW, which correspond to unusually large and/or intensely burning fires that are most likely subject to the effects of SEVIRI MIR detector saturation (Roberts *et al.*, 2005), and which is analysed in Section 5.2.5. Fortunately, the incidence of such fires is rather low, so the effect of SEVIRI pixel saturation is limited when considering all fires made over larger regions, and certainly is much less important than the fact that SEVIRI misses many of the lower FRP fire pixels that MODIS can detect.

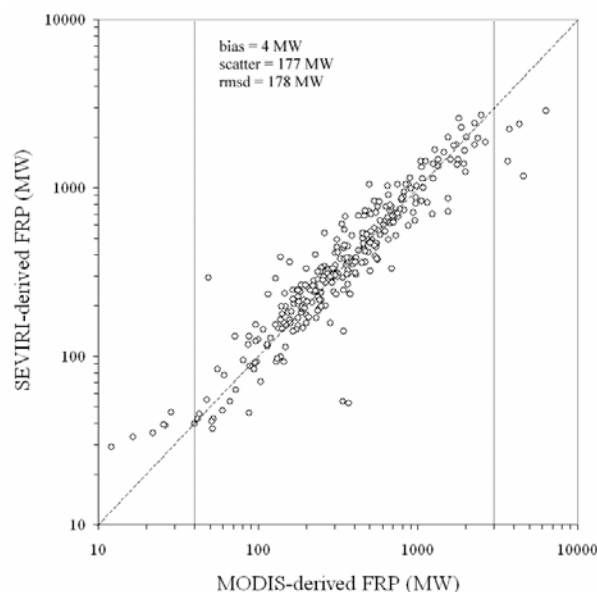


Figure 5.11: A comparison of per-fire FRP derived from SEVIRI and MODIS observations of 289 fires observed near-simultaneously by each sensor in February, May and August 2004. Fires are designated as contiguous clusters of active fire pixels. Correlation between the two datasets is quite strong ($r^2 = 0.62$, p



< 0.0001) but there is clear evidence that SEVIRI overestimates FRP for fires where the MODIS-derived FRP is $< \sim 40$ MW, and underestimates FRP for fires where the MODIS-derived FRP is $> \sim 3000$ MW. Discounting these 17 cases increases the strength of the correlation significantly ($r^2 = 0.87$, $p < 0.0001$).

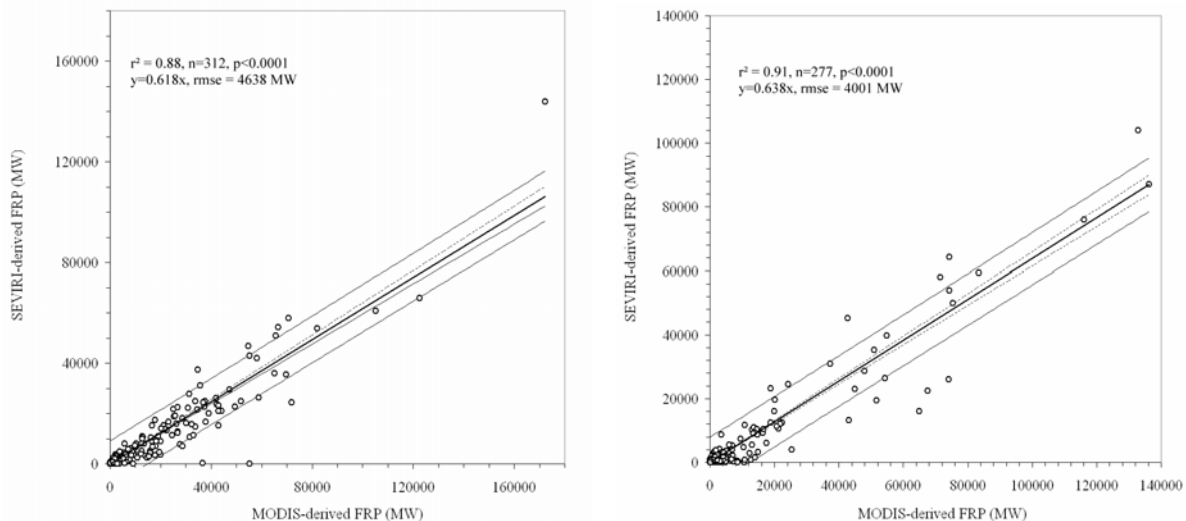
A further effect that mostly impacts retrievals over high-FRP fires is that the SCE cloud mask sometimes flags the thick smoke from particularly large fires as cloud. In the MIR it is possible to detect fire pixels through such smoke, but because the site of the fire pixel is flagged as cloud in the cloud mask, it will remain undetected. Visual inspection of a number of large fires indicates such occurrences are rare, but do occur and contribute to the increased FRP underestimation over the highest FRP fires.

The agreement between the MODIS- and SEVIRI-derived per-fire FRP is also considerably worsened for fire fires detected by SEVIRI where the MODIS-derived FRP was less than 40 MW. Such fires correspond to a SEVIRI MIR brightness temperature increase of only a few Kelvin above the background ($\sim 2 - 3$ K, depending on the ambient temperature and levels of incoming solar radiation), thus indicating that they are at the very limit of the detectability envelope seen in Figure 4.1 and are also most subject to the additive errors introduced by uncertainty in the ambient background characterisation. Considering all 289 matchups presented in Figure 5.11, 76% of the MODIS and SEVIRI FRP values agree to within 33%, a proportion that increases to 79% when considering those fires whose FRP as derived from MODIS fell within the $40 \text{ MW} < \text{FRP} < 3000 \text{ MW}$ limit. Within this limit the data show minimum bias with respect to MODIS (only 3.7 MW between the SEVIRI- and MODIS-derived per-pixel FRP measures).

5.2.2 Effect of Spatial Resolution – Area Based Comparisons

5.2.2.1 Basic Results

Figure 5.12 presents the results of the regional-scale cumulative FRP comparisons, with each point representing the total FRP observed by MODIS and SEVIRI at the time of a MODIS overpass and within the area covered by the entire MODIS swath. This area-based cumulative FRP is clearly underestimated by SEVIRI with respect to MODIS (i.e. the gradient of the lines of best fit are < 1.0), and this underestimation is due to SEVIRI's inability to detect the lowest FRP fire pixels, many of which MODIS can detect due to its significantly higher spatial resolution as already demonstrated.



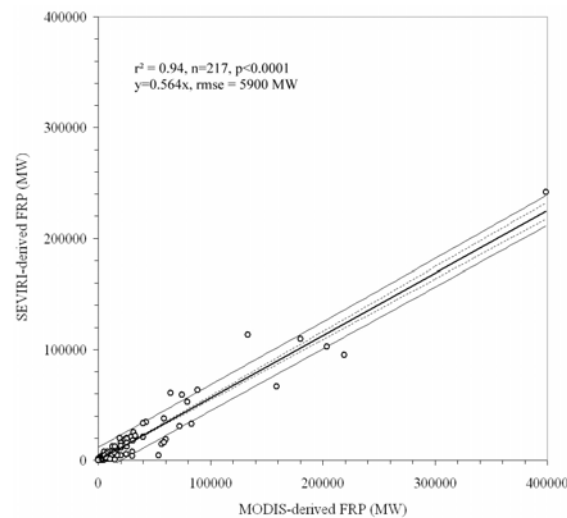



Figure 5.12: Relationship between regional-scale inter-scene FRP derived from all spatially matched, contemporaneous SEVIRI and MODIS observations for, from top left clockwise, February, May, and August 2004. Data are taken from across the African continent in each case, but fires are concentrated in north, central and southern Africa respectively. The data were taken from the entire MODIS swath, between nadir and 55° scan angle, and the area of the relevant contemporaneous SEVIRI image was spatially subset to reflect the same geographic coverage. The OLS linear best-fit passing through the origin is shown (bold line), along with the 95% confidence intervals on the mean (dotted line) and on the prediction of y from x (outermost lines). In each case SEVIRI generally underestimates regional-scale FRP, primarily due to the non-detection of the lowest FRP fire pixels, many of which MODIS can detect.

Since the proportion of low-to-high FRP fire pixels varies between each MODIS image (depending presumably on time of acquisition and its interplay with the fire diurnal cycle, and location of acquisition and its interplay with landcover/landuse) the level of agreement between the cumulative inter-scene FRP recorded by SEVIRI and MODIS also varies, resulting in a significant scatter (as indicated by $r^2 < 1.0$). Nevertheless, the relationship between SEVIRI- and MODIS-derived FRP is quite strong in each case, and the relatively high degree of similarity in the results from the different months and areas (e.g. in terms of the slope of the OLS line of best fit, the RMSE and r^2 coefficient) indicates a degree of consistency in the fire regime and algorithm performance across Africa as a whole. The total FRP measures obtained by accumulating data from the entire month of matched SEVIRI and whole-swath MODIS imagery indicates a SEVIRI-to-MODIS monthly cumulative FRP ratio of 0.57 (Feb), 0.60 (May) and 0.55 (Aug), again indicating a high degree of consistency between months.

Looking in detail at Figure 5.12, it is apparent that in some cases SEVIRI underestimates regional FRP by more than 50% compared to MODIS. The most significant cases turn out to be a consequence of small, scattered clouds and the fact that the cloud mask used in the production of the MOD14 fire product is of a higher spatial resolution than that of SEVIRI, and also appears less conservative in that it sometimes fails to mask smaller clouds and cloud edges (Giglio *et al.*, 2003a). This typically results in a greater proportion of pixels being flagged as cloud contaminated by SEVIRI than by MODIS, and also allows MODIS to correctly identify active fire pixels occurring between closely spaced clouds in a higher proportion of cases. In the remaining examples, thin clouds and/or heavy aerosols covered large areas, and the Stage 2 SEVIRI MIR/RED radiance ratio test detailed in ATBD caused a number of low FRP fire pixels to remain undetected in these cases.

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5.2.2.2 Detailed Sensor-to-Sensor Comparisons of Fire Activity Over the Annual Cycle

Of all SEVIRI scans and MODIS overpasses in the year between February 2004 and January 2005 there were 2239 timeslots in which both sensors concurrently (± 6 minutes) observed a portion of Africa. No fire pixel in the training dataset exists between 0300 and 0630 GMT nor between 1500 and 1900 GMT, due to the absence of a MODIS overpass. Daytime detections accounted for 95% of the total fire counts and 96% of the total FRP within in the training dataset for both MODIS and SEVIRI. Overall SEVIRI detected 20% of the total yearly fire pixel count, and measured 50% of the total yearly FRP compared to MODIS.

Ratios of fire pixel count and FRP were most variable at the instantaneous scale and ranged from 0.0 to 1.27 and from 0.0 to 4.86, respectively ('observation ratios' ϕ_{count} and ϕ_{FRP} in Figure 5.13). This variability in ϕ_{count} and ϕ_{FRP} between consecutive MODIS observations is attributed to the following: i) the dynamic nature and diurnal cycle of fire behaviour, ii) the timing and ground track of the MODIS overpass, iii) the different measured frequency-magnitude distributions associated with fire activity, and iv) the occasionally limited sample of fire pixels used to calculate ϕ_{count} and ϕ_{FRP} . The temporal profiles already presented in 4.3 demonstrate the combined effects of the MODIS overpass time, ground track, and swath width on the diurnal cycle of measured FRP.

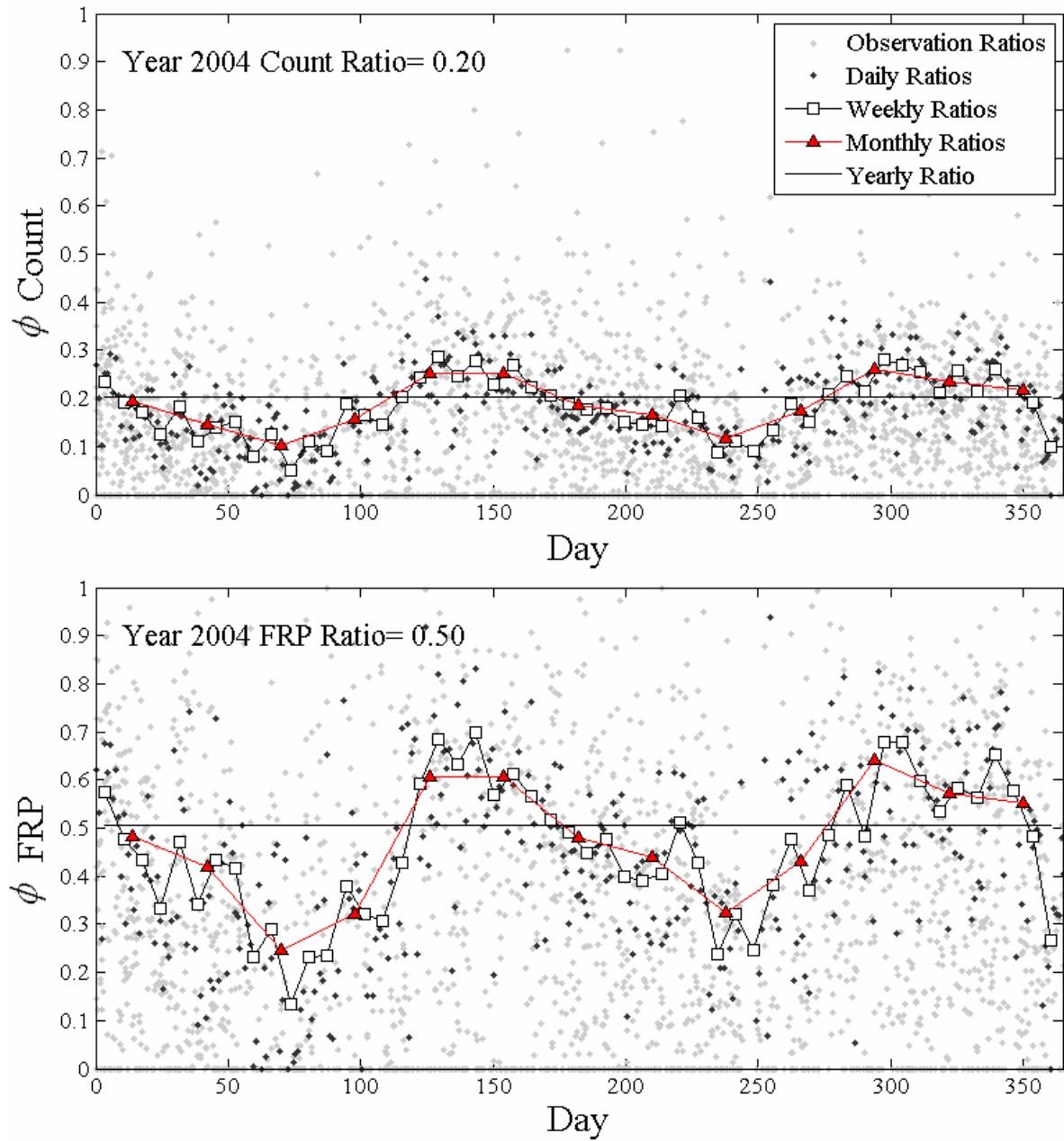


Figure 5.13: Temporal profiles in the ratios between SEVIRI and MODIS of fire pixel count, (ϕ_{Count}) and FRP (ϕ_{FRP}). Using fire pixels within the training dataset, the ratios are calculated within five temporal windows ranging from the instantaneous scale to one year.

Figure 5.14 shows the distribution of ϕ_{FRP} with respect to the FRP measured by SEVIRI and by MODIS. Of note are the two extreme groups of observations with ϕ_{FRP} greater than 1.0 and ϕ_{FRP} less than 0.1. Though each cluster spans three orders of magnitude, the range of FRP_{SEVIRI} with $\phi_{FRP} > 1.0$ was shifted an order of magnitude higher than the range of FRP_{SEVIRI} for which $\phi_{FRP} < 0.1$, while for the MODIS data the opposite behaviour is observed. The characteristics of these two clusters are separated as follows:

- For an identical value of scene-integrated FRP_{SEVIRI} , observations with ϕ_{FRP} less than 0.1 had a greater absolute number of MODIS detections as well as lower fire pixel count ratios. Furthermore 52% of the observations with $\phi_{FRP} < 0.1$ had frequency



magnitude distributions that were composed entirely of SEVIRI fire pixels less than 56 MW.

- The scenario at which FRP_{SEVIRI} was 4.9 times greater than FRP_{MODIS} occurred at an observation with a low absolute number of MODIS detections ($n_{MODIS} = 9$), a high count ratio ($\phi_{FRP} = 0.78$), and captured a thermal distribution in which pixels greater than 56 MW accounted for 90% of FRP_{SEVIRI} .

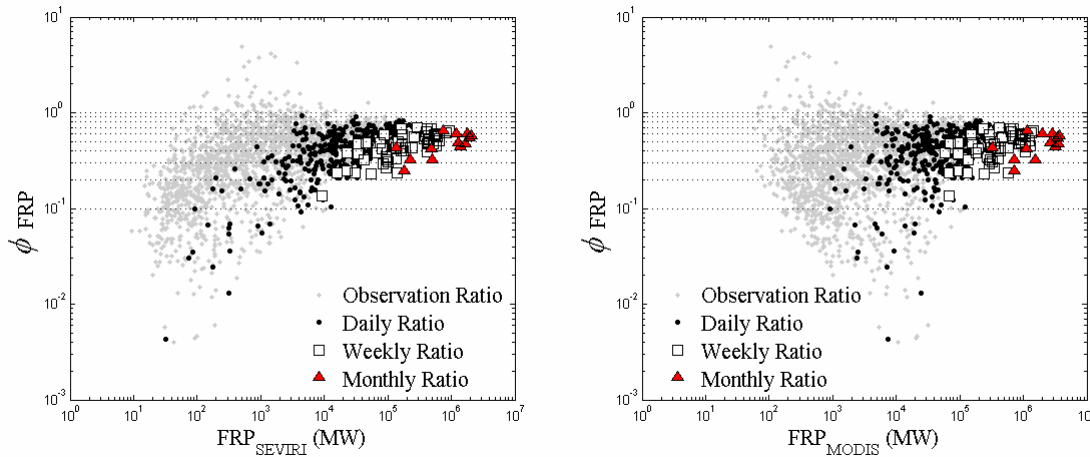


Figure 5.14: Ratios of FRP, ϕ_{FRP} , as a function of the FRP measured by SEVIRI (left) and MODIS (right). Ratios are identical to those presented in Figure 5.13, and are separated by the width of the temporal window in which the fire pixels were aggregated; either on an observational ($n=2239$), daily ($n=365$), weekly ($n=52$), or monthly basis ($n=12$).

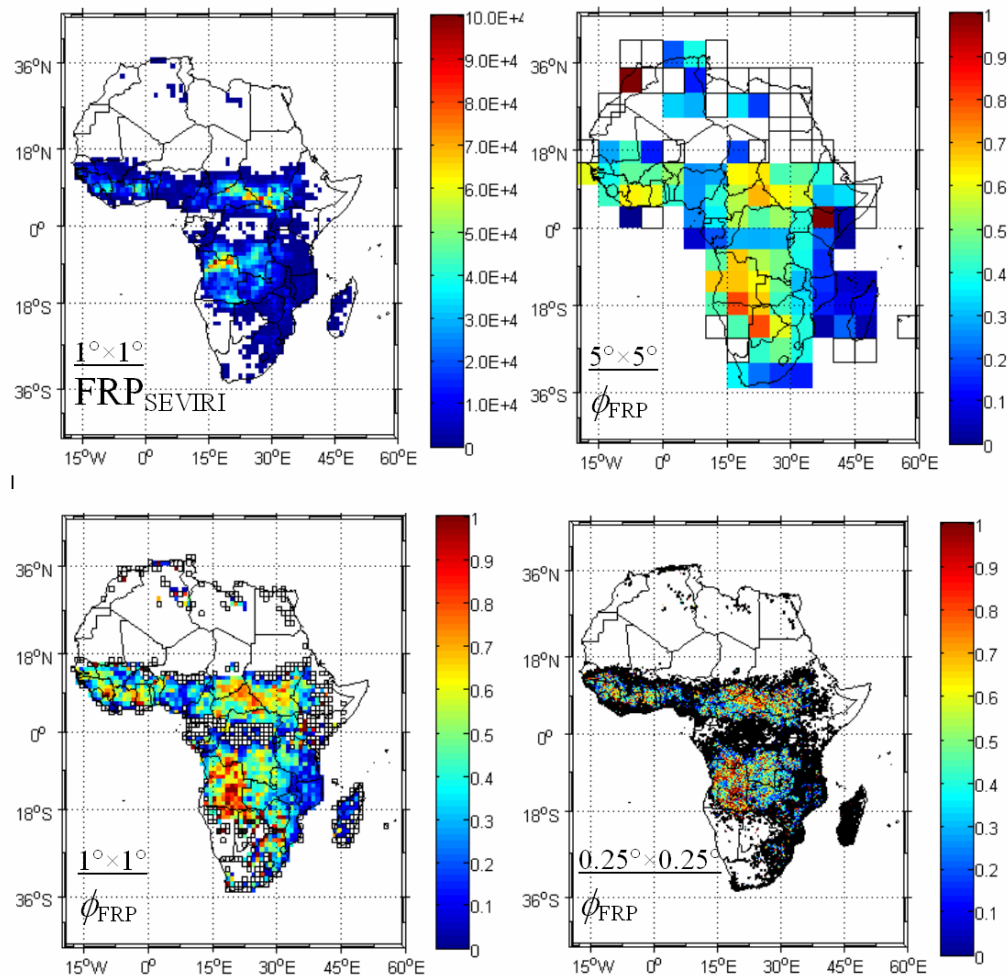
Given the variability of the instantaneous ratios in the training dataset, and the limited number of MODIS overpasses in a single day, diurnal cycles of ϕ_{count} and ϕ_{FRP} could not easily be discerned. However, seasonal patterns of ϕ_{count} and ϕ_{FRP} were discerned after accumulating fire pixels into non-overlapping intervals of one-day, one-week, and four-weeks (Figure 5.13 and Figure 5.14). The variability of the instantaneous ratios narrowed as more in-scene radiant energy was measured; and as an example ϕ_{FRP} converged from over four orders of magnitude between low and moderate measures of FRP_{SEVIRI} to values within 0.4 and 0.9 for temporally aggregated measures of FRP_{SEVIRI} greater than 1×10^5 MW (Figure 5.14a). The temporal superposition of the frequency magnitude distributions not only enhanced the thermal signal above the background, but due to the overpass times and the ground tracks of the MODIS swath, the wider temporal windows coalesced the ratios that were calculated i) at different times in the diurnal cycle of fire behaviour, and ii) at different geographic locations. Thus the extreme variability in the ratios at the instantaneous scale was moderated as the temporal window was widened, and this effect can be most clearly seen in Figure 5.13. Temporal windows above that of the individual MODIS observations include data from all four MODIS passes typically available for any particular location per day (i.e. 1:30am; 10:30am; 1:30pm and 10:30pm local equator crossing time).

Weekly and monthly ratios of ϕ_{count} and ϕ_{FRP} shop vary with the total FRP detected by SEVIRI, but the relationship is imperfect (e.g. Figure 5.14a), and analysis of the seasonal trend in ratios shows that they are loosely coupled to the migration of fire activity over the continent. In Figure 5.13, the elevated ratios ($\phi_{count} > 0.2$ and $\phi_{FRP} > 0.5$) seen at the beginning of February 2005 (Day 1) and also at the end of November through December (Days 300 – 336) are associated with fire activity in the latitudinal belt between 3 and 12° N



in Sierra Leone, Guinea, Ghana, and in particular in Central African Republic and Sudan. Similarly, elevated ratios of ϕ_{count} and ϕ_{FRP} in June and July (Days 125 – 175) are associated with the latitudinal belt between 4 and 20 °S, and in particular the northern part of Angola. The depressed ratios ($\phi_{count} < 0.2$ and $\phi_{FRP} < 0.5$) correspond to the weaker fire activity during the transition between the Northern and Southern hemispheres.

Yearly ratios calculated at 5.0, 1.0 and 0.25° grid cell resolutions illustrate the spatial patterns of ϕ_{count} and ϕ_{FRP} across the African continent (Figure 5.15). Again the relationships between the absolute number of fire pixel counts and ϕ_{count} and between FRP and ϕ_{FRP} were relatively weak. As described above, the ratios at different locations were representative only of the time in which the areas burned. Grid cells at 5° resolution were large enough to span different land cover types, land use practices, and ultimately fire regimes and therefore fail in some respects to adequately capture the inherent spatial variability of the ratios. Conversely however, a higher grid cell resolution can result in noisy ratios that fail to obtain enough statistical samples to reduce the inherent scene-to-scene variability (a feature analogous to the temporal sampling issues demonstrated in Figure 5.13). Similar to the expansion of the temporal window demonstrated there, the aggregation of fire activity within relatively large 5° grid cells moderated the ratios that otherwise can be dominated by localized hotspots at sub-5° grid cell resolutions.



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Figure 5.15: Yearly sum of FRP_{SEVIRI} at 1° grid cell resolution (upper left) and yearly ratios of FRP_{SEVIRI} to FRP_{MODIS} (ϕ_{FRP}) evaluated at 5.0 , 1.0 and 0.25° grid cell resolutions. Open boxes with solid black outlines indicate null ratios where MODIS detected at least one fire pixel, but SEVIRI did not. .

In Figure 5.15, clear spatial patterns in ϕ_{count} and ϕ_{FRP} become visually distinguishable at the 1° grid cell resolution, as compared to the 5° resolution. Furthermore, as with the lower density of fire pixels that surround regions of high fire activity, a higher number of grid cells at this finer spatial resolution had null ratios where MODIS detected fire pixels, but SEVIRI did not (indicated by the open boxes). Of note in Figure 5.15 is that the spatial pattern of ϕ_{FRP} at 0.25° resolution becomes rather noisy, with the variability reinforced due to the smaller sample size that is influenced more by individual combustion events. At this spatial scale, the finest tested here, the small grid cell size and uncertainties in the registration of the fire pixel centres also become increasingly important. Fire pixels that in actuality represent the same fire on the ground might be successfully detected by SEVIRI and MODIS, but at this grid-cell size there is an increased chance they could be erroneously located in different (adjacent) grid cells.

5.2.2.3 Potential Adjustment of SEVIRI Gridded FRP Data for the Effect of Undetected Fires

Two methods were tested for adjusting the observed SEVIRI FRP measurements to what they would have been had MODIS been the observing instrument. Before this, a non-spatially explicit set of continent-wide ϕ_{FRP} ratios were constructed via temporal interpolation of the data shown in Figure 5.13.

(a) Interpolation of the Ratios within the Training Dataset

Based upon the variability of the ratios presented in Figure 5.13, an interval of one week was selected as the minimum temporal window within the training dataset at which there were sufficient number of fire pixels detected by SEVIRI and MODIS *at the overpass times and spatial coverage of MODIS* to i) overwhelm influences of detector sensitivity, algorithm performance, and random variability of fire behaviour at observations of low fire activity, ii) form well structured frequency distributions of FRP, and iii) capture continental trends in the ratios rather than location-specific patterns associated with isolated swaths. The first method for adjusting SEVIRI active fire detections yielded 365 rolling weekly ratios calculated at 1200 GMT each day (Figure 5.16). The rolling weekly ratios shared the same macroscopic trend as the 52 discrete weekly ratios, but also contained microstructure associated with significant fire events occurring at daily resolution. Ratios specifically at SEVIRI timeslots (indicated by the lines connecting the 365 rolling weekly ratios in Figure 5.16) were retrieved by simply linearly interpolating between the ratios at 1200 GMT obtained from Equation 5.2. Since this method offered no predictive capability it could not be independently validated with data collected outside the training dataset. Instead these interpolated ratios were used to evaluate the monthly grid products.

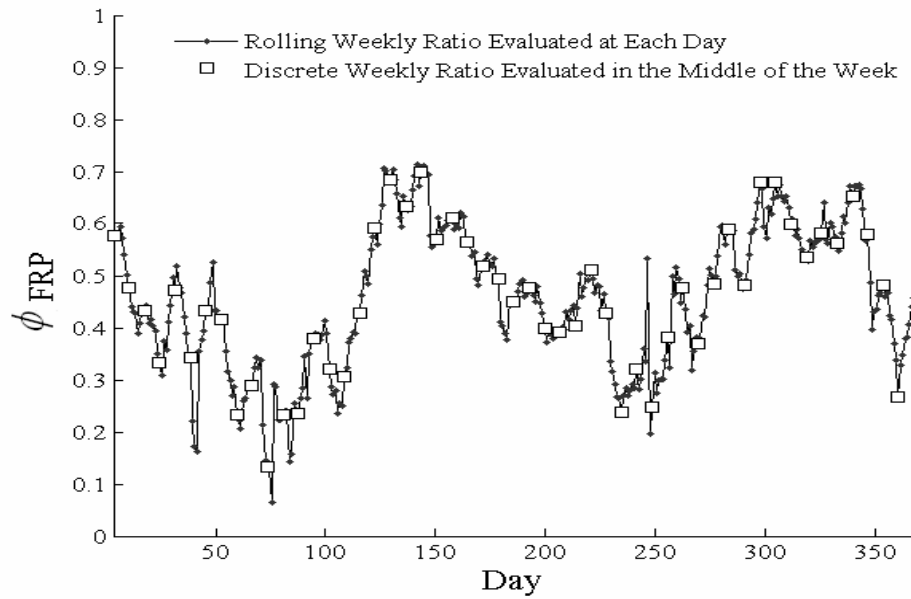


Figure 5.16: Temporal profile of the ratios between FRP_{SEVIRI} and FRP_{MODIS} , ϕ_{FRP} . The 52 discrete weekly ratios were calculated within non-overlapping temporal windows that were each 7 days wide. The 365 rolling weekly ratios were calculated within a moving weekly window such that six of the seven consecutive days overlapped. Ratios used to adjust the 2004/05 SEVIRI dataset at full temporal resolution and continental coverage were determined by linearly interpolating between the rolling weekly ratios assigned each day at 12:00 GMT.

(b) Development of the Monthly Gridded Ratio Products

Spatially explicit monthly ratios of ϕ_{count} and ϕ_{FRP} developed within the training dataset are presented in Figure 5.17 and Figure 5.18, respectively.

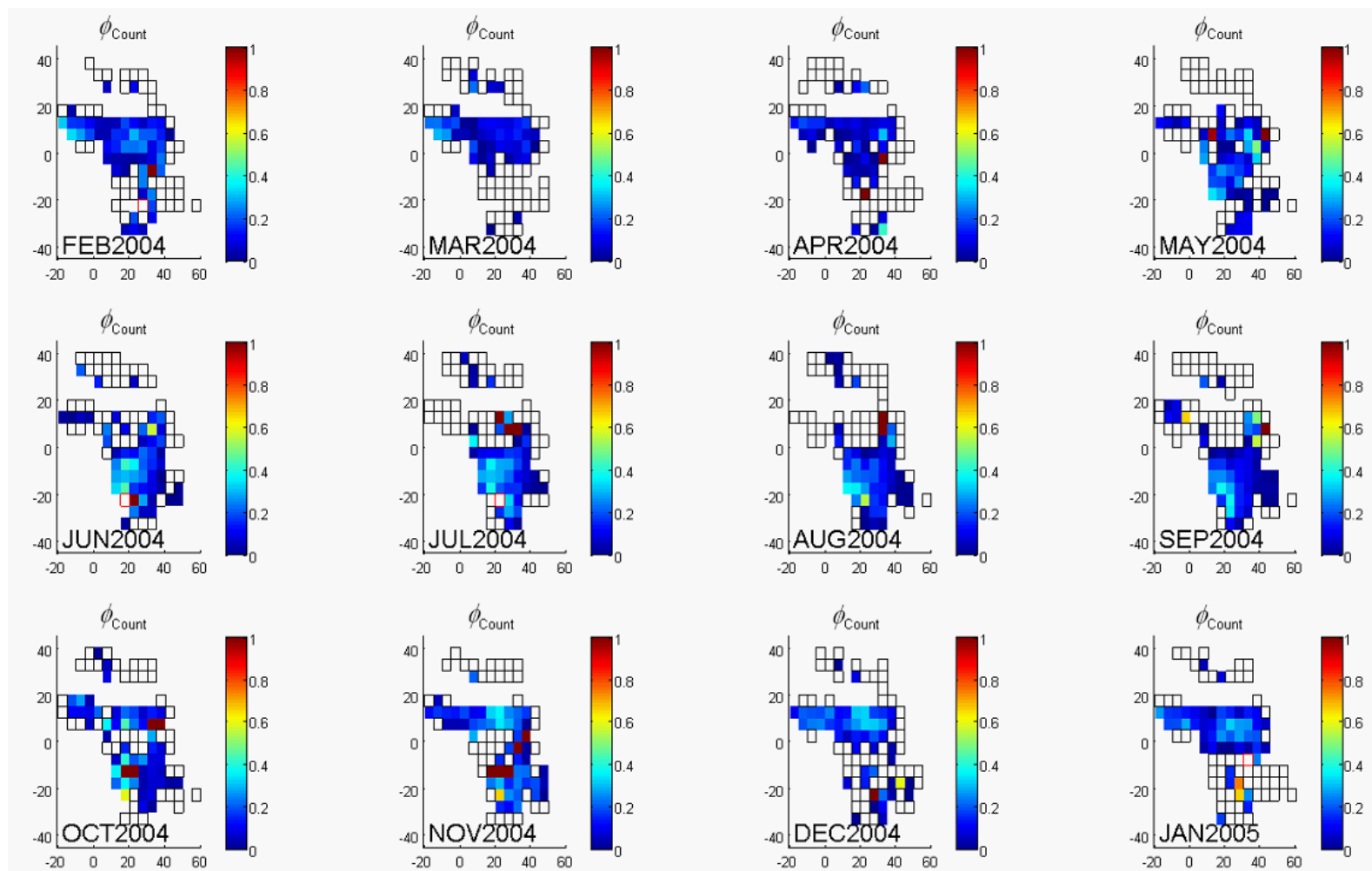


Figure 5.17: Monthly-gridded ratios of fire pixel counts measured between SEVIRI and MODIS (ϕ_{count}). Hollow grid cells with a black outline indicate a ratio of zero where MODIS detected fire pixels, but SEVIRI did not.

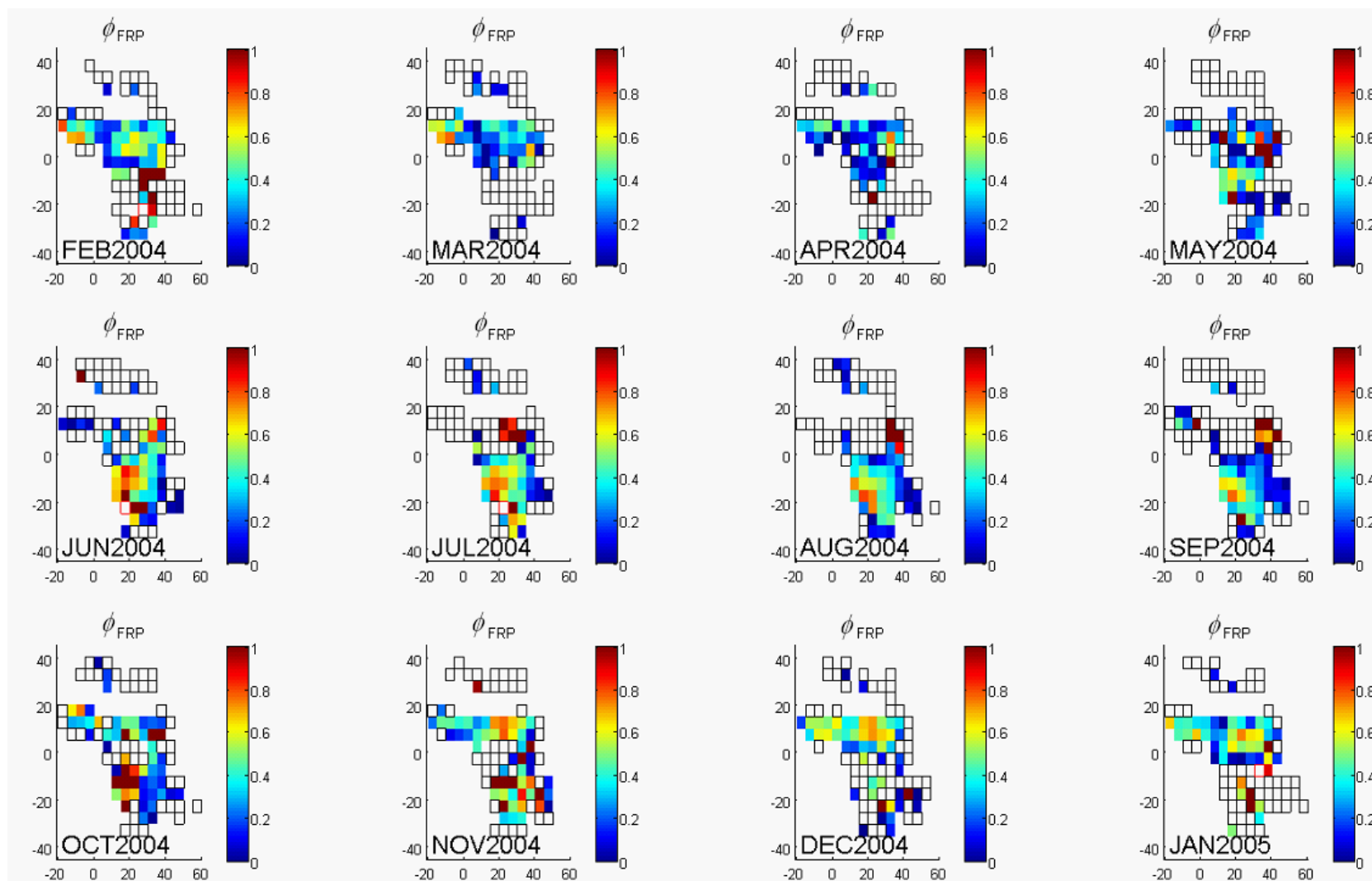


Figure 5.18: Monthly-gridded ratios of FRP measured between SEVIRI and MODIS (ϕ_{FRP}). Hollow grid cells with a black outline indicate a null ratio where MODIS detected fire pixels, but SEVIRI did not.

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(c) Comparison of the temporal and spatial adjustment methods

As an evaluation exercise, the 12 monthly grid products shown in Figure 5.17 and Figure 5.18 were used to adjust the SEVIRI fire pixels counts and observed FRP at the full 15-minute temporal resolution and continental coverage between February 2004 and January 2005. Comparisons between the interpolation of the rolling weekly ratios described in (a) above, and the application of the monthly grid products described in (b) above are presented in Figure 5.19. Although the training dataset (as a subset of the full SEVIRI dataset) supplied the ratios that were both interpolated as well as stored in the monthly grid product, and so the validation cannot be considered fully independent, it is still reassuring that the results from application of both methods show relatively good agreement.

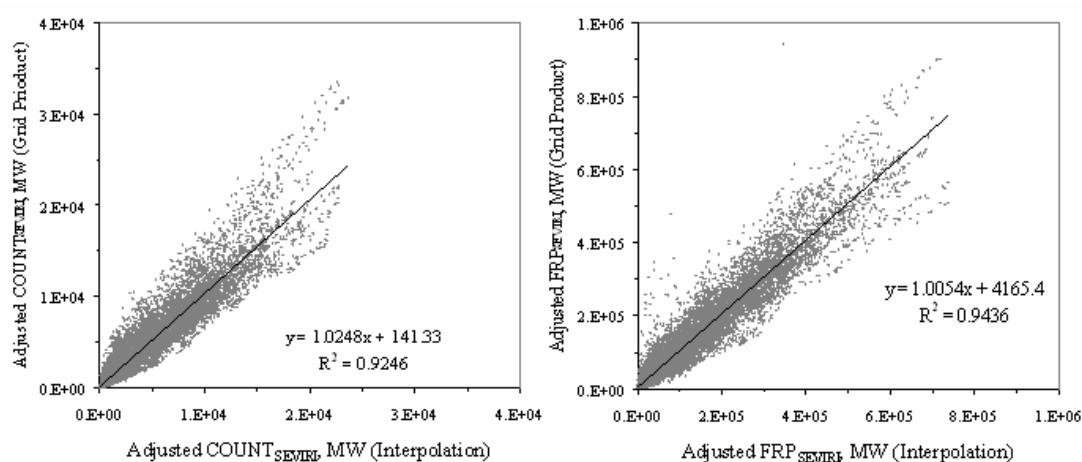


Figure 5.19: Comparisons between two of the methods used to adjust the 2004/05 SEVIRI dataset at full temporal resolution and continental coverage ($n=31616$ observations). Fire pixel counts (left) and FRP (right) were adjusted via interpolation of the rolling weekly ratios and via the monthly grid product. Both the interpolated product and the grid product were derived from concurrent and collocated fire pixels within training dataset.

A fully independent validation of the 5° grid product was performed using a separate dataset from August 2007. Each of the 102 concurrent and collocated matchup observations in August 2007 consisted of a single MODIS ground track that intercepted on average 6 grid cells with a range between one and 18 grid cells. For each concurrent and collocated observation, the FRP_{SEVIRI} in each individual 5° grid cell was summed, divided by the ϕ_{FRP} from the August 2004 grid product, then summed again over all grid cells to yield the total, adjusted FRP_{SEVIRI} on an observational basis. The adjusted FRP_{SEVIRI} was then compared to the actually measured FRP_{MODIS} . The level of agreement will depend on how similar the fire activity in August 2007 is, in terms of the ratio of small to large fires and their spatial distributions, to that seen in August 2004.

Figure 5.20a shows the results of this comparison, and the linear regression fit to the instantaneous observations in Figure 5.20a exhibits relatively good agreement ($r^2=0.83$), the slope of the OLS line of best fit exceeds unity (slope = 1.23) and indicates that using the August 2004 grid product to adjust FRP_{SEVIRI} in August 2007

ultimately overestimates FRP_{MODIS} . However, it overestimates by a smaller factor than the unadjusted SEVIRI data underestimates FRP_{MODIS} by (in that case the slope of the OLS line of best fit is 0.47) and so indicates that applying the adjustment factor (i.e. ϕ_{FRP} determined from the 2004 dataset) does improve the level of agreement between the SEVIRI and MODIS measures of FRP. Furthermore, based upon the relationship between the measured FRP_{SEVIRI} and FRP_{MODIS} at the observational scale (Figure 5.20a), it appears that a simple linear scalar would suffice to adjust SEVIRI-derived FRP to those made by MODIS.

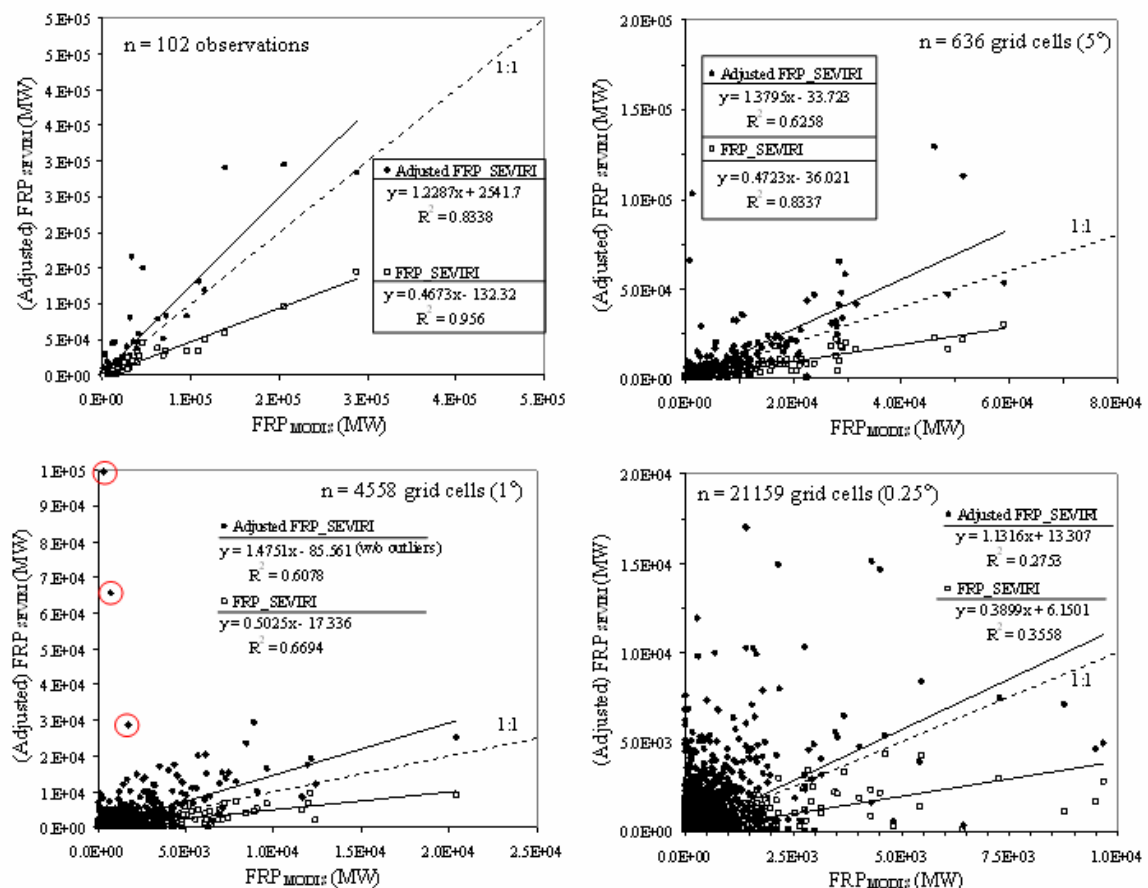



Figure 5.20: Validation of the August 2004 grid product using fire pixels detected by SEVIRI and MODIS in August 2007. Comparisons are presented between FRP_{MODIS} and the adjusted FRP_{SEVIRI} (black circles) and the un-adjusted FRP_{SEVIRI} (hollow boxes). The linear regression fit to the 102 concurrent and collocated observations is valid regardless of the grid cell resolution at which FRP_{SEVIRI} was adjusted (a, upper left). The spatially explicit effects of applying the August 2004 monthly grid product are also presented at the native the 5° grid cell resolution (b, upper right), at 1.0° grid cell resolution (c, lower left) and at 0.25° grid cell resolution (d, lower right). Three outliers (i.e., three grid cells) removed prior to fitting the linear regression at 1.0° grid cell resolution is highlighted by red circles (c, lower left).

Summing over the entire month, the total adjusted SEVIRI data for August 2007 overestimated the monthly MODIS fire counts by 18%, and overestimated the monthly MODIS FRP by 37%. Interestingly the monthly values in the training dataset

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for ϕ_{count} and ϕ_{FRP} in August 2004 were 16.9% and 44.5%, whereas in August 2007 these percentages remained very similar at 16.4% and 46.0%, respectively. The consistency of these figures suggest that, in fact, differences between the predicted FRP_{MODIS} (i.e. the adjusted SEVIRI FRP observations) and the actual measurements of FRP_{MODIS} at the observational scale are very likely attributable to interannual differences in the exact spatial distribution of fires and consequently ϕ_{count} and ϕ_{FRP} , rather than to their overall magnitude (i.e. many of the fires in August 2007 were in a different grid-cell than in August 2004, and these different cells had different ϕ_{count} and ϕ_{FRP} values).

The adjusted FRP_{SEVIRI} and measured FRP_{MODIS} at 5° resolution were also compared at the grid cell level. Fire pixels detected by either SEVIRI or MODIS during the 102 individual observations in August 2007 were contained within 636 grid cells at 5° resolution (i.e., grid cells with the same extents at different time slots were considered individually). The linear regression relating the adjusted FRP_{SEVIRI} and the measured FRP_{MODIS} for each of the 636 grid cells at 5° resolution is presented in Figure 5.20b. Again the positive bias indicates that adjustments of FRP_{SEVIRI} using the August 2004 grid product served to over predict the FRP_{MODIS} actually measured in August 2007. Furthermore the correlation coefficient ($r^2 = 0.63$) supports the inference of the spatial heterogeneity of the adjustments as stated above for the observation scale. Once again the true, rather linear, relationship between the measured FRP_{SEVIRI} and FRP_{MODIS} implies that at the grid level a simple scalar would suffice to adjust one to the other.

Finally, the August 2004 grid product of ratios was applied to the instantaneous measurements of FRP_{SEVIRI} in August 2007 summed at 1° and 0.25° resolution. At the observational scale, the relationship between the adjusted FRP_{SEVIRI} and the measured FRP_{MODIS} were identical to those presented in Figure 5.20b, regardless of the grid cell spatial resolution. This is because at the observational scale all energy is accounted for regardless from which grid cell it is emitted. Interestingly, after three outliers were removed from the linear regression, the relationship between the adjusted FRP_{SEVIRI} summed at 1° resolution and the measured FRP_{MODIS} summed at 1° resolution is not too different from the grid-level relationship at 5° resolution (Figure 5.20c). Although the bias changes between scales, the nearly equivalent correlation coefficients (i.e., $r^2 = 0.63$ vs. $r^2 = 0.61$) demonstrates that these two methods of application offer similar predictive capability. These results suggest that the monthly grid products at 5° grid resolution can be applied at 1° resolution without a dramatic loss of confidence in the estimate. At 0.25°, however, the relationship between the adjusted FRP_{SEVIRI} and measured FRP_{MODIS} per grid cell disintegrates (Figure 5.20d), and we conclude that a 1° grid cell resolution is thus the highest spatial resolution appropriate for the SEVIRI gridded FRP product that will include the adjustment for smaller ‘undetected’ fires.

Also analysed was the value of deriving time-specific values of ϕ_{count} and ϕ_{FRP} from the 2004 matchup datasets appropriate for the different MODIS overpass times (Figure 5.21). Due primarily to the preponderance of low FRP fires during morning and evening overpass times when compared to daytime overpass times, the ratios of both MODIS to SEVIRI fire pixel counts and FRP are, on average, lower at these times. However, when the additional value offered by these diurnal ratios was tested

using the August 2007 validation data (via modulation of the 2004-derived grid-cell ratios by the value appropriate to the particular MODIS observation time being considered), the level of agreement between the ‘adjusted’ FRP_{SEVIRI} and ‘observed’ FRP_{MODIS} was the same as that shown in Figure 5.20c. Further work is needed to explore this issue and identify whether the fixed grid-cell method is the optimum approach for deriving such adjustments.

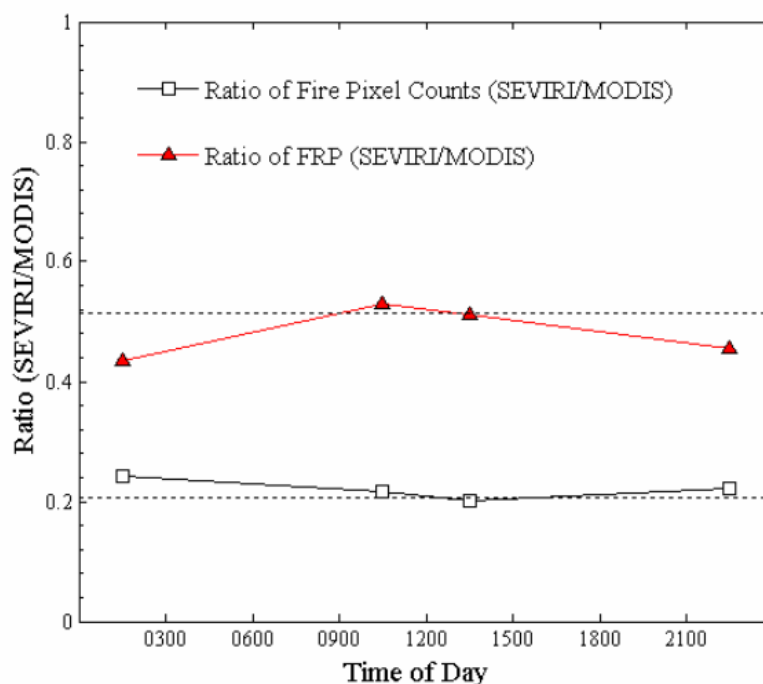


Figure 5.21: Diurnal pattern of ratios calculated using all concurrent and collocated fire pixels detected by SEVIRI and MODIS over Africa during 2004. Ratios are categorized into the morning and afternoon overpasses of AQUA and TERRA.

5.2.3 Analysis of Ecosystem-Specific Biases

Figure 5.22 shows the land cover classification from the GLC 2000 data set and the fractions of fires detected in each land cover type for the MODIS MOD14 and SEVIRI data sets. There is generally good agreement between the two data sets with maximum differences of 4% attribution (maximum relative error of 25%). SEVIRI has a tendency to detect relatively more fires in mosaic forests and deciduous woodlands compared to MODIS, while MODIS detects more fires in scrublands and croplands. For the most part this can be explained by the different detection thresholds of the two instruments (a lower limit of 20-40 MW FRP for SEVIRI and 7-10 MW FRP for MODIS) and the sorts of fires dominating each particular landcover class. In particular, cropland fires tend to be very small (i.e. have low FRP) and are thus more likely to be missed by SEVIRI data set than by MODIS.

With the present analysis it remains unclear to what extent the (small but significant) differences in the vegetation-type specific fire detection efficiency are related to the viewing geometry of the two instruments. This could in future be tested by analyzing fires in similar vegetation classes which occur in different regions on the African continent (for example cropland fires in the Sahel zone versus those in Northern Africa or South Africa).

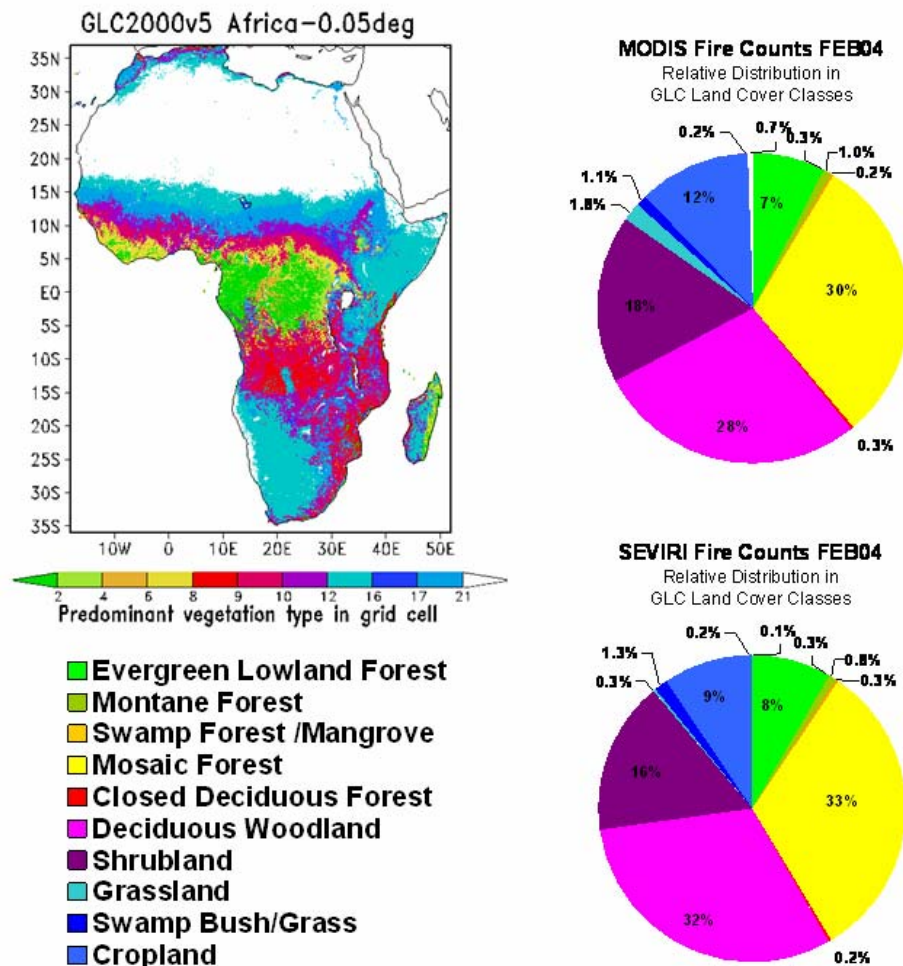



Figure 5.22: GLC 2000 land cover classification and relative frequency of fire detection in each land cover type for MODIS and SEVIRI data.

5.2.4 Effects of Viewing Geometry

No specific analysis was performed to investigate the effects of the viewing geometry. However, various results reported in the other sub sections point to a decreasing detection efficiency and reduced FRP accuracy for pixels far away from the sub-satellite point (see for example Figure 5.35).

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5.2.5 Effects of Saturation

To quantify the extent of MIR channel sensor saturation, the KCL FRP product data of February, May and August 2004 were used. It was found that SEVIRI detected 1.3 million fire pixels in February 2004 across Africa, of which only 0.1% were saturated in the level 1.5 data. In May and August the numbers were 0.9 million (0.5% saturated) and 1.7 million (0.6% saturated) respectively, and thus saturation when taken over the entire dataset, is seen to be a relatively minor occurrence. However, on a per-fire basis saturation levels can be more than an order of magnitude greater, even potentially affecting 25% of the fire pixels recorded over very intense/large fires, and on a per-slot basis at the time of peak fire activity saturation typically affects a few percent of the detected fire pixels.

Figure 5.23 shows the results of the SEVIRI ‘special operations mode’ experiment with regard to instrument saturation. In this case the Meteosat-8 SEVIRI instrument was operated with an extended dynamic range and with a rapid 5-minute scan over southern Africa during September 2007, at the peak of the fire season in this region. The plots shows a comparison of total sub-scene FRP when the instrument is operated in low gain mode (essentially without any saturation of the MIR spectral channel) as compared to the same data with the saturation effect artificially induced. Results are not currently available for data collected around the midday period, but the plot indicates that saturation is a more prevalent phenomenon at the location of peak burning than is suggested by the continent-wide data above. Towards the diurnal peak, approaching 5% of detected fire pixels are saturated, resulting in an FRP underestimation of around 10%. At night this increases up to 8% and 40% respectively, though the total sub-scene FRP at night is low so the overall effect on the cumulative time-integrated FRP (i.e. the FRE) would be minimal and the lower levels of FRP percentage underestimation present during the day cause a far greater total effect. Analysis of the individual pixel brightness temperatures confirms that under this extended dynamic range operation (max MIR channel BT = 375 K) less than 0.002% of the total fire pixels detected over the day are saturated, and thus operating SEVIRI in such a mode would effectively negate any impact of pixel saturation on the FRP results.

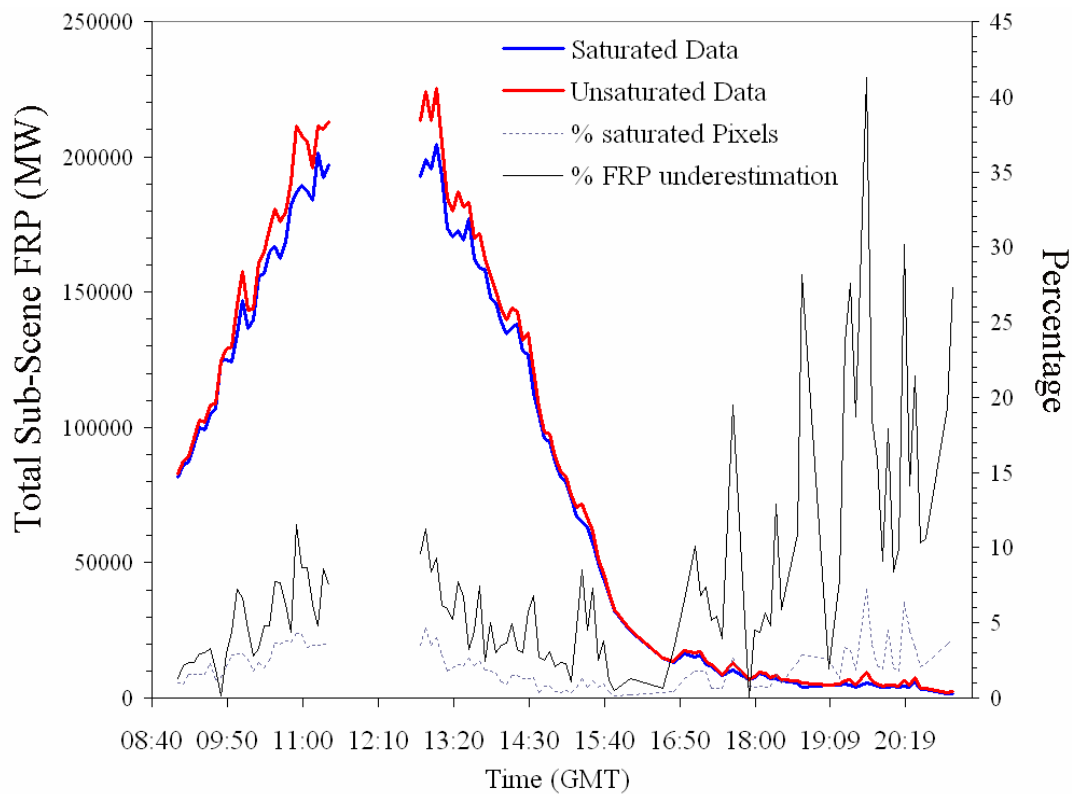



Figure 5.23. Data from the SEVIRI ‘special operations mode’ experiment conducted on 4 September 2007, when the Meteosat 8 SEVIRI instrument was put into low-gain mode. The figure compares the sub-scene cumulative FRP recorded in this ‘unsaturated’ mode to that which would have been recorded under normal conditions (i.e. with saturation present for pixels with a MIR BT of 335 K or greater), and the figure also show the % of pixels that would have been saturated, and the degree of FRP underestimation caused by this saturation, also expressed as a percentage.

5.2.6 Effect of SEVIRI Image Processing Chain

Table 5.1 shows the impact of the level 1.0 to level 1.5 conversions on the number of saturated SEVIRI pixels. It is very clear that the smoothing employed in the spatial regridding of the level 1.0 data results in a much lower number of saturated pixels in the output level 1.5 data. As a consequence, under normal observation conditions there is likely to be more FRP underestimation present than is suggested by the number of saturated pixels present in the level 1.5 product.

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Date and time	Level 1.0 3.9 BT saturation range (DN)	Level 1.5 Max 3.9 BT (Kelvin)	Level 1.0 Number of Saturated Pixels	Level 1.5 Number of Saturated Pixels
20040712081503	334.22 - 334.49 (1023)	335.56	8	4
20040712083003	334.21 - 334.49 (1023)	332.20	64	27
20040712084504	334.49 (1023)	335.56	1	1
20040712090004	334.21 - 334.49 (1023)	335.56	9	1

Table 5.1: Pixel saturation statistics for level 1.0 and level 1.5 versions of SEVIRI fire scenes.

Data from the SEVIRI ‘special operations mode’ experiment is shown in Figure 5.24 with regard to the on-board application of the FIR filter. In this case the FIR filter was not applied to the Meteosat-8 data, and the improved fidelity of the observations of this fire can be clearly seen when compared to the contemporaneously recorded Meteosat-9 data upon which the FIR filter was used.

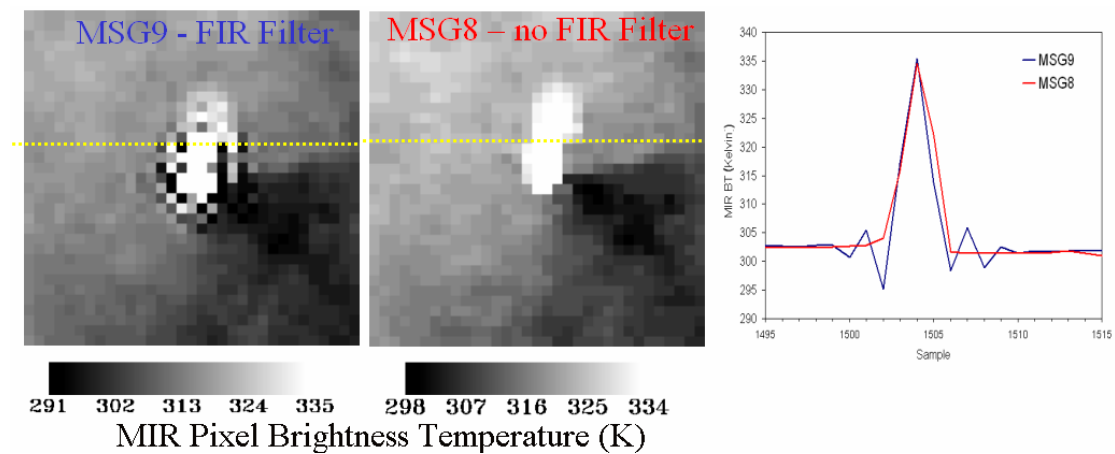



Figure 5.24. Data from the SEVIRI ‘special operations mode’ experiment conducted on 4 September 2007, when the FIR filter was removed from the Meteosat 8 SEVIRI instrument but kept on the Meteosat 9 SEVIRI instrument that observed the same area almost simultaneously. The figure shows the MIR brightness temperatures recorded over the same fire by both systems, and the transect illustrates the effect of the FIR filter negative side lobes.

The impact of this FIR filter on the retrieved FRP observations was assessed primarily through simulations, calculated using the steps shown in Figure 5.25. An example output from the simulation of the SEVIRI observation process, which included

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representations of both the SEVIRI point spread function (PSF) and finite impulse response (FIR) filter and a set fire size and temperature, is shown in

Figure 5.26. A real SEVIRI active fire observation with the FIR filter employed is shown for comparison. The similarity of these two representations is apparent, particularly in terms of the increased radiance at the fire pixels themselves and the depressed radiances at the surrounding pixels due to convolution with the FIR response filter and its negative side lobes. The primary difference in the two representations is that in the model a spatially ‘flat’ background (i.e. constant brightness temperatures) are used, whereas the background in the true SEVIRI data has some variability due to ambient surface temperature variations. These depressed radiances can induce a higher brightness temperature variability in the ambient background window around fire pixels, and thus can impact the likelihood of the fire pixels actually being detected (since the algorithm scales certain of the detection criteria by a measure of the variability of signals found with the surrounding background window).

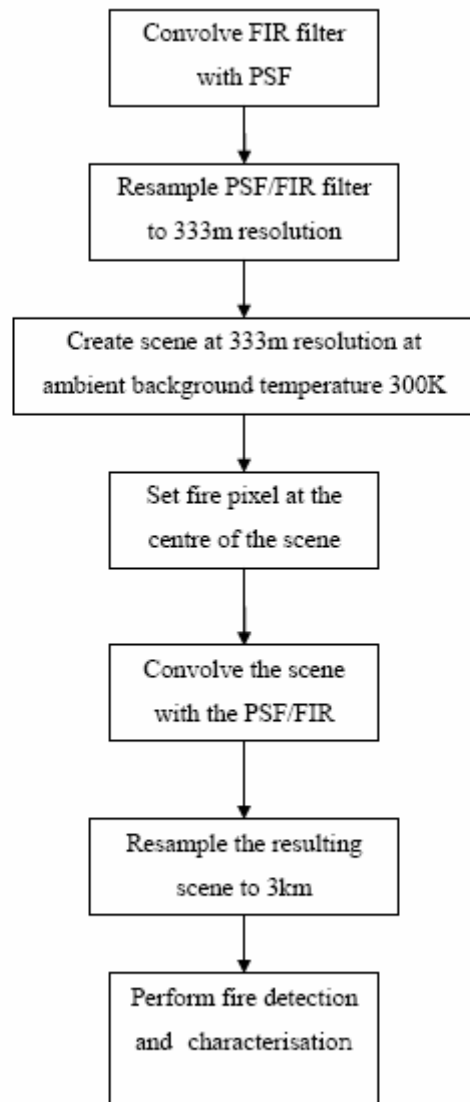


Figure 5.25. *The major steps involved in simulating SEVIRI active fire observations using a spatially invariant background temperature of 300 K.*

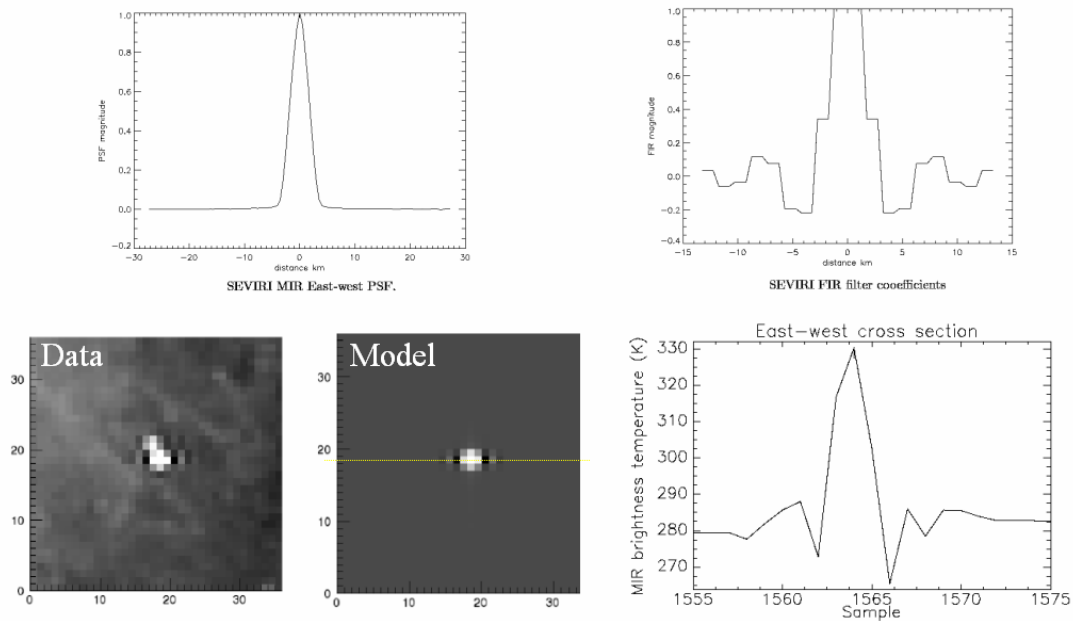


Figure 5.26: The SEVIRI point spread function (E-W) and the finite impulse response filter, together with a SEVIRI observation of an active fire modelled with these as compared to a real SEVIRI active fire observation. The effect of the negative side lobes (resulting in depressed radiances either side of the fire) induced by the FIR filter can be seen in both, and their impact is shown quantitatively by the east-west transect.

The effect of the SEVIRI observation process on the quantification of FRP was assessed using simulated SEVIRI active fire data of the sort shown Figure 5.27, calculated for differing fire size and temperature distributions (and so different FRP values). The SEVIRI PSF acts to smooth the fire radiance out over neighbouring pixels and can result in fire pixels at the edges of the fire actually contain some of the fire energy output, but with signals that do not allow them to be detected as fire pixels. This will cause underestimation of FRP compared to the raw FRP error (induced by the Planck function approximation), and the magnitude of this is shown in the “FRP without FIR” error value in Figure 5.27. In some cases its magnitude actually cancels out the effect of the Planck function approximation. The additional application of the FIR filter, expressed by the “FRP level 1 error” makes the most significant difference to the degree of error in the case where the fire forms the largest proportion of the pixel (1%), but in fact all such fires would have in reality resulted in a saturated SEVIRI pixel in any case, so the effect would have been outweighed in magnitude by the saturation impact. For non-saturated fires covering 0.1% and 0.01% of the SEVIRI pixel field of view (FOV), application of the FIR filter has less of an effect. It acts in two ways, with the positive side lobes directly giving rise to additional fire pixels and the negative side lobes having an adverse affect on the background characterisation involved in the fire detection algorithm (and thus potential leading to FRP overestimation via depression of the background temperature estimate). The lowest FRP fires shown here are those where the fire size is 0.01% of the SEVIRI FOV (rightmost plot), and for fires of this size only those with a fire-

effective temperature of ~ 800 K or higher would in fact be detectable under real conditions (i.e. with a varying ambient background temperature). Nevertheless, the Figure indicates that such low FRP but still potentially detectable fires may in theory have their FRP underestimated by up to 60% under the conditions examined here, due primarily to the effect of the sensor PSF smoothing the fire radiance out over a number of pixels, and to some of these pixels failing to be detected as fire pixels. At such low signals, the effect of the FIR filter is negligible, and thus the FRP underestimate is equal with and without the FIR filter.

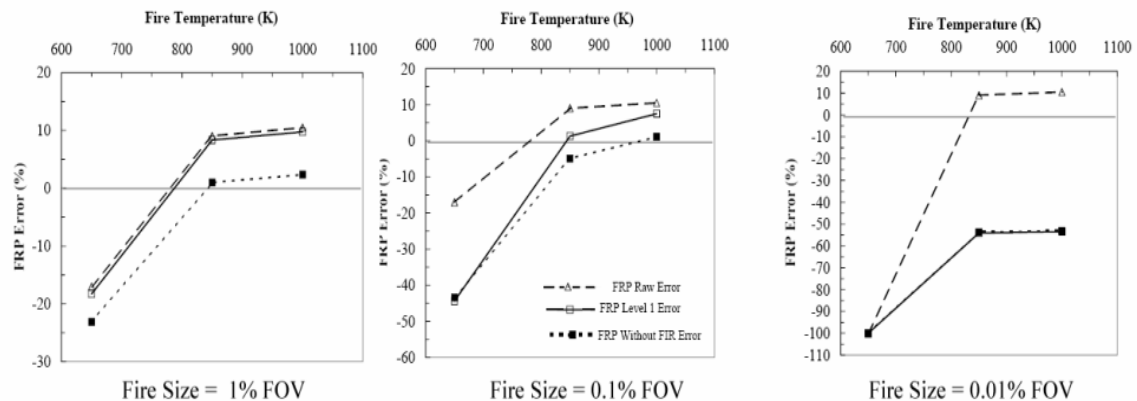



Figure 5.27: The effect of the SEVIRI observation process on the retrieval of FRP for fires of different effective temperatures and pixel proportions. The errors in FRP is shown due to the fourth order approximation to the Planck function only, to the complete modelled level 1 observations process (PSF and FIR filter) and to the observations without the FIR filter.

In order to determine the effect when the ambient background temperature is allowed to vary in a realistic way, BIRD data were used to provide the MIR background radiances for the simulations, upon which the modelled fire spectral signals were superimposed. The resulting array subject to the same SEVIRI observation process as described above. Figure 5.28 shows the resulting simulated SEVIRI MIR and TIR channel data, whilst Figure 5.29 shows the degree of error for the range of fire FRP's that are detectable from SEVIRI. The use of the varying background temperature has increased the background variability measure, thus increasing certain of the fire pixel detection algorithm thresholds that are scaled by this parameter, consequently making any low signal fire pixels less likely to be detected. This has resulted in a decreased total FRP measure, since more of the true fire pixels caused by spreading out of the fires radiance into surrounding pixels due to the PSF and FIR filter convolutions remain undetected. For low FRP fires, this results in a greater level of FRP underestimation when the varying background is used, as compared to the flat (spatially invariant) background.

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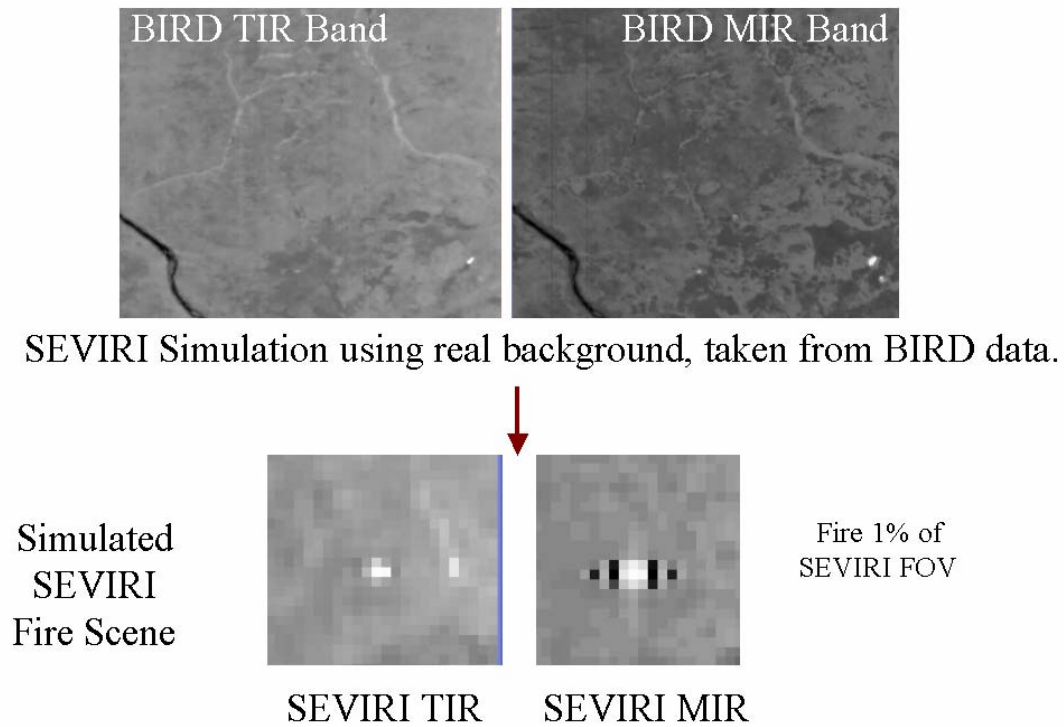


Figure 5.28: Simulated SEVIRI active fire TIR and MIR channel data, derived from higher spatial BIRD imagery to provide the ambient background measurements, and with a modelled fire spectral radiance signal superimposed.

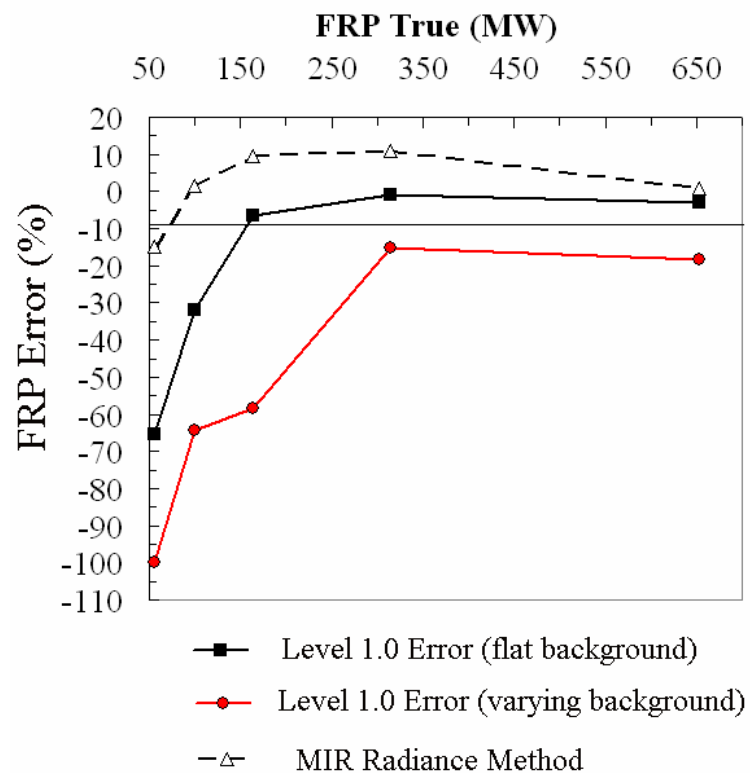


Figure 5.29: Degree of underestimation induced by the SEVIRI observation process on simulated fires of the sort depicted in Figure 5.28 and which have been modelled with a varying ambient background temperature (taken from BIRD imagery) and a spatially invariant ‘flat’ background temperature. The error due only to the MIR radiance method alone is also shown.

Finally, Figure 5.30 shows the results of the SEVIRI ‘special operations mode’ experiment with regard to data collected simultaneously by Meteosat-8 and Meteosat-9, firstly when the former system had the FIR filter present and then when it was removed. Under standard operations, Meteosat-8 measures per-scene FRPs on average around 10% lower than those recorded by Meteosat-9. On removal of the FIR filter, this difference is increased to around 22%, due to a combination of the removal of the influence of the –ve side lobes, the fact that some fire pixels remain undetected in the non-FIR filtered data since they have lower MIR radiances (see Figure 5.24) and to the effect of the removal of the FIR filter on the extent on signal saturation.

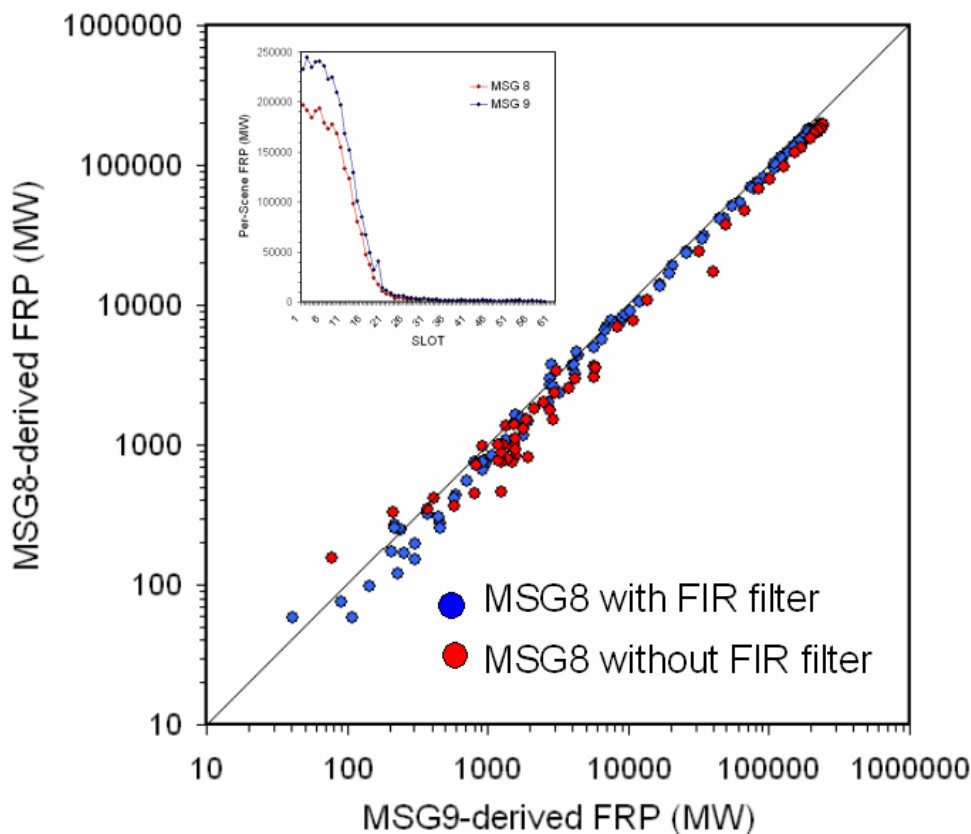


Figure 5.30. Comparison of Meteosat-8 and Meteosat-9 per-scene FRP data recorded simultaneously over southern Africa during the Meteosat-8 ‘special operations mode’ experiment. Greater discrepancies are seen when the FIR filter is removed from the Meteosat-8 SEVIRI (Meteosat-9 had the filter always applied).

5.3 Results of Land SAF Product Validations

5.3.1 Comparison to KCL Product

In terms of active fire pixel detection for each slot of data in August 2007, on average 12.7% of the fire pixels detected by the KCL FRP product in a slot did not have a corresponding Land SAF product fire pixel, whilst in 22.7% the reverse occurs. Whilst these figures may seem high, these averages are hugely influenced by night-time observations when there are very few fire pixels. During daytime conditions, where fire pixel counts and total FRP are typically orders of magnitude greater than at night and where the non-detection or false-detection of individual fire pixels is thus far less significant, the KCL and Land SAF products agree within 0.2% and 0.3%. Therefore in general the products show very similar performance characteristics in terms of fire pixel detections at the times when there are significant numbers of fires.

Figure 5.31 shows that when both the Land SAF and KCL products detect the same fire pixels, their FRP is retrieved almost identically, with a very slight positive bias in the Land SAF product most likely due to the specific calibration methods used in each data processing chain. The level of difference is found to be similar when summing all FRP observed in each product over the complete Land SAF southern African region (the OLS line of best fit is $y = 1.006x + 1336$, $r^2 = 0.99$), and thus the Land SAF products for this region are essentially expected to have the same bulk error characteristics and accuracies as the original KCL product.

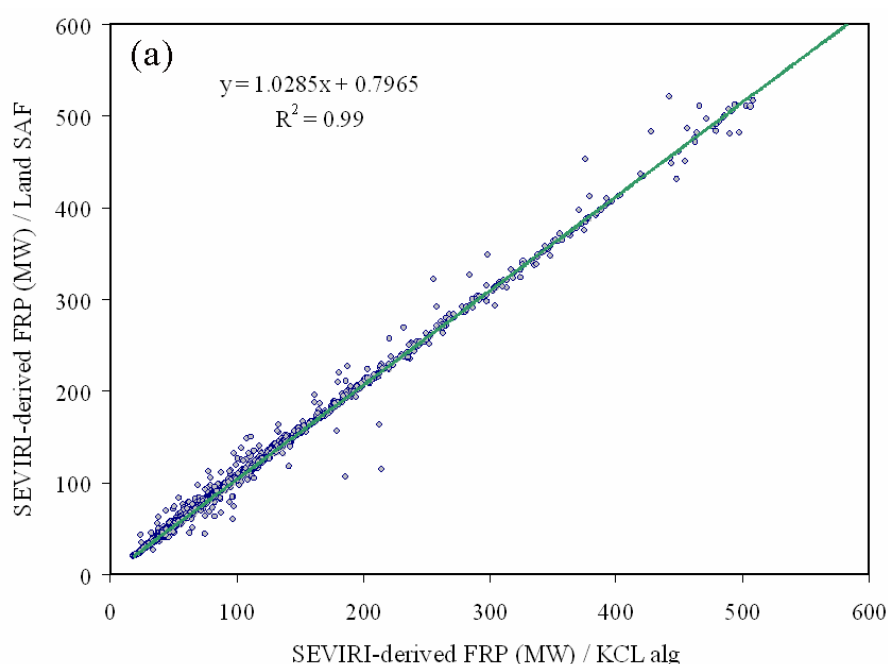


Figure 5.31: FRP comparison between the Land SAF FRP product and that generated at KCL from EUMETCAST-received SEVIRI data of the same imaging slots. The figure shows the per-pixel comparison for the Land SAF southern African region, where only data from fire pixels identified in both products are included in the match up dataset.

5.3.2 Comparison to MODIS

In August 2007 over South Africa, errors of omission in terms fire detection were 68%, i.e. 68% of MODIS-detected fire pixels had no corresponding SEVIRI fire pixel within the Land SAF product (compared to 54% in the KCL product for August 2004, see section 5.2.2.1). Again it should be remembered that a large number of these MODIS pixels would have been in clusters, such that many ‘missing’ MODIS fire pixels might have corresponded to only one ‘extra’ SEVIRI pixel. Errors of commission were low, with only 2% of the Land SAF products fire pixels having no matching MODIS pixel (compared to 6-8% in the KCL product). On a per-fire basis, there is a strong correlation between the FRP measures made by SEVIRI and by MODIS (Figure 5.32), and this is in agreement with the results of the SEVIRI to MODIS per-fire FRP comparison made with the original KCL product (Figure 5.11).

On average, over the month, in the southern African region the Land SAF algorithm for SEVIRI detects 65% of the total FRP that MODIS detects when observing the same area almost simultaneously, this underestimate being a result of the aforementioned inability of SEVIRI to detect the lowest FRP fire pixels, as outlined earlier. Figure 5.33 shows the relationship between SEVIRI- and MODIS-detected cumulative FRP on a per-MODIS scene basis, and the strong linear correlation found here attests to the similarity of the Land SAF product and the KCL FRP product whose swath-based relationship to MODIS was previously shown in Figure 5.12.

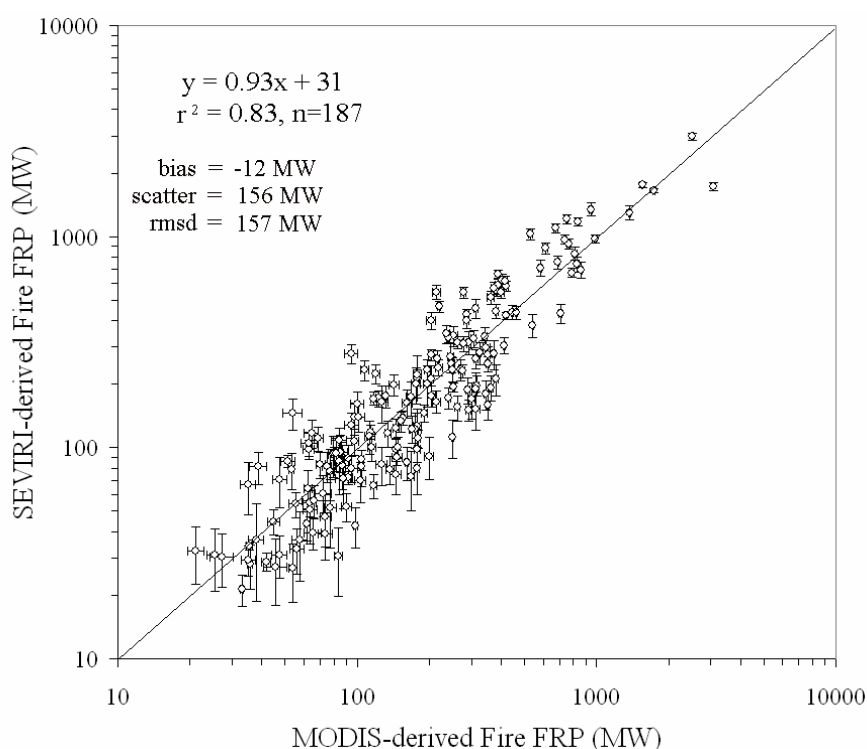


Figure 5.32: A comparison of per-fire FRP derived from SEVIRI and MODIS observations of 187 fires observed near-simultaneously by each sensor. Fires are designated as contiguous clusters of active fire pixels and SEVIRI FRP measured were taken from the Land SAF FRP per-pixel products of southern Africa collected in August 2007.

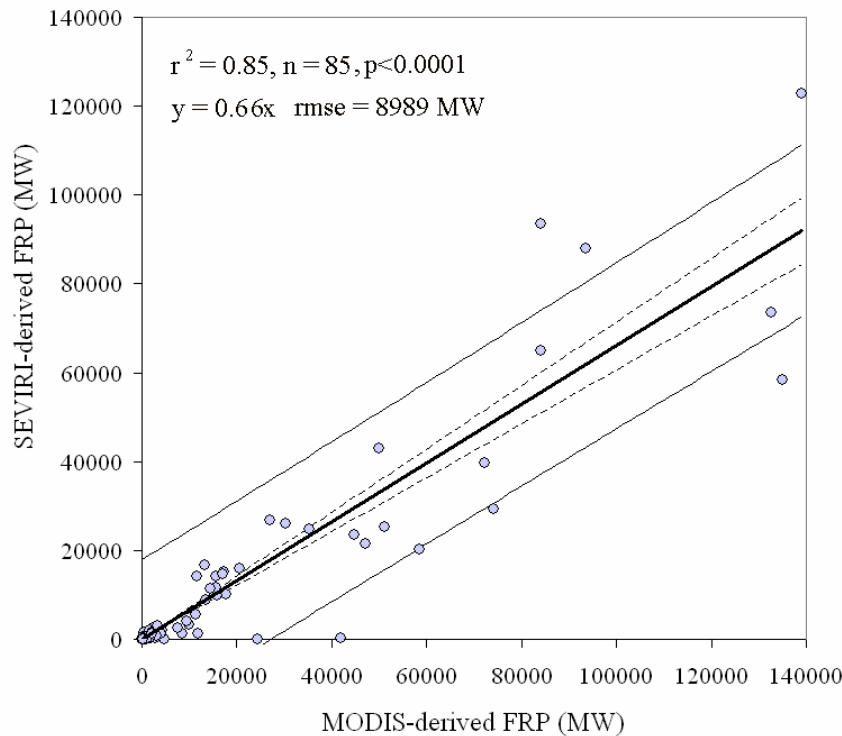


Figure 5.33: Relationship between regional-scale inter-scene FRP derived from all spatially matched, contemporaneous SEVIRI and MODIS observations for the south African region in August 2007, where the MODIS swath is taken as the observation area and the Land SAF per-pixel FRP product was used as the SEVIRI record. The OLS linear best-fit passing through the origin is shown (bold line), along with the 95% confidence intervals on the mean (dotted line) and on the prediction of y from x (outermost lines). In each case SEVIRI generally underestimates regional-scale FRP, primarily due to the non-detection of the lowest FRP fire pixels, many of which MODIS can detect.

Agreement between the area based results for the South American region is far worse than for the African regions, and within a given time-period there are also far fewer matchups due to the area viewed by SEVIRI having fewer fires than does southern Africa and to the extreme viewing angle making fire pixels harder to detect by SEVIRI. Reflecting this degraded performance compared to the southern African region, on average in the South American Land SAF region, fire pixel errors of omission were 79% with respect to MODIS (larger than the southern African case), whilst errors of commission were around the same at 2.5%. Figure 5.34 shows the level of agreement between the MODIS and SEVIRI-derived FRP measures over South America, at the level of individual fire-clusters. The agreement is seen to be far worse than that noted over South Africa seen in Figure 5.32.

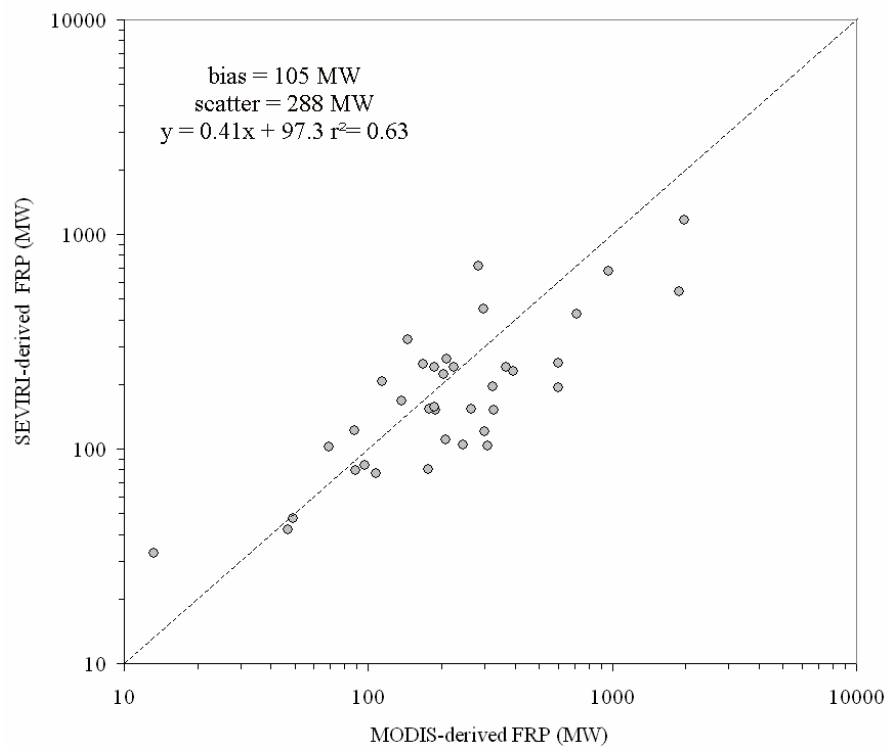


Figure 5.34: A comparison of per-fire FRP derived from SEVIRI and MODIS observations of fires observed near-simultaneously by each sensor over South America. Fires are designated as contiguous clusters of active fire pixels and SEVIRI FRP measured were taken from the Land SAF FRP per-pixel products of South America collected in July 2007.

Figure 5.35 indicates the similarly relatively poor performance of the SEVIRI-derived area FRP estimates, as compare to simultaneous observations from MODIS made across the same spatial extent. We conclude that extreme viewing angles present in SEVIRI views of South America have significantly degraded FRP product performance.

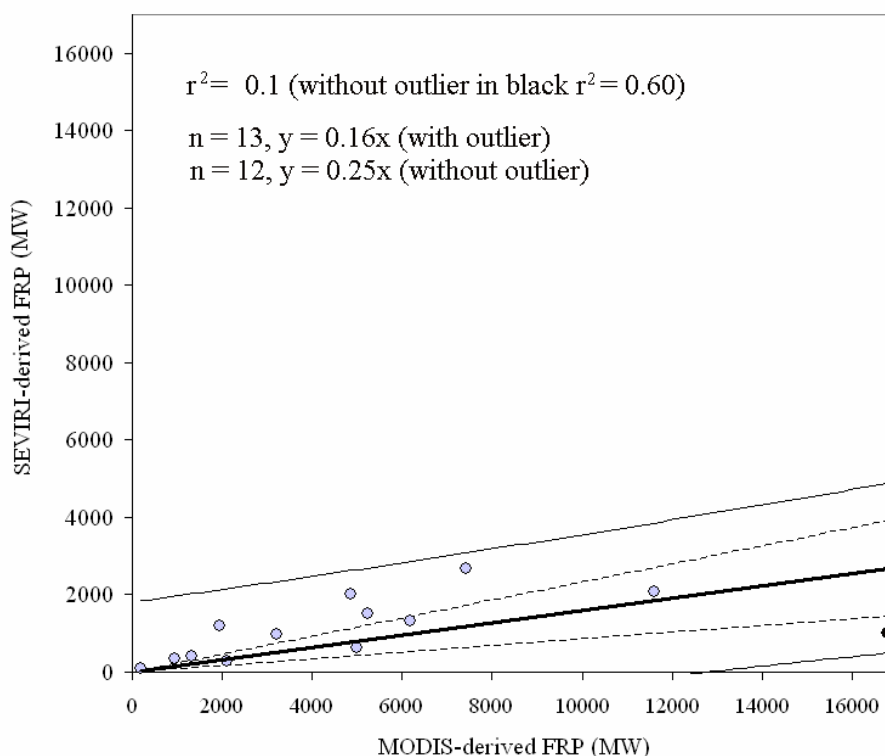


Figure 5.35: Relationship between regional-scale inter-scene FRP derived from all spatially matched, contemporaneous SEVIRI and MODIS observations for the south American region in July 2007, where the MODIS swath is taken as the observation area and the Land SAF per-pixel FRP product was used as the SEVIRI record. The OLS linear best-fit passing through the origin is shown (bold line), along with the 95% confidence intervals on the mean (dotted line) and on the prediction of y from x (outermost lines). In each case SEVIRI generally underestimates regional-scale FRP, primarily due to the non-detection of the lowest FRP fire pixels, many of which MODIS can detect.

5.4 Results of Validation Based on the Impact Studies

Global atmospheric monitoring systems like the one developed in the GEMS project (Hollingsworth *et al.* 2008) for the forthcoming GMES Atmospheric Service (GAS) envisaged by the European Commission and ESA require information on the wildfire emissions of several species as input. Because of the high temporal variability of fire activity the emission input has to be generated from fire observations. None of the currently available fire emission products satisfies all requirements of the monitoring system, in terms of accuracy, spatial and temporal coverage and resolution, timeliness, and operational availability (Kaiser *et al.*, 2006). The SEVIRI FRP product promises to improve the available fire emission input in several aspects:

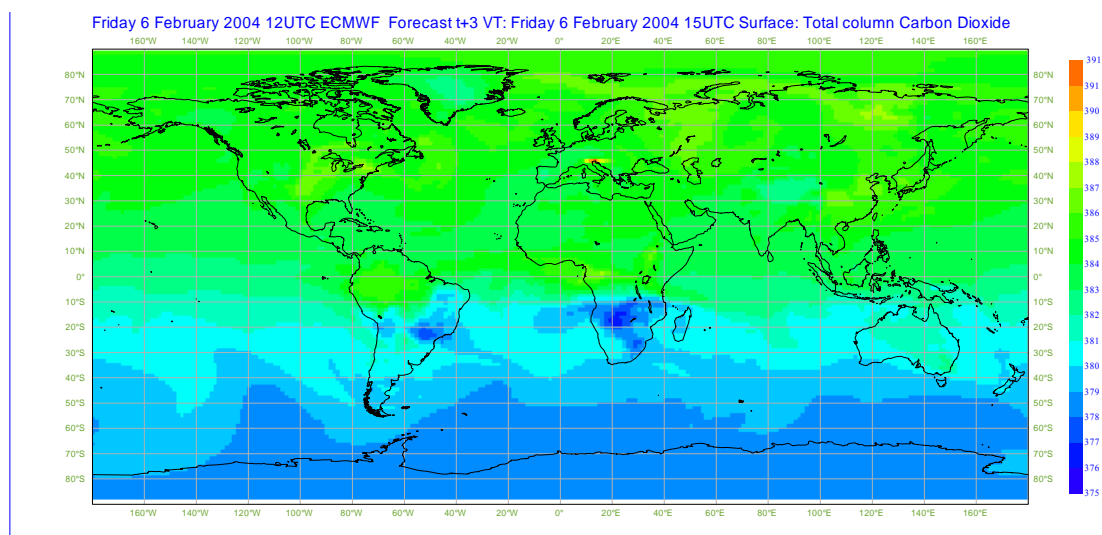
1. improved temporal resolution, compared to products based on low Earth-orbit (LEO) observations;
2. improved accuracy, compared to hot spot products;

3. operational availability with sufficient timeliness for real-time forecasting.

The impact of the first aspect has been studied using the GEMS CO₂ monitoring system (see section 5.4.1) and it was a key aspect of a high-resolution study of impacts from Greek forest fires in the summer of 2007. The impact of the, theoretically, improved accuracy of the emission estimates is tested in a study by FMI, which compares the impact of using the MODIS thermal anomaly (TA) or FRP product in the FMI Fire Assimilation System and the HIRLAM regional air quality forecasts. The overall quality of the SEVIRI FRP product is also tested by comparison to the community-standard monthly fire emission inventory GFEDv2. An end-to-end case study of aerosol plumes emanating from forest fires in Greece in August 2007 demonstrates the capabilities of the real-time monitoring based on the GEMS system and SEVIRI FRP.

5.4.1 Impacts of Temporal Resolution-Study of Sensitivity to Temporal Resolution of Emissions: Global Carbon Dioxide Modelling of 2004

Examples of the simulated CO₂ fields on 6 February 2004 are shown in Figure 5.36. They are expressed in total column (TC) CO₂, defined as the pressure-weighted vertical average mixing ratio [ppm]. The top plot shows the CO₂ field for the simulation without fire emissions and the bottom one shows the field resulting from 1-hourly emissions. Both fields exhibit the typical inter-hemispheric gradient observed in winter. The contribution of the fire emissions is evident as an enhancement over central Africa.



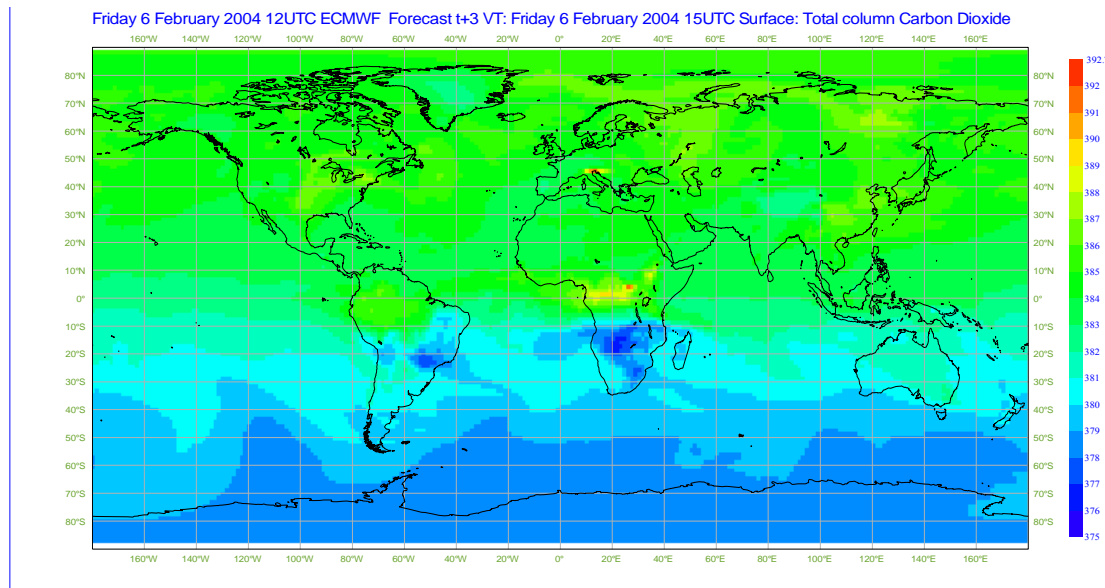


Figure 5.36: Total column CO_2 for simulation without (top) and with (bottom) fire emissions.

The contribution of the fire CO_2 emissions to the CO_2 field is shown directly in Figure 5.37. It is computed as the difference between modelled TC CO_2 with fire emissions at 1-hour (top) and 8-day (bottom) time resolution and a simulation without any fire emissions over Africa. Note, that the total emission within each 8-day period is the same. Since the 8-day time resolution is the current GEMS baseline input (from the GFEDv2 inventory), the differences between the 8-day and 1-hour fire simulations describe the error that the current system suffers due to the limited temporal resolution of the fire emission input. Conversely, it can be interpreted as the positive impact that usage of the SEVIRI FRP product will have on the CO_2 fields modelled with the GEMS system.

Neglecting the temporal variation of the fires during each 8-day period results in a visibly smoother fire contribution to the CO_2 field. Furthermore, the CO_2 “plume” is shifted southwards in the simulations using the 8-day fire product. This is consistent with relatively less fire activity during the first few days of the 8-day period starting on 2 February and more fire activity later on, combined with a general transport southwards, which is evident upon closer inspection of the simulations, but not explicitly shown in this report.

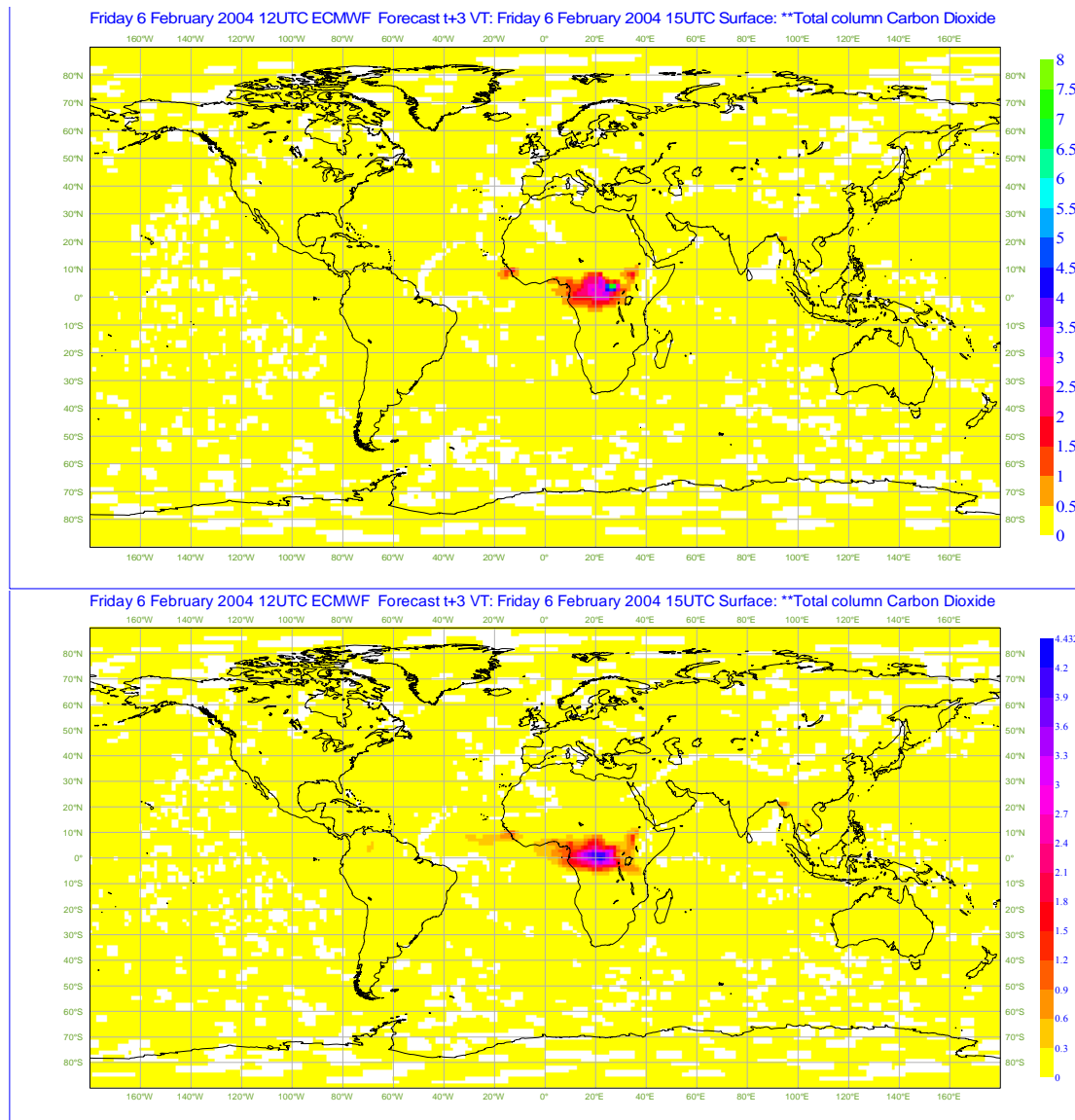


Figure 5.37: Fire emission contribution to total column CO₂ for emission with 1-hour (top) and 8-days (bottom) emission time resolution.

The impact of providing CO₂ fire emission input with the various time resolutions is shown in Figure 5.38. It is computed as difference between the fire emission contributions to the TC CO₂ field in the three simulations with fire emissions. For example, the top plot shows the difference between the contributions in the simulation using 1-hourly emissions versus the one with 8-daily emissions. The top plot can be interpreted as the error in the CO₂ field that is induced by neglecting the temporal evolution of the fire emissions during 8 day periods.

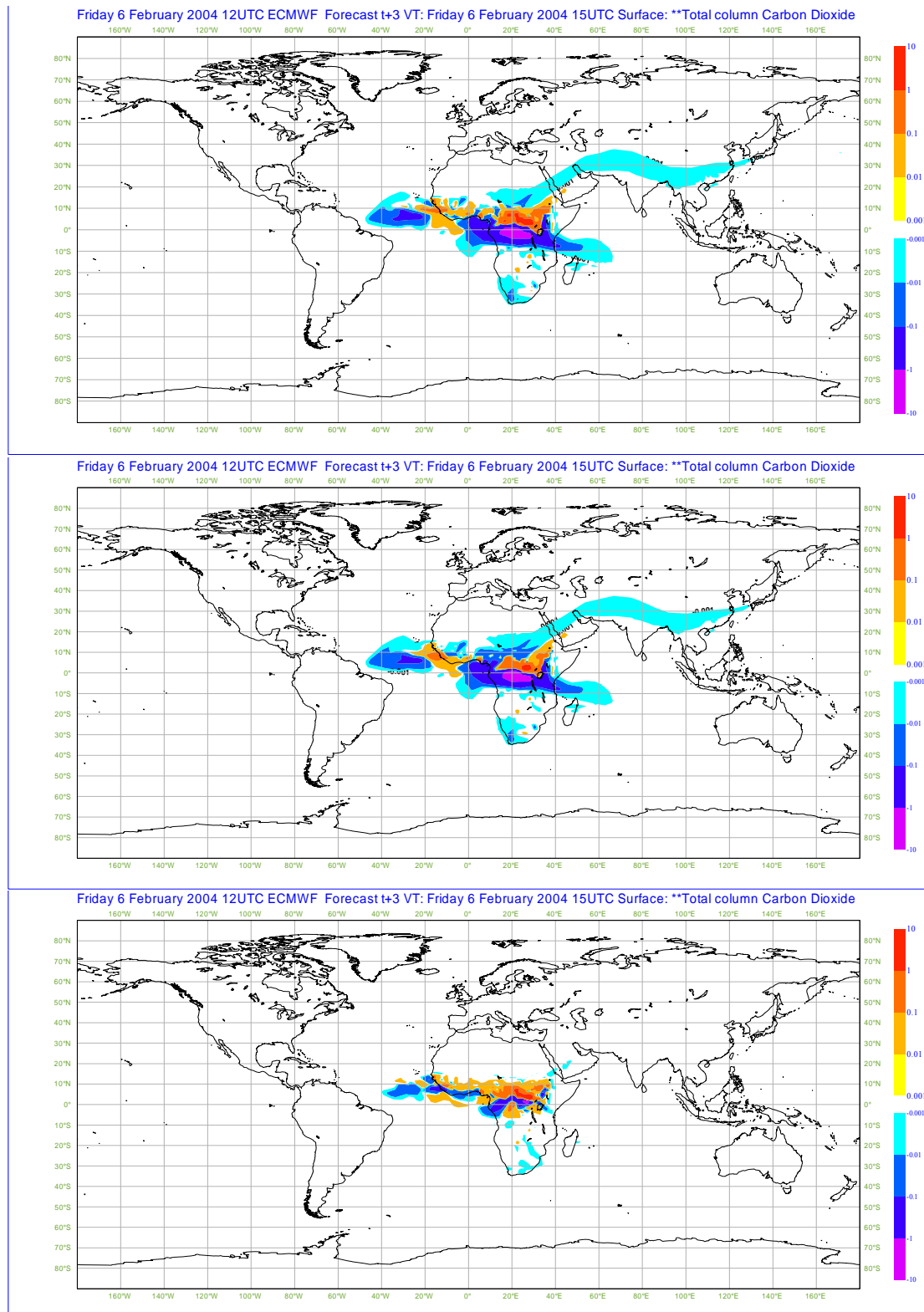


Figure 5.38: Differences in fire contribution to total column CO₂ for emissions with different time resolutions: 1h - 8d (top, Figure 5.37 top - bottom), 1d - 8d (middle), 1h - 1d (bottom).

The middle and bottom plots of Figure 5.38 show the contributions of day-to-day variations and diurnal variations, respectively. They add up to the impact shown in the top plot. The strong North-South dipole over central Africa is caused by the shift in “plume” position mentioned above. It is evidently caused by the day-to-day variability of the fire activity. This also causes small effects that are propagated inter-continently within a few days (the response of less than 0.01 ppm TC CO₂ is however negligible in current CO₂ monitoring applications).

The diurnal variability of fire activity adds finer, more localised structure, as expected. The fine structure has almost the same amplitude as the broader structure induced by the day-to-day variability.

An example vertical cross section of the difference in the CO₂ mixing ratio due to neglecting all fire variability during 8-day windows is shown in Figure 5.39. The difference pattern has a complex structure that stretches across the whole troposphere, which is testament to the intimate link between emission and atmospheric transport variability. The impact is strongest in the boundary layer with values of up to more than ± 4 ppm.

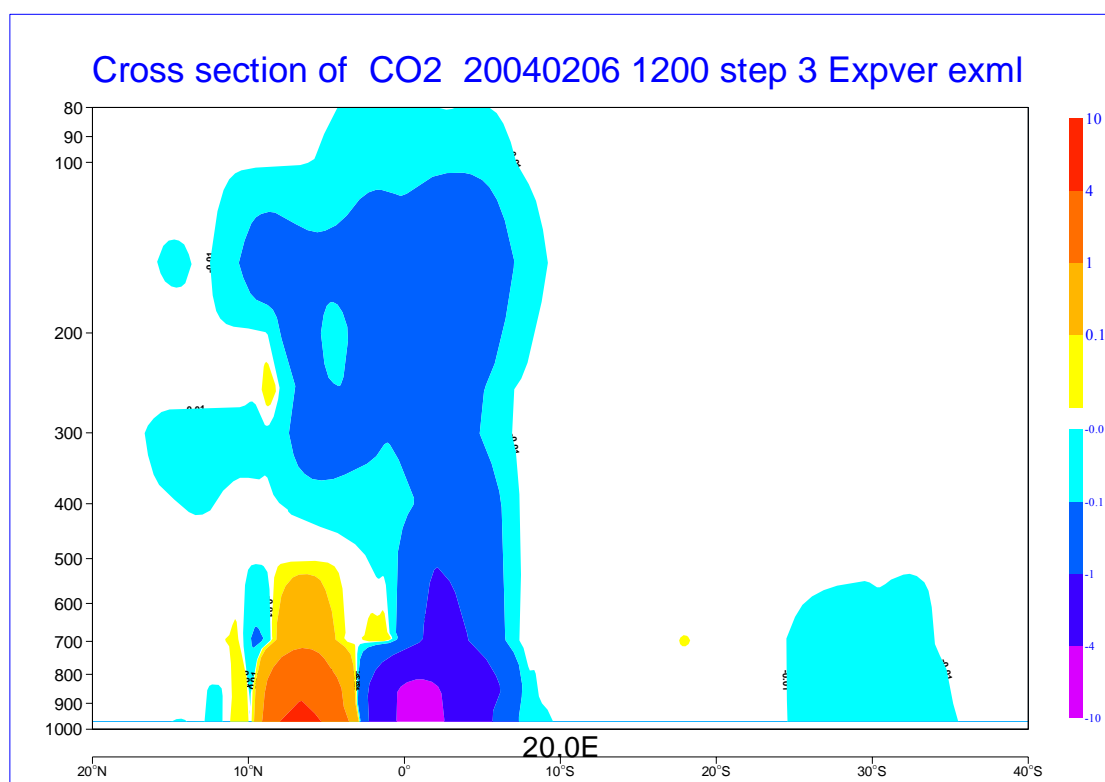


Figure 5.39: Vertical distribution of difference in fire contribution to the CO₂ mixing ratio for emissions with different time resolutions of 1-hour and 8-days.

The relative impact of 1-hour temporal resolution emissions as compared to 8-day ones is computed by normalising the observed differences by the contribution of (8-day) fire emissions to the CO₂ field. The result is shown in Figure 5.40. By neglecting the temporal variability, errors between -90% and +70% can be incurred. The



difference in the CO₂ fields is also propagated onto the Atlantic, far away from the burning regions. On a hemispheric scale the impact is diluted to about 1% of its typical regional value. Due to the tracer-like properties of CO₂, these results are expected to be valid for all long-lived pollutants in the fire plumes (such as carbon monoxide, organic carbon, etc.).

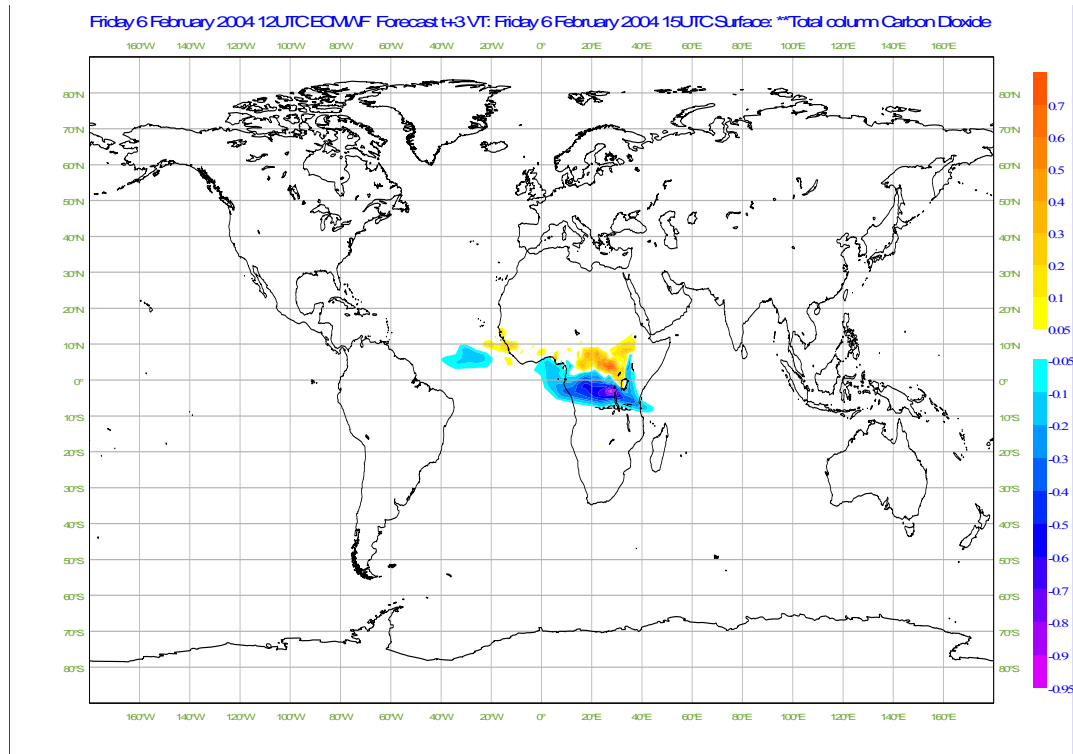


Figure 5.40: Relative difference of total column CO₂ for different time resolutions. $(1\text{-hourly} - 8\text{-daily fires [ppm]}) / (1\text{-hourly} - \text{no fires} + 1 \text{ ppm})$.

Analyses of simulated aerosol fields on 6 February 2004 and of the simulated CO₂ fields near the end of the simulation period have confirmed the general findings described above (not shown).

5.4.2 Impact on Estimating Fire Emissions

In this section, we show a) results of the comparison of SEVIRI-based monthly carbon emission estimates with data from the Global Fire Emissions Database (GFED

version 2) and b) a qualitative comparison of the seasonal pattern of SEVIRI FRP with MOPITT CO profiles.

SEVIRI and GFED give similar results for Africa north and south of the equator, but SEVIRI tends to show slightly lower values overall (Figure 5.41). It is important to note that uncertainties are large in the GFED approach, so no quantitative assessment can be made on the SEVIRI-based emissions performance. The most relevant difference seen between SEVIRI and GFED version 2 is the timing of the emissions peak in both hemispheres, which is diagnosed about one month later in GFED than in SEVIRI. The later timing of the peak appears more consistent with observations of atmospheric trace compounds (see next section), but until now the factors causing the difference between the peak fire occurrence and maximum loading of the atmosphere have not been determined satisfactorily. Preliminary data from GFED3 indicates that GFED2 emissions may have been too high in northern hemispheric Africa, leading to a closer match between SEVIRI and GFED estimates. In southern Africa, however, GFED3 estimates will be higher than GFED2 estimates, which were already higher than SEVIRI-based estimates. The difference is mostly resulting from emission estimates in woodland areas. In principle, the SEVIRI FRP product should be independent of vegetation type (see also section 5.2.3) so that differences in one particular ecosystem might hint to errors in the GFED system. This requires further proof, however. It is noteworthy, that due to large uncertainties in GFED based emissions, discrepancies between FRP and GFED do not necessarily point at shortcomings of the FRP method.

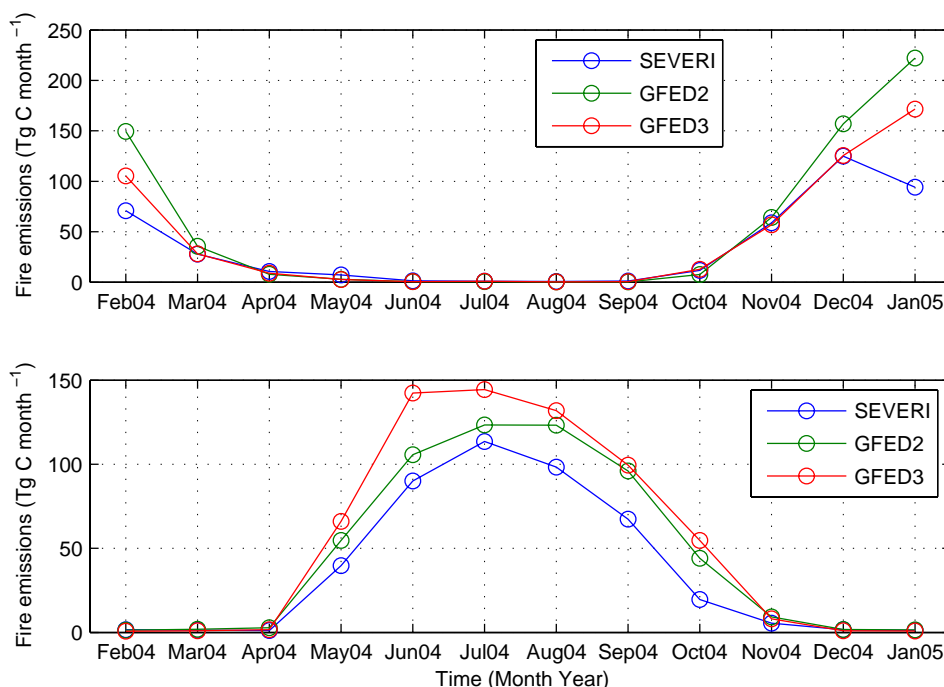


Figure 5.41: Comparison of monthly SEVIRI based carbon emissions with Global Fire Emissions Database (GFED) versions 2 and preliminary version 3 for Africa north of the equator (top panel) and Africa south of the equator (bottom panel).

Figure 5.42 shows the comparison of interannual variations in SEVIRI FRP with MOPITT CO profiles in the southern hemisphere. The peak CO loading derived from the MOPITT sensor occurs in September for retrievals between 700-1000 mb. Retrievals higher in the atmosphere (250 and 350 mb) indicate that the peak atmospheric CO concentration occurs later (October), though this discrepancy may lie with sensitivity of the averaging kernels at different heights to other factors (e.g. surface temperature). The temporal trajectories of the MOPITT CO concentration and total cumulative monthly FRP (proportional to total fuel burned) in the southern hemisphere are offset from one another, with peak FRP-derived biomass burning total in July and peak CO concentrations in September/October. The shapes of the distribution are, however, extremely similar.

The temporal lag is removed when examining the mean per-pixel FRP, which should be approximately proportional to the mean rate of combustion per grid cell. This suggests that there may be additional information in this parameter, which, with further refinement, might enable better parameterisation of temporal evolution of emissions factors used to convert fuel consumption measures into emission of trace gases.

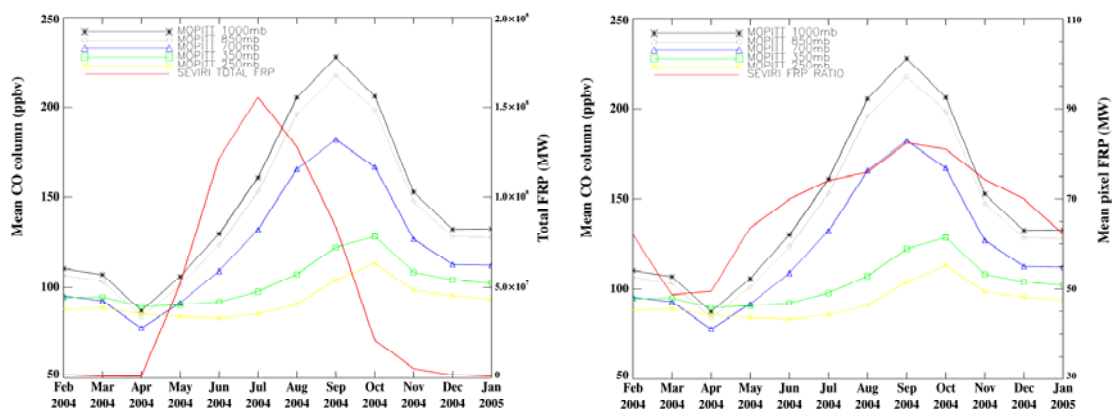


Figure 5.42: Annual variation of mean monthly MOPITT CO mixing ratios retrieved for five pressure levels over land between February 2004 and January 2005 in comparison to total FRP (left) and mean per-pixel FRP (right) for southern hemisphere Africa.

5.4.3 End-to-end Use Case Study: Modelling the Greece Fire Plumes of August 2007

This section shows the results of a case study initiated in the FREEVAL project on modelling the smoke plumes from fires occurring in the Mediterranean region in August 2007 using SEVIRI FRP derived fire aerosol emission estimates. It allows for

some independent validation of the SEVIRI product and also served to identify the necessary technical processing steps and required product characteristics of the pixel and gridded SEVIRI FRP products. The study set-up is described in section 4.4.4.

Figure 5.43 shows the number of active fires detected over the Mediterranean region by MODIS and by SEVIRI on August 25, 2007, when fire activity was at a peak level. Most fires occurred on the western half of the Greece Peloponnese island. While the MODIS and the SEVIRI products match very well in terms of spatial pattern of fire activity, the SEVIRI product detects much more active fires than the MODIS product. As a result, MODIS distinctively under-represents the spatial expansion of the main clusters of fire activity on Peloponnese island compared to SEVIRI.

MODIS Detected fires 25 Aug 2007 SEVIRI Detected fires 25 Aug 2007

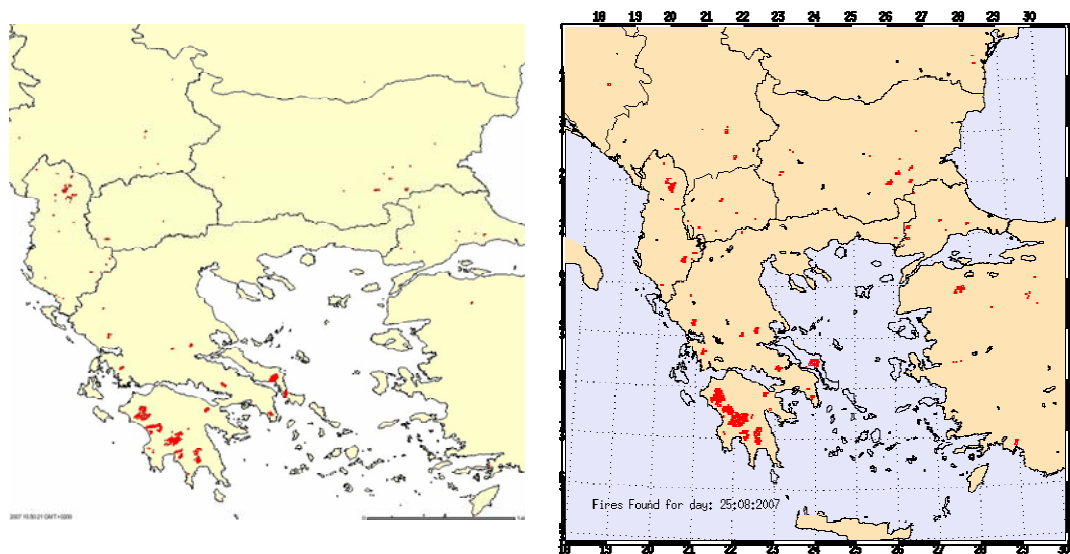


Figure 5.43: Number of active fires (hotspots) detected by MODIS (left) and by SEVIRI (right) on August 25, 2007 over the Mediterranean region.

Two snapshots of simulated optical depth of organic matter and black carbon aerosols, which dominate the smoke optical depth from fire plumes and have comparably smaller other emission sources, are plotted and compared to concurrent MODIS visual images in Figure 5.44. The plots also show the fire activity observed by SEVIRI and MODIS. The simulations qualitatively reproduce the key features of the observations, in particular the fact that the smoke plumes are separated into series of individual “puffs”, which originate from the high fire activity during daytime and are separated by the low activity at night. An animation of the modelled plumes shows that the ones near the Libyan coast have been emitted on the previous day and the one in Algeria is two days old. Furthermore, on August 25, the following observations can be made:

- a very strong plume just off the Peloponnese, associated with very high FRP values (exceeding 70,000 MW)
- a westward broadening of the plume over the Mediterranean
- smaller plumes off the coasts of Albania, Southern Italy, and Sicily

- a strong plume falling on land in Libya
- And for the following day:
- a very strong plume falling on land in Libya on 26 Aug, associated with the very high FRP values observed on 25 Aug
 - a distinct “mirrored S” shape of the plume
 - a thin, weak plume originating in Albania

Despite the striking similarities, the locations of the plume features are often slightly shifted in the simulations with respect to the MODIS images. This may be related to the parameterisation of the smoke plume injection height (currently at the lowest model level) but needs further investigation.

The simulated optical depth of all the model aerosol species that are emitted by fire, i.e. organic matter, black carbon, and sulphate, are compared to the aerosol optical depths derived from concurrent MODIS observations on 25, 26, and 27 August in Figure 5.45 to Figure 5.47. The figures also show the corresponding scatter plots for the entire maps and specific rectangles defined covering just the Greek fire plumes. On 25 and 26 August, the simulations and observations of the Greek fire plumes display very similar shapes, as discussed above. On 25 August, the simulated plume is much broader. This could indicate that even the operational resolution of the ECMWF model is insufficient to accurately capture the plume dispersion on such scales. Furthermore, a tendency of the model to overestimate the AOD is apparent. We estimate that this is a consequence of applying the Ichoku and Kaufman (2005) emission factors, which are reportedly too high.

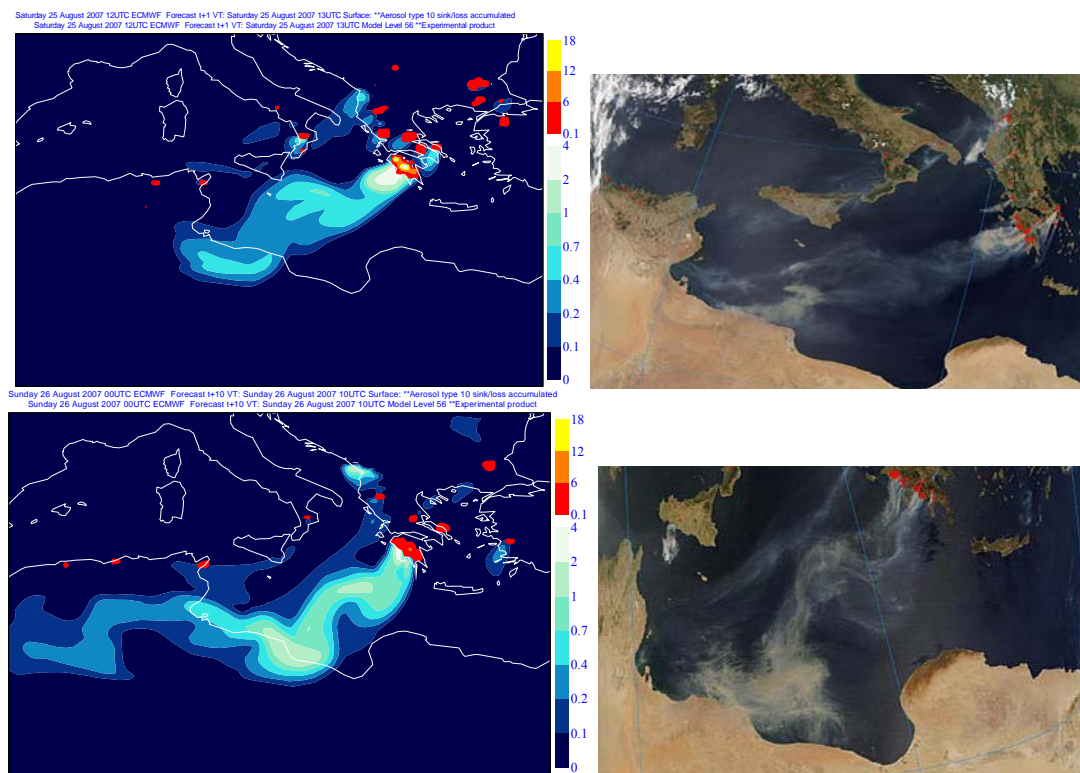



Figure 5.44: Modelled organic matter plus black carbon AOD [-] (left, blue) and MODIS visual images (right) for an Aqua overpass on 25 August, 1205UTC, (top) and a Terra overpass on 26 August,

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0935UTC (bottom). Overlaid with SEVIRI FRP [W/m²] interpolated to model resolution (left, orange) and MODIS hot spots in (right, red).

The AOD comparison of 26 August confirms these findings: The plume shapes are reproduced well, but the plume AOD values are mostly overestimated. Additionally, the background, which originates from different sources, is underestimated. This might be due to cloud cover effects, which are not simulated.

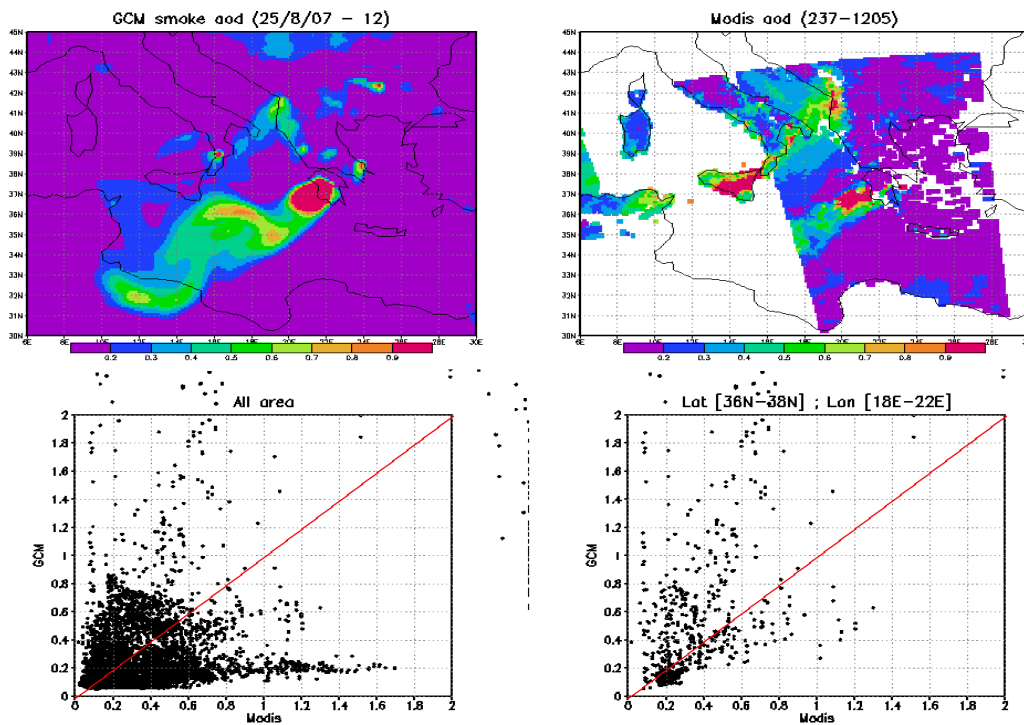


Figure 5.45: Modelled smoke AOD [-] (left) and observed MODIS AOD [-] product (right) for Aqua overpasses on 25 August, 1205UTC (top). AOD scatter plots for the entire area and a box on the fire Greek plume (bottom).

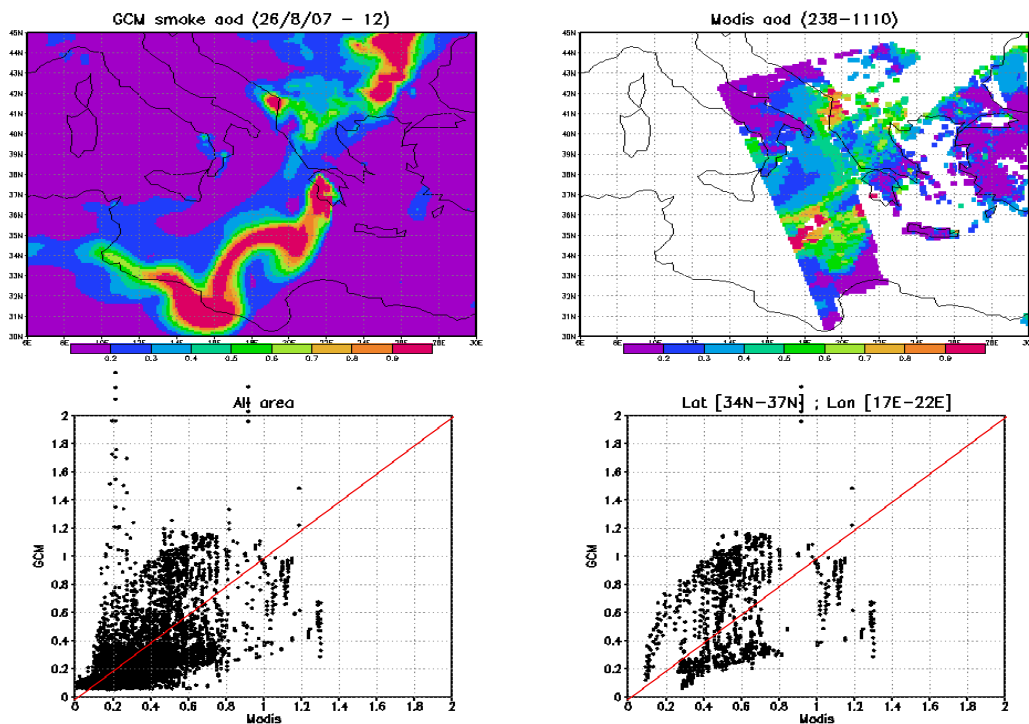


Figure 5.46: Modelled smoke AOD [-] (left) and observed MODIS AOD [-] product (right) for Aqua overpasses on 26 August, 1110UTC (top). AOD scatter plots for the entire area and a box on the fire Greek plume (bottom).

On 27 August, the Peloponnese was partly covered by clouds, the effects of which have been neglected in the tested SEVIRI FRP product generation. Obviously, the shortcoming translates into a marked degeneration of the quality of the simulated aerosol field: The westward outflow from the Peloponnese is overestimated and the southward outflow in the simulation has not been detected by the observations at all.

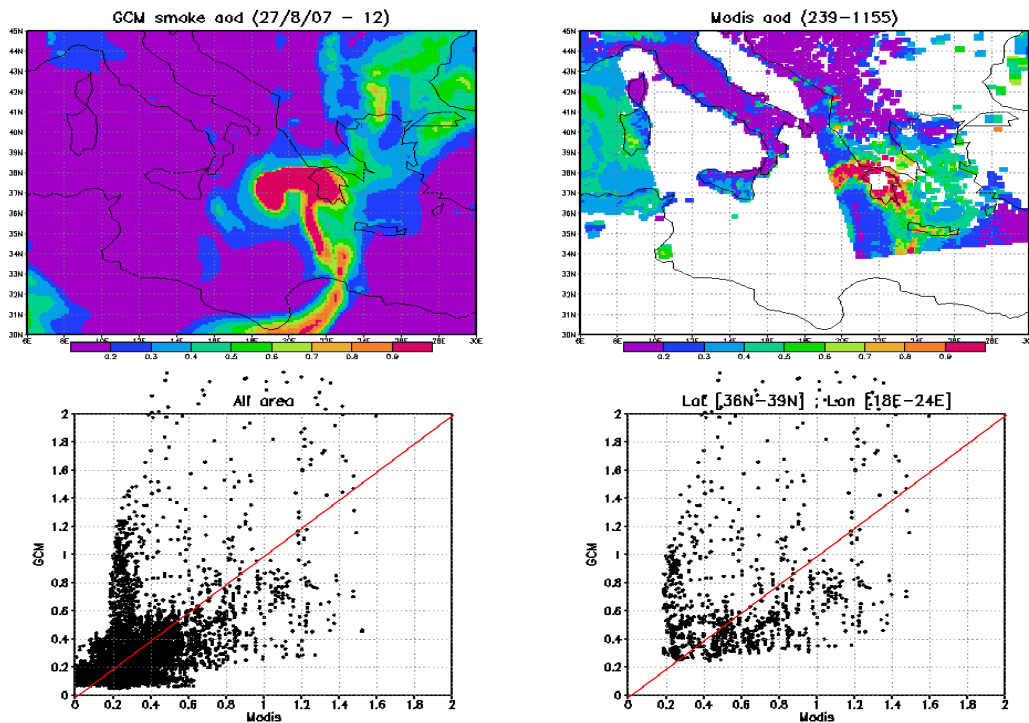


Figure 5.47: Modelled smoke AOD [-] (left) and observed MODIS AOD [-] product (right) for Aqua overpasses on 27 August, 1155UTC (top). AOD scatter plots for the entire area and a box on the fire Greek plume (bottom).

Starting on 26 August, SEVIRI detected large fires along the Algerian coast. The resulting smoke plumes, travelling north-eastwards, are also evident in our simulation. Figure 5.48 shows an example of the fire activity and the developing smoke plume on 30 August. The AERONET station at Lecce University in Southern Italy observed an aerosol plume passing through on 30-31 August, see Figure 5.49. It is confirmed by MODIS observations. The fact that the steep rise is predominantly in the recorded fine mode AOD indicates that the aerosols may originate from fires. The simulation exhibits a mixed dust and smoke plume passing over Lecce on 30 August. The steepest rise in AOD is attributed to a rise of the smoke aerosol components, which originated from the Algerian fires. The dust component clearly has a smoother time evolution. This is another indication that the observed strong plume is dominated by smoke emitted in Algeria and transported across the Mediterranean.

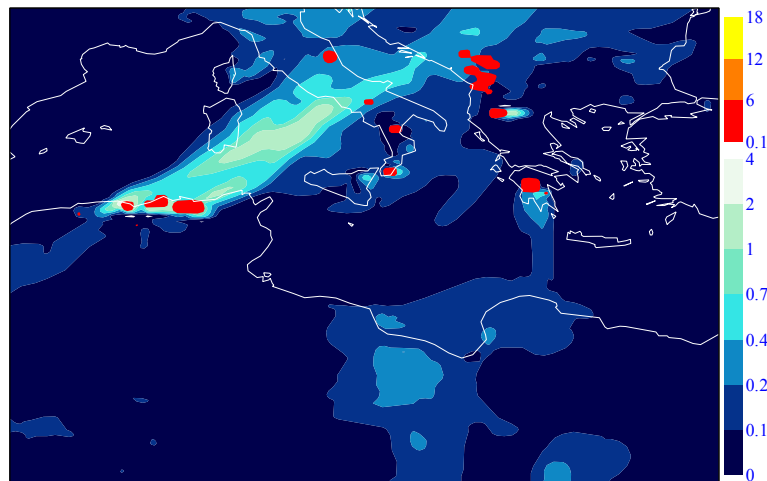


Figure 5.48: Modelled organic matter plus black carbon AOD [-] (bluish) on 30 August 2007, 1430UTC, overlaid with observed SEVIRI FRP [W/m²] interpolated to model resolution (reddish). The University of Lecce AERONET station is indicated by a white circle.

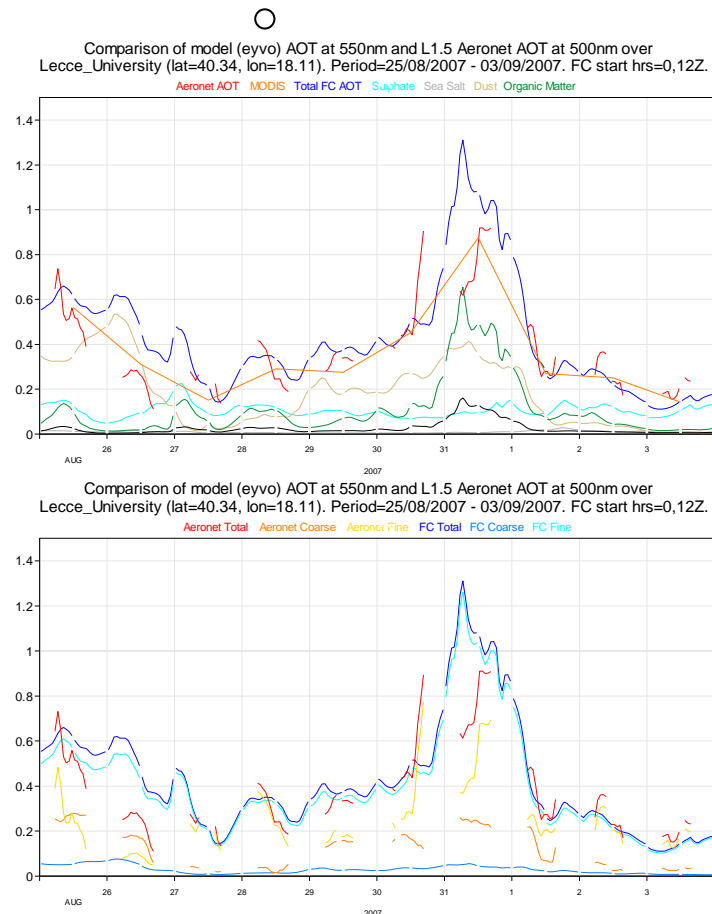



Figure 5.49: Observed and modelled AOD time series over Lecce, Southern Italy. Observations by MODIS (top orange: daily average AOD) and AERONET (red: AOD, bottom orange: coarse mode AOD, yellow: fine mode AOD). Modelled AOD (dark blue) and AOD contributions by the aerosol model species (top) and modes (bottom). The mode definition of AERONET and the model are, unfortunately not identical. [graphics by L. Jones, ECMWF. MODIS data from

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*http://gcmd.nasa.gov/records/GES_DAAC_MOVAS.html, AERONET data from
http://aeronet.gsfc.nasa.gov/]*

As a conclusion, this end-to-end study shows that retrospective aerosol fire plume modelling with the GEMS aerosol model driven by SEVIRI fire emission input works well. More comprehensive validation is needed, but

- High temporal resolution seems vital in order to reproduce the observed smoke plume structures.
- Model runs based on SEVIRI FRP data reproduce horizontal structures found in the observations.
- Emission factors found in the literature vary by a factor of five at least. An intermediate value would be most appropriate for the Greek fire case.
- Exact plume positions and absolute scaling may still be improved. This will require
 - the best possible correction for cloud cover
 - better modelling of injection heights
 - better knowledge of emission factors.

Several distinct Greek fire plumes have been simulated. They have travelled more than 1000 km in 1-2 days. Algerian fire plumes, mixed with Saharan dust, have also been simulated. They have travel to Italy, where they were apparently identified by ground-based observations.

In light of the potential use of the SEVIRI FRP data for smoke plume forecasts it can be concluded that forecasting of the transport and evolution of the fire plume is possible for 1-2 days into the future if the SEVIRI data are made available within a few hours after observation. Since the study was performed at a horizontal resolution typical for a regional air quality model, forecasts of smoke plumes in Southern Europe similar to the shown examples can be expected from the future regional air quality systems in GEMS when the SEVIRI FRP product becomes available. The global GEMS modelling system will be able to produce routine smoke and air pollution plume forecasts for Europe and Africa at a coarser resolution of ~125 km. This resolution will be further enhanced in the coming years.

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6 Conclusions

6.1 Product Validation Summary

Within the FREEVAL project, the SEVIRI FRP product has been evaluated with respect to

- the validity of assumptions made in the algorithm derivation;
- the capability of the SEVIRI instrument to reliably detect fires and quantify FRP;
- the influence of SEVIRI data processing on the FRP product;
- the impact of using it in potential operational applications.

The theoretical and radiative transfer modelling analysis of the algorithm performance has shown that the MIR radiance method algorithm used within the SEVIRI FRP products has an underlying accuracy of $\pm 12\%$ over the temperature range expected for active fires, and that the assumptions made when implementing this algorithm on data of highly-sub pixel sized fires (as will be the case with coarse spatial resolution satellite data such as that from SEVIRI) in theory introduce negligible other errors. In this case, if the fire pixels that comprise an individual fire can be reliably detected, show a sufficiently large MIR radiance increase above the background, and if the MIR atmospheric transmission is reliably known then the FRP can be quantified to this level of uncertainty. Differences between the original KCL algorithm and the Land SAF implementation are negligible in this respect.

In practical terms, the most limiting factor for product accuracy appears to be the current coarse pixel size, of area $\sim 23 \text{ km}^2$ at the sub-satellite point, increasing to $\sim 90 \text{ km}^2$ near the disk edge (assuming full width at half maximum sensitivity values). Numerous fire pixels with FRP values less than 40 MW escape detection by SEVIRI, and the detection and quantification of slightly larger fires (40-100 MW) will be less reliable, because the enhancement of the MIR brightness temperature due to the fire with respect to the (somewhat variable) background temperature of surrounding pixels is rather small. To some extent the impacts of the coarse spatial resolution are balanced by the extremely high temporal resolution of the geostationary observations. As was shown for fires in the Central African Republic, over the course of a day SEVIRI will capture a signal from most fire events that the much higher spatial resolution MODIS instruments on EOS Aqua and Terra can detect during their four-times per day overpasses. We assume that this is related to the ability of SEVIRI to observe the complete fire life cycle and thus capture fires when they reach their peak intensity. However, for any particular SEVIRI observation, the cumulative FRP measured at the regional (e.g. grid cell or country-scale) is likely to be an underestimate of what would have been measured by MODIS had it observed the whole area at the same moment, by on average around 50%.

Due to the higher spatial resolution observations and wide usage of the MODIS active fire products these are taken to be the reference standard against which the SEVIRI FRP product is assessed. Comparisons were performed for the period February 2004 to January 2005 and included data of August 2007. Tests were made on a per-fire

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basis, as well as on a regionally gridded basis. When MODIS and SEVIRI detect the same fire, in 76 % of the cases the FRP retrieved by SEVIRI is within 33 % of that reported by MODIS. Errors of omission and commission are estimated to 54% (68% for the one month of data of the Land SAF product) and 8% (2%), respectively, varying with season. Fire detection has been found to be largely independent of the dominant vegetation type in which the fire occurs, although SEVIRI shows a small tendency to detect fewest of the MODIS-detected fires in croplands (a landcover type dominated by smaller fires), and more of them in forested areas.

Since the MIR channel on SEVIRI was not designed for fire detection but rather for land surface monitoring, it saturates around 335 K, a temperature that is easily exceeded by larger fire events. The effect of this saturation is an underestimation of FRP for large fires, which can in fact contribute significantly to an underestimation of FRP in a given region. Limited experiments have indicated an FRP underestimation of ~ 10% by day due to pixel saturation and up to 40% at night, though at night there are many fewer fires and much lower regional FRP totals, so saturation of a few night-time pixels can induce large percentage errors. A change of the MIR SEVIRI band gain corresponding to a saturation temperature of 375K would remove this effect.


The spatial filtering and geometric interpolation performed on-board MSG as part of the level 1 to level 1.5 processing induces some additional noise in the MIR field, which further reduces the instrument's ability to detect all the fire pixels associated with an individual fire event, and to accurately quantify their FRP. The "blurring" of fire radiances related to this pre-processing can reduce level 1.5 fire pixel MIR temperatures, and as a consequence fewer pixels appear to be saturated in the level 1.5 data than were originally saturated at the instrument (level 1.0) stage. However, it is shown through theoretical modelling and targeted data analysis that the effects of the level 1 to level 1.5 processing are generally outweighed by the limitations given by the sensor resolution and the pixel saturation effects.

6.2 Demonstrated Usefulness of Product

FREEVAL has undertaken two types of activity in order to assess the potential use of the SEVIRI FRP product in (predominantly) operational applications:

- Several potential users were contacted and queried about their requirements and willingness to use an FRP product from SEVIRI and
- a number of impact studies were performed in the context of pre-operational modelling systems for monitoring of atmospheric composition.

Several users provided a strong recommendation for operational generation of FRP from the SEVIRI sensor. Although SEVIRI performs less well than for example MODIS with respect to the detection and quantification of fires on a per-observational basis, its high temporal sampling frequency and the expected availability of near real-time data products offers great potential to improve the prediction of smoke plumes from fire events in Southern Europe and Africa, and this has been demonstrated in the

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case studies described in this report. These case studies also underline the readiness of the community to make use of the product very soon after its release. Furthermore, the 15-minute sampling frequency will also be of interest for operational warning services, such as that operated by the South African power company ESCOM (see section 1.2).

6.3 Definition of Accuracy Requirements

The user requirements for FRP products in general were collected in Table 6.1 in section 2.3 of this report. Here, we assess the accuracy requirements specifically for the SEVIRI FRP product and in light of the theoretical performance that is achievable with this sensor under its standard operating conditions.

The three accuracy values tabulated below are defined as follows:

- *Threshold accuracy*: this is the accuracy limit which is needed so that the product fulfils its purpose.
- *Target accuracy*: this is the average product accuracy under the present operating conditions and with the instrument characteristics of SEVIRI. With this product quality the product will be valuable for most of the users identified above.
- *Optimal accuracy*: this is the accuracy that can be reached under optimum conditions (sub-satellite point, cloud-free scene, homogeneous background, medium sized fire).

As was demonstrated in the product validation activities, the accuracy of the SEVIRI FRP product will depend on various factors related to pixel resolution, saturation, viewing geometry and on-board and ground-based pre-processing of raw signals. Furthermore, the required level of accuracy will depend on the application, and different aspects of accuracy might be emphasized in different applications. For example, a fire warning system will be less concerned about the absolute quantitative value of FRP as long as the fire can be reliably detected rapidly (with few commission errors in particular) and there is some indication about fire severity. Chemical forecasts, and even more so reanalysis simulations, on the other hand, depend on the reliability of area-averaged fire emissions (and thus FRP) and have less concern about the ability of the instrument to capture each and every fire.

Table 6.1: Summary of accuracy requirements for the SEVIRI FRP pixel and gridded products

	Pixel product	Gridded product
Threshold accuracy	N.A. ¹	Factor 3 over continental area
Target accuracy	70% of retrieved FRP within 50% of “true” values as defined by MODIS	Factor 2 at the scale of ecozones
Optimal accuracy	±15%	25% on a 5° grid

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¹ successful detection of a significant fraction of fires reproducing the spatial and temporal distribution can be considered the threshold target

In summary it can be said that the SEVIRI FRP product fulfils the accuracy requirements given in the table above. It will greatly improve the ability of operational atmospheric models to monitor emissions from highly variable vegetation fires and the smoke plumes emanating from them.

Acknowledgments

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Project team:

Martin G. Schultz, FZ Jülich, Germany (coordinator)
Martin Wooster, King’s College, London, UK (co-coordinator)

Olivier Boucher, Met. Office, Exeter, UK
Marie Doutriaux-Boucher, Met Office, Exeter, UK
Claire Granier, University Paris, France
Angelika Heil, FZ Jülich, Germany
Anthony Hollingsworth[†], ECMWF, Reading, UK
Johannes W. Kaiser, ECMWF, Reading, UK
Thomas Kasikowski, Met Office, Exeter, UK
Jean-Jacques Morcrette, ECMWF, Reading, UK
Gareth Roberts, King’s College, London, UK
Adrian Simmons, ECMWF, Reading, UK
Guido van der Werf, Vrije Universitet, Amsterdam, The Netherlands

External contributions from Mikhail Sofiev, FMI are highly appreciated.

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[†] Dr. Anthony Hollingsworth sadly passed away on 29 July 2007.


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